ECS 231

Introduction to Spectral Clustering

Motivation

Image segmentation in computer vision



Motivation

Community detection in network analysis



Outline

- I. Graph and graph Laplacian
 - Graph
 - Weighted graph
 - Graph Laplacian
- II. Graph clustering
 - Graph clustering
 - Normalized cut
 - Spectral clustering

An (undirected) graph is G = (V, E), where

- $V = \{v_i\}$ is a set of vertices;
- $E = \{(v_i, v_j), v_i, v_j \in V\}$ is a subset of $V \times V$.



Remarks:

- An edge is a pair $\{v_i, v_j\}$ with $v_i \neq v_j$ (no self-loop);
- ▶ There is at most one edge from v_i to v_j (simple graph).

For every vertex v_i ∈ V, the degree d(v_i) of v_i is the number of edges adjacent to v:

$$d(v_i) = |\{v_j \in V | \{v_j, v_i\} \in E\}|.$$

• Let $d_i = d(v_i)$, the **degree matrix**

$$D = D(G) = \operatorname{diag}(d_1, \ldots, d_n).$$



▶ Given a graph G = (V, E), with |V| = n and |E| = m, the incidence matrix $\widetilde{D}(G)$ of G is an $n \times m$ matrix with

$$\tilde{d}_{ij} = \left\{ \begin{array}{ll} 1, & \text{if } \exists \, k \, \, \text{s.t.} \, \, e_j = \{v_i, v_k\} \\ 0, & \text{otherwise} \end{array} \right.$$



$$\widetilde{D}(G) = \begin{array}{cccc} e_1 & e_2 & e_3 & e_4 & e_5 \\ v_1 & 1 & 1 & 0 & 0 & 0 \\ v_2 & v_3 & 1 & 0 & 1 & 1 & 0 \\ v_4 & 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 \end{array} \right)$$

► Given a graph G = (V, E), with |V| = n and |E| = m, the adjacency matrix A(G) of G is a symmetric n × n matrix with

$$a_{ij} = \left\{ \begin{array}{ll} 1, & \text{if } \{v_i, v_j\} \in E \\ 0, & \text{otherwise} \end{array} \right.$$



$$A(G) = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{pmatrix}$$

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A weighted graph is G = (V, W) where

- $V = \{v_i\}$ is a set of vertices and |V| = n;
- $W \in \mathbb{R}^{n \times n}$ is called *weight matrix* with

$$w_{ij} = \begin{cases} w_{ji} \ge 0 & \text{if } i \neq j \\ 0 & \text{if } i = j \end{cases}$$

The underlying graph of G is $\widehat{G}=(V,E)$ with

$$E = \{\{v_i, v_j\} | w_{ij} > 0\}.$$

• If
$$w_{ij} \in \{0,1\}$$
, $W = A$,

Since $w_{ii} = 0$, there is no self-loops in \widehat{G} .

For every vertex v_i ∈ V, the degree d(v_i) of v_i is the sum of the weights of the edges adjacent to v_i:

$$d(v_i) = \sum_{j=1}^n w_{ij}.$$

• Let $d_i = d(v_i)$, the **degree matrix**

$$D = D(G) = \operatorname{diag}(d_1, \ldots, d_n).$$

• Let $d = \operatorname{diag}(\mathsf{D})$ and denote $\mathbf{1} = (1, \dots, 1)^T$, then

$$d = W1.$$

• Given a subset of vertices $A \subseteq V$, we define the **volume** by

$$\operatorname{vol}(A) = \sum_{v_i \in A} d(v_i) = \sum_{v_i \in A} \left(\sum_{j=1}^n w_{ij} \right)$$

If vol(A) = 0, all the vertices in A are isolated. Example:



If
$$A = \{v_1, v_3\}$$
, then

$$vol(A) = d(v_1) + d(v_3)$$

= $(w_{12} + w_{13}) + (w_{31} + w_{32} + w_{34})$

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• Given two subsets of vertices $A, B \subseteq V$, the **links** is defined by

$$\mathsf{links}(A,B) = \sum_{v_i \in A, v_j \in B} w_{ij}.$$

Remarks:

