

Dynamic Programming

Four-step (two-phase) method:

1. Characterize the structure of an optimal solution
2. Recursively define the value of an optimal solution
3. Compute the value of an optimal solution in a bottom-up fashion
4. Construct an optimal solution from computed information

Longest Common Subsequence (LCS) – DP case study 3

Problem statement:

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Input: Sequences

$$X_m = \langle x_1, x_2, x_3, \dots, x_m \rangle$$

$$Y_n = \langle y_1, y_2, \dots, y_n \rangle$$

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Output: longest common subsequence (LCS) of X_m and Y_n

LCS

Terminology

1. Sequence, e.g.

- ▶ $X_7 = \langle A, B, C, B, D, A, B \rangle$
- ▶ ALGORITHM

LCS

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3. Common subsequence, e.g.

- ▶ Given $X_7 = \langle A, B, C, B, D, A, B \rangle$
 $Y_6 = \langle B, D, C, A, B, A \rangle$
- ▶ $Z_3 = \langle B, C, A \rangle$ is a common subsequence of X_7 and Y_6
- ▶ $Z_4 = \langle B, C, B, A \rangle$ is also a common subsequence of X_7 and Y_6

LCS

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4. Longest common subsequence (LCS), e.g.

- ▶ Z_4 is a longest common subsequence (LCS) of X_7 and Y_6
- ▶ LCS is not unique, $\langle B, C, A, B \rangle$ is also a LCS.

LCS

A brute-force solution:

- ▶ For every subsequence of X_m , check if it is a subsequence of Y_n .

LCS

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- ▶ For every subsequence of X_m , check if it is a subsequence of Y_n .
- ▶ Running time: $\Theta(n \cdot 2^m)$
- ▶ **Intractable!**

LCS

DP – step 1: *characterize the structure of an optimal solution*

LCS

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Let $Z_k = \langle z_1, z_2, \dots, z_k \rangle$ be any LCS of

$$X_m = \langle x_1, x_2, \dots, x_m \rangle \quad \text{and} \quad Y_n = \langle y_1, \dots, y_n \rangle$$

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► **Case 1.** If $x_m = y_n$, then

(a) $z_k = x_m = y_n$

(b) $Z_{k-1} = \langle z_1, z_2, \dots, z_{k-1} \rangle = \text{LCS}(X_{m-1}, Y_{n-1})$

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► **Case 2.** If $x_m \neq y_n$, then

(a) $z_k \neq x_m \implies Z_k = \text{LCS}(X_{m-1}, Y_n)$

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In words, the optimal solution to the (whole) problem **contains within it** the optimal solutions to subproblems

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In words, the optimal solution to the (whole) problem **contains within it** the optimal solutions to subproblems = **the optimal substructure property**

LCS

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LCS

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we have

$$c[i, j] = c[i - 1, j - 1] + 1$$

LCS

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we have

$$c[i, j] = \max\{c[i, j-1], c[i-1, j]\}$$

LCS

- ▶ In summary,

$$c[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \text{ (initials)} \\ c[i - 1, j - 1] + 1 & \text{if } x[i] = y[j] \text{ (Case 1)} \\ \max\{c[i, j - 1], c[i - 1, j]\} & \text{if } x[i] \neq y[j] \text{ (Case 2)} \end{cases}$$

LCS

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$$c[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0 \text{ (initials)} \\ c[i - 1, j - 1] + 1 & \text{if } x[i] = y[j] \text{ (Case 1)} \\ \max\{c[i, j - 1], c[i - 1, j]\} & \text{if } x[i] \neq y[j] \text{ (Case 2)} \end{cases}$$

- ▶ Meanwhile, create $b[i, j]$ to record the optimal subproblem solution chosen when computing $c[i, j]$

LCS

DP – step 3: *compute $c[i, j]$ (and $b[i, j]$) in a bottom-up approach*

- ▶ Compute $c[i, j]$ and $b[i, j]$ in a **bottom-up approach**.
 - ▶ $c[i, j]$ is the length of $\text{LCS}(X_i, Y_j)$
 - ▶ $b[i, j]$ shows how to construct the corresponding $\text{LCS}(X_i, Y_j)$

LCS

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 - ▶ $c[i, j]$ is the length of $\text{LCS}(X_i, Y_j)$
 - ▶ $b[i, j]$ shows how to construct the corresponding $\text{LCS}(X_i, Y_j)$
- ▶ Cost:
 - ▶ Running time: $\Theta(mn)$
 - ▶ Space: $\Theta(mn)$

LCS

```
LCS-length(X,Y)
set c[i,0] = 0 and c[0,j] = 0
for i = 1 to m // Row-major order to compute c and b arrays
  for j = 1 to n
    if X(i) = Y(j)
      c[i,j] = c[i-1,j-1] + 1
      b[i,j] = 'Diag'      // go to up diagonal
    elseif c[i-1,j] >= c[i,j-1]
      c[i,j] = c[i-1,j]
      b[i,j] = 'Up'      // go up
    else
      c[i,j] = c[i,j-1]
      b[i,j] = 'Left'    // go left
    endif
  endfor
endfor
return c and b
```

LCS

DP – step 4: *construct an optimal solution from computed information*

LCS

Example: $X_7 = \langle A, B, C, B, D, A, B \rangle$ and $Y_6 = \langle B, D, C, A, B, A \rangle$

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$c[\cdot, \cdot] + b[\cdot, \cdot]$:

| | | j | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
|---|----------|-------|----------|----|----------|----|----------|----------|---|
| | | y_j | B | D | C | A | B | A | |
| 0 | x_i | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | A | 0 | ↑ | ↑ | ↑ | ↖1 | ←1 | ↖1 | |
| 2 | B | 0 | ↖1 | ↖1 | ←1 | ↑1 | ↖2 | ←2 | |
| 3 | C | 0 | ↑1 | ↑1 | ↖2 | ←2 | ↑2 | ↑2 | |
| 4 | B | 0 | ↖1 | ↑1 | ↑2 | ↑2 | ↖3 | ←3 | |
| 5 | D | 0 | ↑1 | ↖2 | ↑2 | ↑2 | ↑3 | ↑3 | |
| 6 | A | 0 | ↑1 | ↑2 | ↑2 | ↖3 | ↑3 | ↖4 | |
| 7 | B | 0 | ↖1 | ↑2 | ↑2 | ↑3 | ↖4 | ↑4 | |

LCS

Example: $X_7 = \langle A, B, C, B, D, A, B \rangle$ and $Y_6 = \langle B, D, C, A, B, A \rangle$

$c[\cdot, \cdot] + b[\cdot, \cdot]$:

| | | j | 0 | 1 | 2 | 3 | 4 | 5 | 6 |
|---|-------|-------|---|---|---|---|---|---|---|
| | | y_j | B | D | C | A | B | A | |
| 0 | x_i | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 1 | A | 0 | ↑ | ↑ | ↑ | ↖ | ← | ↖ | |
| 2 | B | 0 | ↖ | ← | ← | ↑ | ↖ | ← | |
| 3 | C | 0 | ↑ | ↑ | ↖ | ← | ↑ | ↑ | |
| 4 | B | 0 | ↖ | ↑ | ↑ | ↑ | ↖ | ← | |
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(1) Length of LCS = $c[7, 6] = 4$

(2) By the b-table (“↑, ←, ↖”), the LCS is $BCBA$