



Structural DNA nanotechnology

a.k.a. DNA carpentry

a.k.a. DNA self-assembly

slides © 2021, David Doty

ECS 232: Theory of Molecular Computation, UC Davis



Ljubljana Marshes Wheel. 5k years old

Building things



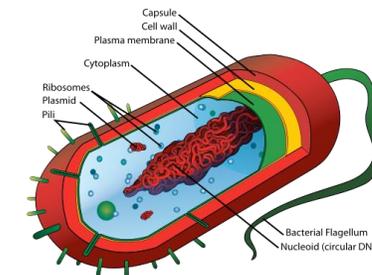
Newgrange, Ireland. 5.2k years old

Building things by hand: use tools! Great for scale of $10^{\pm 2} \times$ 

Building tools that build things: specify target object with a computer program

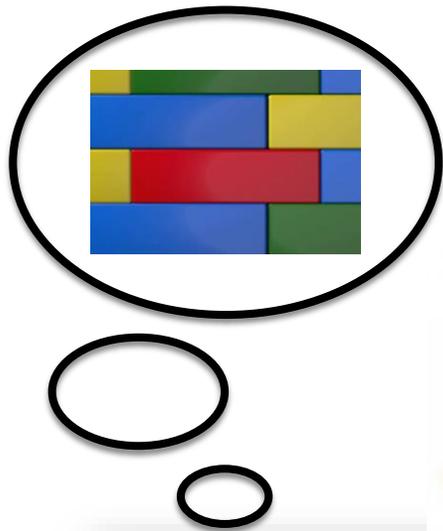


Programming things to build themselves: for building in small wet places where our hands or tools can't reach



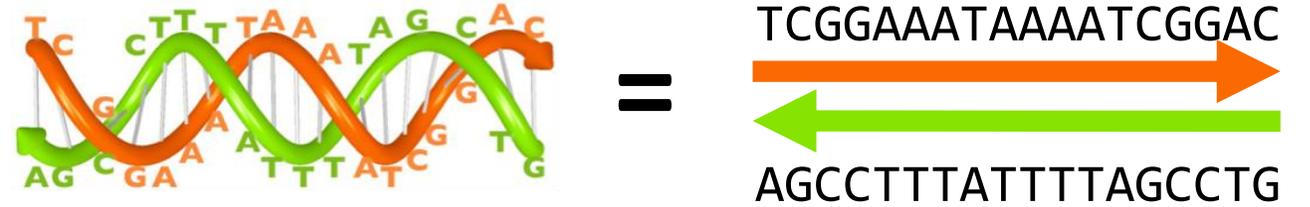
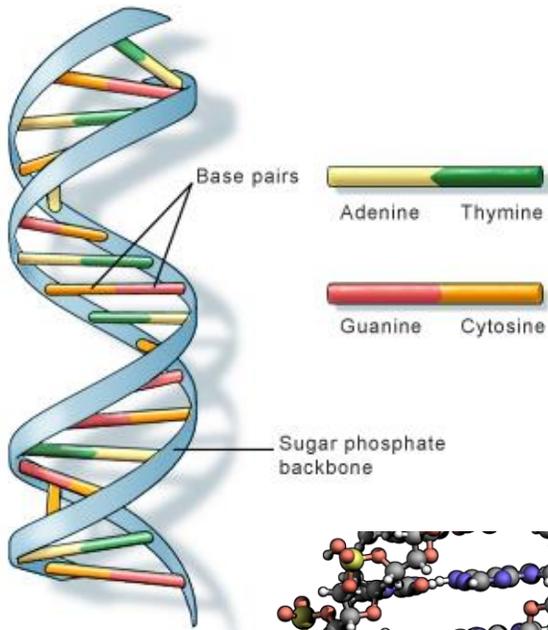
Mariana Ruiz Villarreal