- A and B are not necessarily distinct;
- Since W is symmetric, links(A, B) = links(B, A);
- $\blacktriangleright \ \operatorname{vol}(A) = \operatorname{links}(A, V).$

▶ The quantity cut(A) is defined by

$$\mathsf{cut}(A) = \mathsf{links}(A, V - A).$$

▶ The quantity assoc(A) is defined by

$$\mathsf{assoc}(A) = \mathsf{links}(A, A).$$

Remarks:

- cut(A) measures how many links escape from A;
- ▶ assoc(A) measures how many links stay within A;

•
$$\operatorname{cut}(A) + \operatorname{assoc}(A) = \operatorname{vol}(A).$$

Given a weighted graph G = (V, W), the (graph) Laplacian L of G is defined by

$$L = D - W.$$

where D is the degree matrix of G, and $D = \text{diag}(W \cdot 1)$.

Properties of Laplacian

1.
$$x^T L x = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (x_i - x_j)^2$$
 for $\forall x \in \mathbb{R}^n$,
2. $L > 0$ if $w_{ij} > 0$ for all i , i

- 2. $L \ge 0$ if $w_{ij} \ge 0$ for all i, j,
- **3**. $L \cdot 1 = 0$,
- 4. If the underlying graph of G is connected, then

$$0 = \lambda_1 < \lambda_2 \le \lambda_3 \le \ldots \le \lambda_n,$$

where λ_i are the eigenvalues of L.

5. If the underlying graph of G is connected, then the dimension of the nullspace of L is 1.

Proof of Property 1. Since L = D - W, we have

$$\begin{aligned} x^{T}Lx &= x^{T}Dx - x^{T}Wx \\ &= \sum_{i=1}^{n} d_{i}x_{i}^{2} - \sum_{i,j=1}^{n} w_{ij}x_{i}x_{j} \\ &= \frac{1}{2}(\sum_{i}^{n} d_{i}x_{i}^{2} - 2\sum_{i,j=1}^{n} w_{ij}x_{i}x_{j} + \sum_{j=1}^{n} d_{j}x_{j}^{2}) \\ &= \frac{1}{2}(\sum_{i,j=1}^{n} w_{ij}x_{i}^{2} - 2\sum_{i,j=1}^{n} w_{ij}x_{i}x_{j} + \sum_{i,j=1}^{n} w_{ij}x_{j}^{2}) \\ &= \frac{1}{2}\sum_{i,j=1}^{n} w_{ij}(x_{i} - x_{j})^{2}. \end{aligned}$$

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Proof of Property 2.

- ▶ Since $L^T = D W^T = D W = L$, L is symmetric.
- ► Since $x^T L x = \frac{1}{2} \sum_{i,j=1}^n w_{ij} (x_i x_j)^2$ and $w_{ij} \ge 0$ for all i, j, we have $x^T L x \ge 0$.

Proof of Property 3.

$$L \cdot \mathbf{1} = (D - W)\mathbf{1} = D\mathbf{1} - W\mathbf{1} = d - d = \mathbf{0}.$$

Proofs of Properties 4 and 5 are skipped, see §2.2 of [Gallier'13].

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II.1 Graph clustering

k-way partitioning: given a weighted graph G = (V, W), find a partition A_1, A_2, \ldots, A_k of V, such that

•
$$A_1 \cup A_2 \cup \ldots \cup A_k = V;$$

•
$$A_1 \cap A_2 \cap \ldots \cap A_k = \emptyset;$$

▶ for any i and j, the edges between (A_i, A_j) have low weight and the edges within A_i have high weight.

If k = 2, it is a *two-way partitioning*.

