# EGR2013 Tutorial 9

# Linear Algebra

## Outline

- Linear Independence/Dependence of Vectors and Subspace
- Fundamental Vector Spaces of a Matrix
- Matrix Eigenvalue Problem

### Linear Independence/Dependence of Vectors

A Linear combination of vectors  $a_1, a_2, \dots, a_m$  in a vector space V is an expression

$$k_1\mathbf{a}_1 + k_2\mathbf{a}_2 + \dots + k_m\mathbf{a}_m$$

These vectors are called linear independence if the vector equation

$$k_1 a_1 + k_2 a_2 + \dots + k_m a_m = 0$$

implies that  $k_1 = 0, k_2 = 0, \dots, k_m = 0$ . Otherwise, they are linear dependent.

**<u>Span</u>**: If  $S = \{a_1, a_2, \dots, a_r\}$  is a set of vectors in a vector space V, then the

subspace W of V is called the space spanned by  $a_1, a_2, \dots, a_r$ , denoted by

$$W = span(S)$$
 or  $W = span\{a_1, a_2, \dots, a_r\}$ 

**<u>Dimension</u>**:  $\dim(V)$  = the maximum number of linear independent vectors.

#### **Basis:**

- The basis of V consists of a maximum possible number of linear independent vectors in V.
- Every vector in V can be expressed as a linear combination of the vectors in the basis.
- ➤ A basis is not unique.

#### Example 1

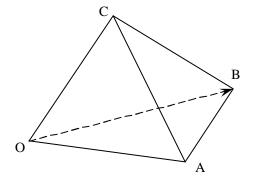
Given All vectors in  $R^4$  such that  $v_1 = 0, v_3 = 0, v_2 + v_4 \le 0$ , is this set of vectors a vector space?

#### Example 2

If vectors  $a_1, a_2$  and  $a_3$  are linear independent, determine whether the

vectors (1)  $a_1 - a_2, a_2 - a_3, a_3 - a_1$ ; (2)  $a_1 + a_2, a_2 + a_3, a_3 + a_1$  form a linear dependent set or a linear independent set. **Solution:** Geometric interpretation:

Because  $a_1, a_2$  and  $a_3$  are linear independent, so they are not in the same plane. We can assume they are the edges of a triangular pyramid O-ABC,



If  $OA = a_1, OB = a_2, OC = a_3$ , then  $a_1 - a_2, a_2 - a_3$  and  $a_3 - a_1$  are the edges of the triangle ABC respectively, so they are in the same plane, in other words, they are linear dependent. But  $a_1 + a_2, a_2 + a_3$  and  $a_3 + a_1$  are in the plane OAB, OBC and OCA respectively, obviously, they are not in the a plane, so they are linear independent.

(1)  $a_1 - a_2, a_2 - a_3$  and  $a_3 - a_1$  are linear dependent.

Because we have  $1(a_1-a_2)+1(a_2-a_3)+1(a_3-a_1)=0$ .

(2)  $a_1 + a_2, a_2 + a_3$  and  $a_3 + a_1$  are linear independent.

The vector equation

$$k_1(a_1+a_2) + k_2(a_2+a_3) + k_3(a_3+a_1) = 0$$

can be written as

$$(k_1+k_3)a_1 + (k_1+k_2)a_2 + (k_2+k_3)a_3 = 0$$

because  $a_1, a_2$  and  $a_3$  are linear independent, then we have

$$\begin{cases} k_1 & + k_3 &= 0\\ k_1 & + k_2 & = 0\\ & k_2 & + k_3 &= 0 \end{cases}$$
  
because the determinant 
$$\begin{vmatrix} 1 & 0 & 1\\ 1 & 1 & 0\\ 0 & 1 & 1 \end{vmatrix} = 2 \neq 0$$

thus the system has trivial solutions  $k_1 = k_2 = k_3 = 0$ , so  $a_1 + a_2, a_2 + a_3$ and  $a_3 + a_1$  are linear independent.

### **Fundamental Vector Spaces of a Matrix**

A is a  $m \times n$  matrix, then we define,

**Row space:** subspace of  $R^m$  spanned by row vectors;

**Column space:** subspace of  $R^n$  spanned by column vectors;

**Nullspace:** the solution space of AX = 0.

#### **Basic Concepts of Fundamental Matrix Space:**

- Row operation doesn't change the fundamental spaces of a matrix;
- Basis can be obtained by reducing the matrix A to its echelon form;
- dim (row space) = dim (column space) = rank (A);
- The dimension of the nullspace of A is called the nullity of A, and rank(A)+nullity(A)=n, n is the number of column of A.