Things that build themselves

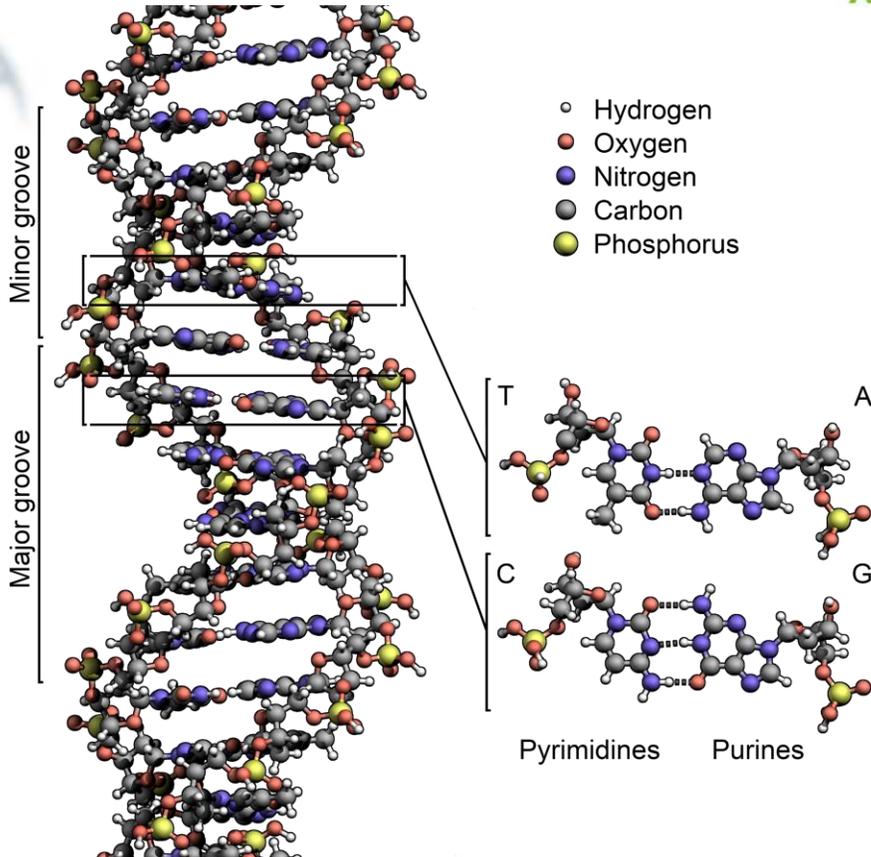


Our topic: self-assembling molecules that compute as they build themselves

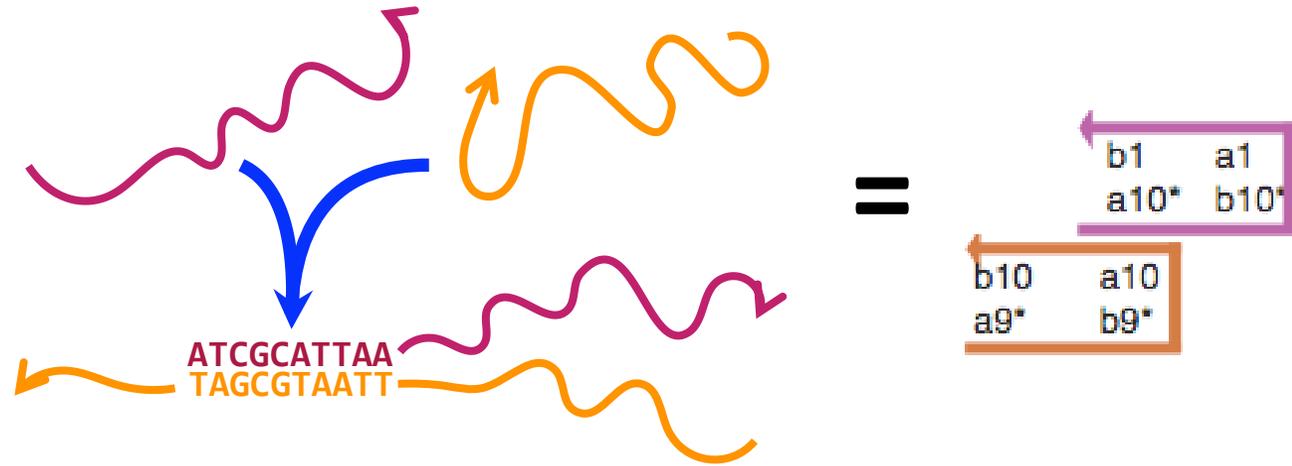