II.1 Graph clustering

Recall: (two-way) cut:

$$\mathsf{cut}(A) = \mathsf{links}(A, V - A) = \sum_{v_i \in A, v_j \in V - A} w_{ij}$$

II.1 Graph clustering problems

The **mincut** is defined by

$$\min \operatorname{cut}(A) = \min_{A} \sum_{v_i \in A, v_j \in V - A} w_{ij}.$$

In practice, the mincut typically yields unbalanced partitions.



The **normalized cut**¹ is defined by

$$\mathsf{Ncut}(A) = \frac{\mathsf{cut}(A)}{\mathsf{vol}(A)} + \frac{\mathsf{cut}(\bar{A})}{\mathsf{vol}(\bar{A})}.$$

where $\bar{A} = V - A$.

¹Jianbo Shi and Jitendra Malik, 2000

Minimal Ncut:

 $\min \mathsf{Ncut}(A)$

Example:



Let $x = (x_1, \ldots, x_n)$ be the *indicator vector*, such that

$$x_i = \left\{ \begin{array}{ll} 1 & \text{if } v_i \in A \\ -1 & \text{if } v_i \in \bar{A} = V - A \end{array} \right.$$

Then

1.
$$(\mathbf{1} + x)^T D(\mathbf{1} + x) = 4 \sum_{v_i \in A} d_i = 4 \cdot \operatorname{vol}(A);$$

2. $(\mathbf{1} + x)^T W(\mathbf{1} + x) = 4 \sum_{v_i \in A, v_j \in A} w_{ij} = 4 \cdot \operatorname{assoc}(A).$
3. $(\mathbf{1} + x)^T L(\mathbf{1} + x) = 4 \cdot (\operatorname{vol}(A) - \operatorname{assoc}(A)) = 4 \cdot \operatorname{cut}(A);$
4. $(\mathbf{1} - x)^T D(\mathbf{1} - x) = 4 \sum_{v_i \in \bar{A}} d_i = 4 \cdot \operatorname{vol}(\bar{A});$
5. $(\mathbf{1} - x)^T W(\mathbf{1} - x) = 4 \sum_{v_i \in \bar{A}, v_j \in \bar{A}} w_{ij} = 4 \cdot \operatorname{assoc}(\bar{A}).$
6. $(\mathbf{1} - x)^T L(\mathbf{1} - x) = 4 \cdot (\operatorname{vol}(\bar{A}) - \operatorname{assoc}(\bar{A})) = 4 \cdot \operatorname{cut}(\bar{A}).$
7. $\operatorname{vol}(V) = \mathbf{1}^T D \mathbf{1}.$

• With the above basic properties, Ncut(A) can now be written as

$$\begin{aligned} \mathsf{Ncut}(A) &= \frac{1}{4} \left(\frac{(\mathbf{1}+x)^T L(\mathbf{1}+x)}{k(\mathbf{1}^T D \mathbf{1})} + \frac{(\mathbf{1}-x)^T L(\mathbf{1}-x)}{(1-k)(\mathbf{1}^T D \mathbf{1})} \right) \\ &= \frac{1}{4} \cdot \frac{((\mathbf{1}+x) - b(\mathbf{1}-x))^T L((\mathbf{1}+x) - b(\mathbf{1}-x))}{b(\mathbf{1}^T D \mathbf{1})}. \end{aligned}$$

where $k = \operatorname{vol}(A)/\operatorname{vol}(V)$, b = k/(1-k) and $\operatorname{vol}(V) = \mathbf{1}^T D \mathbf{1}$. • Let $y = (\mathbf{1} + x) - b(\mathbf{1} - x)$, we have

$$\mathsf{Ncut}(A) = \frac{1}{4} \cdot \frac{y^T L y}{b(\mathbf{1}^T D \mathbf{1})}$$

where

$$y_i = \left\{ \begin{array}{ll} 2 & \text{if } v_i \in A \\ -2b & \text{if } v_i \in \bar{A} \end{array} \right. .$$