#### Example 3

A is a n-th order matrix, if A is invertible  $\Leftrightarrow |A| \neq 0 \Leftrightarrow \operatorname{rank}(A) = n$ 

#### Example 4

Given rank(A)=3, evaluate a and b. 
$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & b \\ 2 & 3 & a & 4 \\ 3 & 5 & 1 & 7 \end{bmatrix}$$

#### Solution:

Row operations:

$$A \rightarrow \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & b \\ 0 & 1 & a-2 & 2 \\ 0 & 2 & -2 & 4 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & -1 & b \\ 0 & 0 & a-1 & 2-b \\ 0 & 0 & 0 & 4-2b \end{bmatrix}$$

because rank (A)=3, therefore  $a \neq 1, b = 2$  or  $a = 1, b \neq 2$ .

#### Example 5

Given A is a  $m \times n$  matrix, B is a  $n \times s$  matrix, if AB=0, show  $rank(A) + rank(B) \le n$ 

#### **Proof:**

Matrix B can be expressed as  $B = (B_1, B_2, \dots, B_s)$ , then we have

$$AB = A(B_1, B_2, \dots, B_s) = (AB_1, AB_2, \dots, AB_s) = (0, 0, \dots, 0)$$
$$\Rightarrow AB_j = 0 \qquad j = 1, 2, \dots, s.$$

Therefore, each column of B is a solution of AX=0. The dimension of nullspace of A is equal to n - rank(A),  $B_j$  is some vectors in this nullspace,

so 
$$rank(B) = rank(B_1, B_2, \dots, B_s) \le n - rank(A)$$
.

Then we have  $rank(A) + rank(B) \le n$ 

### Matrix Eigenvalue Problem

#### **Eigenvalue and Eigenvetor:**

For an  $n \times n$  matrix A, and a vector x, if a value of  $\mathbf{l}$  exists such that

Ax = Ix, has nonzero solution vector  $x \neq 0$ , then I is defined as an eigenvalue of matrix A, the corresponding solution vector x is eigenvector.

#### Method for Finding Eigenvalues and Eigenvectors:

- > Characteristic equation:  $p(\mathbf{l}) = \det(A \mathbf{l}I) = (-1)^n \mathbf{l}^n + \dots + c_n = 0$
- > The eigenvector corresponding to I is the solutions of (A II)x = 0

### Example 6

$$A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$$
, find the eigenvalues and eigenvectors of A.

#### Solution:

(1) The Characteristic equation of A is

$$\det(A - \mathbf{I}I) = 0 \Rightarrow \begin{vmatrix} -\mathbf{I} & 1 \\ -1 & -\mathbf{I} \end{vmatrix} = \mathbf{I}^2 + 1 = 0$$
$$\Rightarrow (\mathbf{I} + i)(\mathbf{I} - i) = 0 \Rightarrow \mathbf{I}_1 = -i, \mathbf{I}_2 = i$$

(2) Eigenvectors are the solutions of (A - II)x = 0

For  $\boldsymbol{l}_1 = -i$ , the linear system becomes

$$\begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow \begin{bmatrix} i & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = s \begin{bmatrix} i \\ 1 \end{bmatrix} \text{ so that } \begin{bmatrix} i \\ 1 \end{bmatrix}$$

is a eigenvector corresponding  $I_1 = -i$ .

For  $\boldsymbol{l}_1 = \boldsymbol{i}$ , the linear system becomes

$$\begin{bmatrix} -i & 1 \\ -1 & -i \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow \begin{bmatrix} -i & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = 0 \Rightarrow \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = s \begin{bmatrix} -i \\ 1 \end{bmatrix} \text{ so that } \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

is a eigenvector corresponding  $\boldsymbol{l}_1 = \boldsymbol{i}$ .

### Example 7

If I is the eigenvalue of matrix A, evaluate the eigenvalue of  $A^2 + 2A - I$ . Solution:

If I is the eigenvalue of matrix A, and X is the eigenvector corresponding I,

then we have Ax = Ix.

Multiply both sides by matrix A, then we get

$$AAx = A\mathbf{I} x \Longrightarrow A^2 x = \mathbf{I} Ax = \mathbf{I}^2 x$$

thus  $\mathbf{l}^2$  is eigenvalue of matrix  $A^2$  with the corresponding eigenvector x. In the same way, we can get the eigenvalue of  $A^2 + 2A - I$  is  $\mathbf{l}^2 + 2\mathbf{l} - 1$ .