DNA as a building material



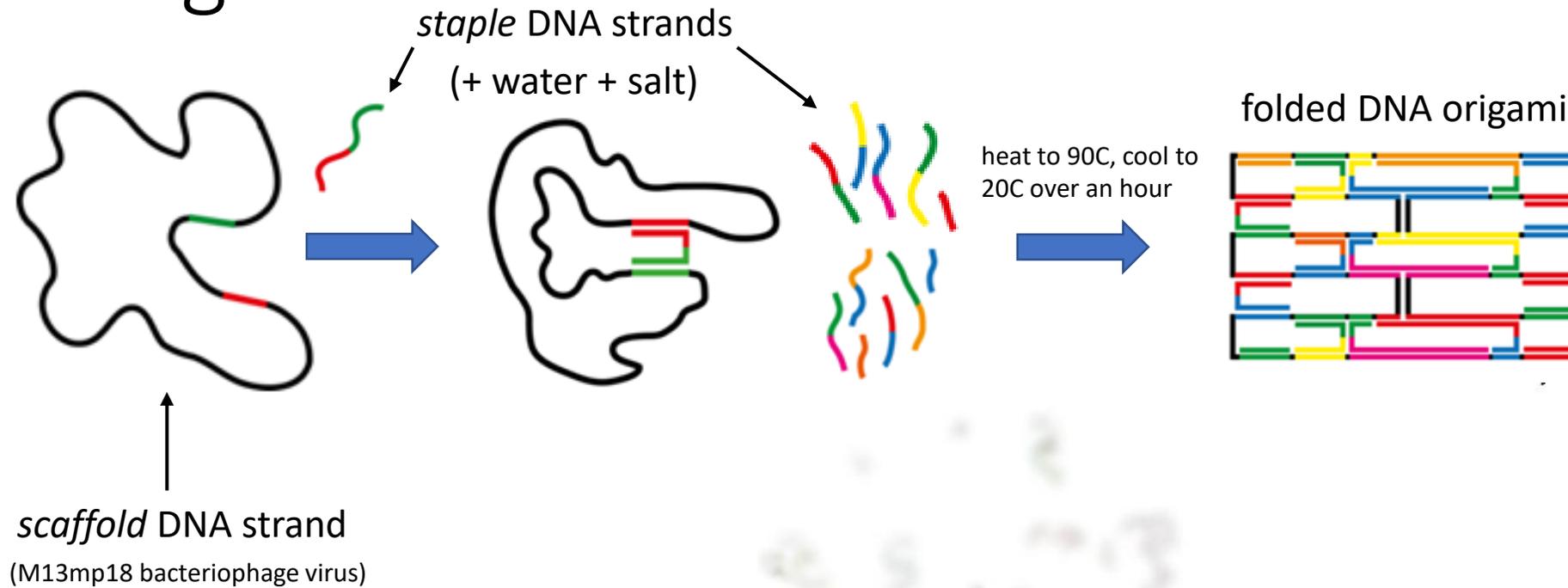
U.S. National Library of Medicine



DNA strands bind even if only *part* of strands are complementary:



DNA origami



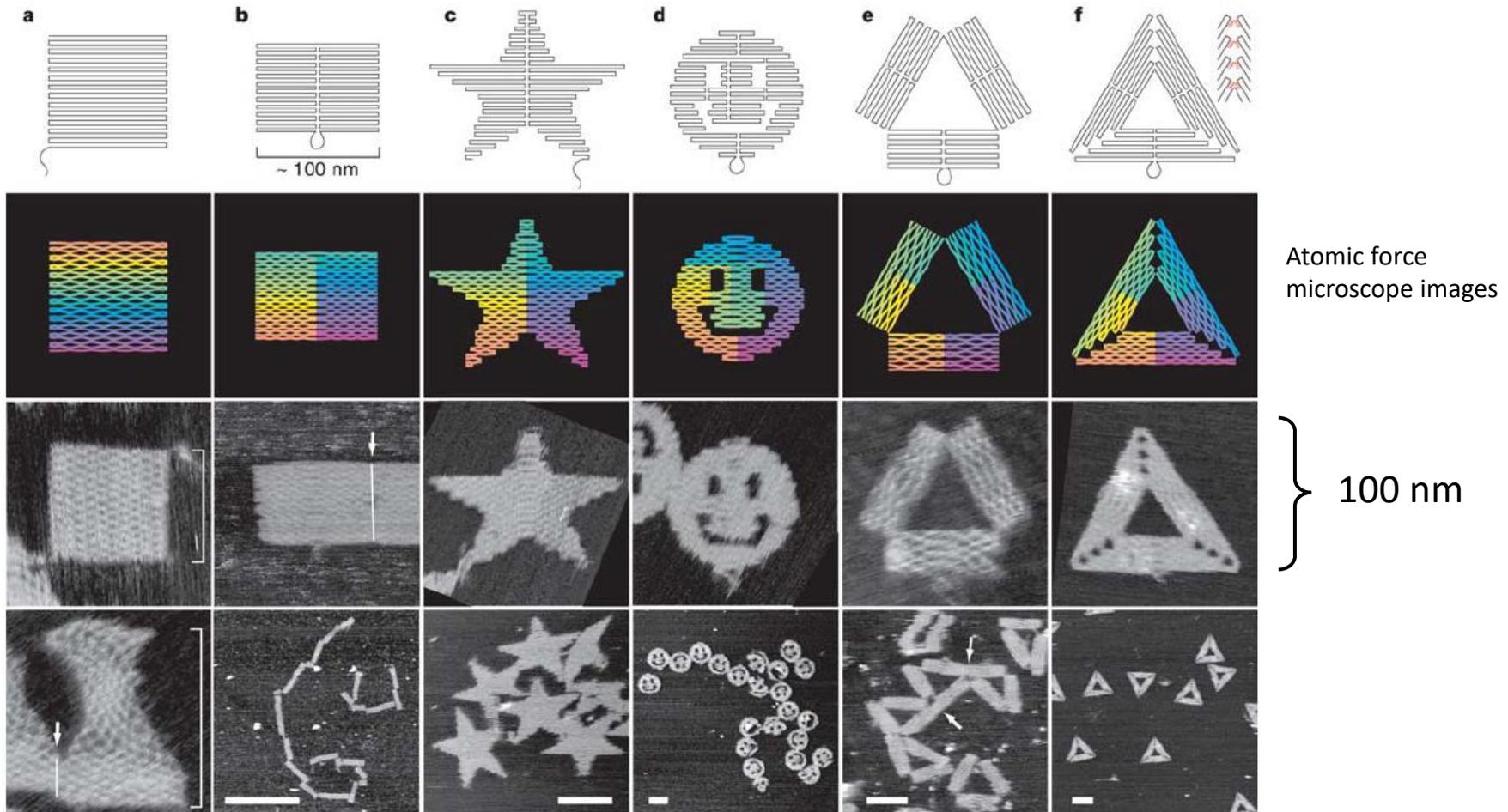
Paul Rothemund
Folding DNA to create nanoscale shapes and patterns
Nature 2006