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Since
$$b = k/(1-k) = \operatorname{vol}(A)/\operatorname{vol}(\bar{A})$$
, we have

$$\frac{1}{4}(y^T D y) = \sum_{v_i \in A} d_i + b^2 \sum_{v_i \in \bar{A}} d_i = \operatorname{vol}(A) + b^2 \operatorname{vol}(\bar{A})$$

$$= b(\operatorname{vol}(\bar{A}) + \operatorname{vol}(A)) = b \cdot (\mathbf{1}^T D \mathbf{1}).$$

► In addition,

$$y^T D \mathbf{1} = y^T d = 2 \cdot \sum_{v_i \in A} d_i - 2b \cdot \sum_{v_i \in \bar{A}} d_i$$
$$= 2 \cdot \operatorname{vol}(A) - 2b \cdot \operatorname{vol}(\bar{A}) = 0$$

In summary, the **minimal normalized cut** is to solve the following **binary optimization**:

$$\min_{y} \quad \frac{y^{T}Ly}{y^{T}Dy}$$
(1)
s.t. $y(i) \in \{2, -2b\}$
 $y^{T}D\mathbf{1} = 0$

By Relaxation, we solve

$$\min_{y} \quad \frac{y^{T}Ly}{y^{T}Dy}$$
(2)
s.t. $y \in \mathbb{R}^{n}$
 $y^{T}D\mathbf{1} = 0$

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Variational principle

► Let $A, B \in \mathbb{R}^{n \times n}$, $A^T = A$, $B^T = B > 0$ and $\lambda_1 \le \lambda_2 \le \ldots \lambda_n$ be the eigenvalues of $Au = \lambda Bu$ with corresponding eigenvectors u_1, u_2, \ldots, u_n ,

then

$$\min_{x} \frac{x^{T}Ax}{x^{T}Bx} = \lambda_{1} , \quad \arg\min_{x} \frac{x^{T}Ax}{x^{T}Bx} = u_{1}$$

and

$$\min_{x^T B u_1 = 0} \frac{x^T A x}{x^T B x} = \lambda_2 , \quad \arg\min_{x^T B u_1 = 0} \frac{x^T A x}{x^T B x} = u_2.$$

More general form exists.

- For the matrix pair (L, D), it is known that $(\lambda_1, y_1) = (0, 1)$.
- By the variational principle, the relaxed minimal Ncut (2) is equivalent to finding the second smallest eigenpair (λ₂, y₂) of

$$Ly = \lambda Dy \tag{3}$$

Remarks:

- L is extremely sparse and D is diagonal;
- ▶ Precision requirement for eigenvectors is low, say $O(10^{-3})$.

Image segmentation: original graph



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Image segmentation: heatmap of eigenvectors



Image segmentation: result of $\min \textit{Ncut}$



Ncut remaining issues

- Once the indicator vector is computed, how to search the splitting point that the resulting partition has the minimal Ncut(A) value?
- ► How to use the extreme eigenvectors to do the *k*-way partitioning?

The above two problems are addressed in spectral clustering algorithm.

Spectral clustering algorithm [Ng et al, 2002]

Given a weighted graph G = (V, W),

- 1. compute the normalized Laplacian $L_{\rm n} = D^{-\frac{1}{2}}(D-W)D^{-\frac{1}{2}};$
- 2. find k eigenvectors $X = [x_1, ..., x_k]$ corresponding to the k smallest eigenvalues of L_n ;
- 3. form $Y \in \mathbb{R}^{n \times k}$ by normalizing each row of X such that Y(i, :) = X(i, ;) / ||X(i, :)||;
- 4. treat each Y(i,:) as a point, cluster them into k clusters via K-means with label $c_i = \{1, ..., k\}$.

The label c_i indicates the cluster that v_i belongs to.

Synthetic example: original data



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Synthetic example: computed eigenvectors



Synthetic example: 2-way clustering



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Synthetic example: 3-way clustering



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Synthetic example: 4-way clustering



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Extension: constrained spectral clustering Spectral clustering



Ncut segmentation



Constrained spectral clustering

constraint Ncut



constrained segmentation



References

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- 4. PhD thesis work of C. Jiang http://cmjiang.cs.ucdavis.edu/fastge2.html