DNA origami

Paul Rothemund

Folding DNA to create nanoscale shapes and patterns

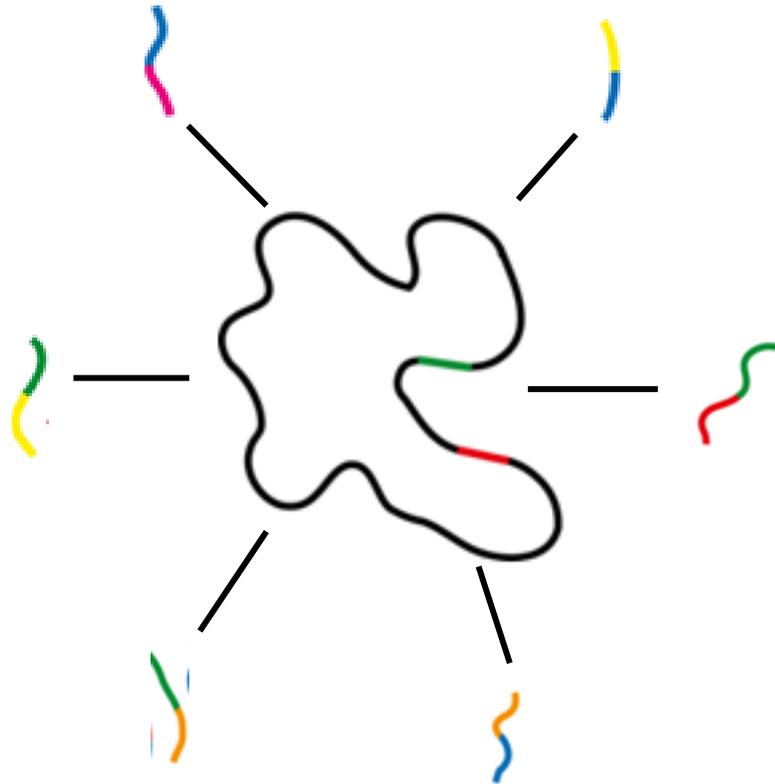
Nature 2006



Binding graphs

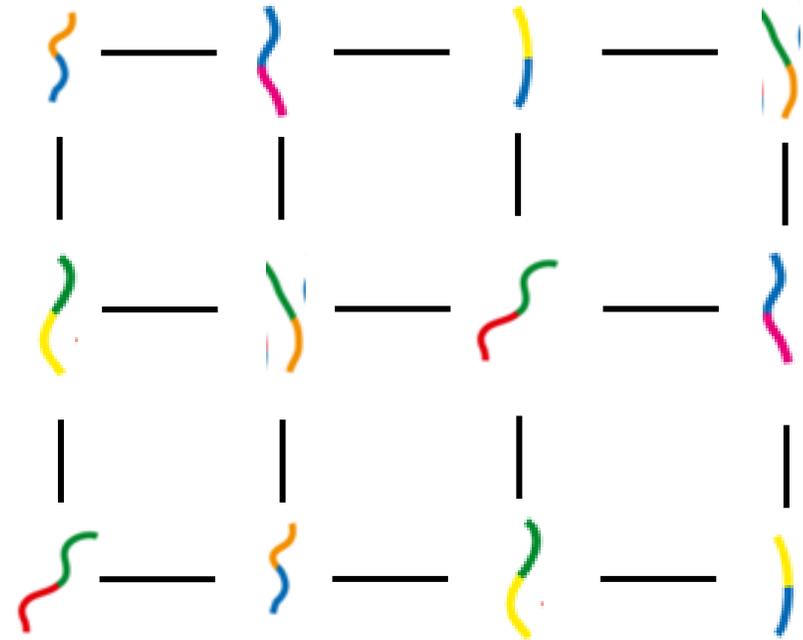
DNA origami: **star graph**

(all binding is between staples and scaffold)



DNA tiles: **grid graph**

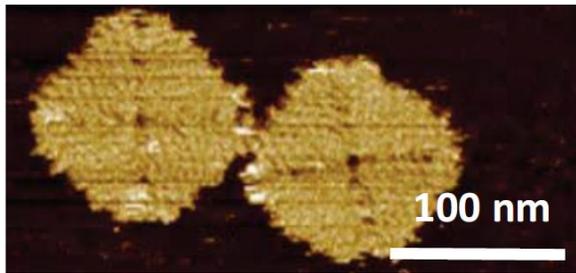
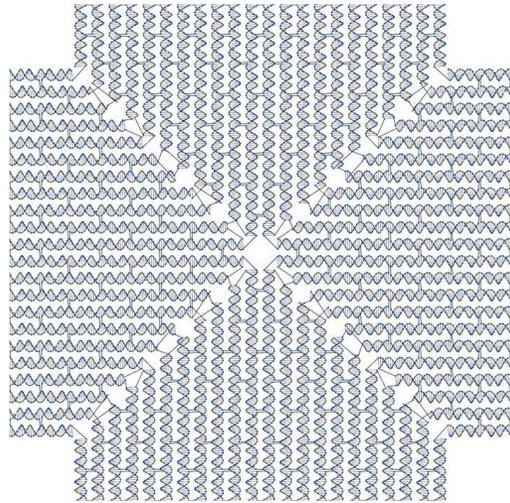
(tiles bind to each other, each has ≤ 4 neighbors)



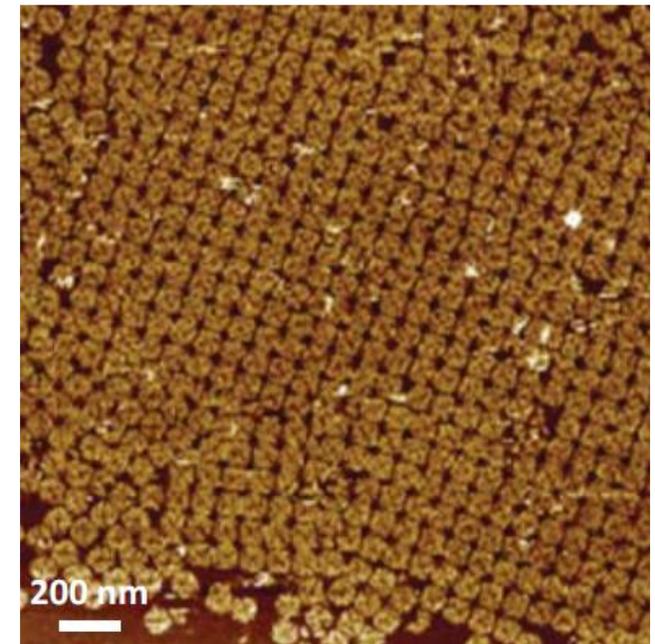
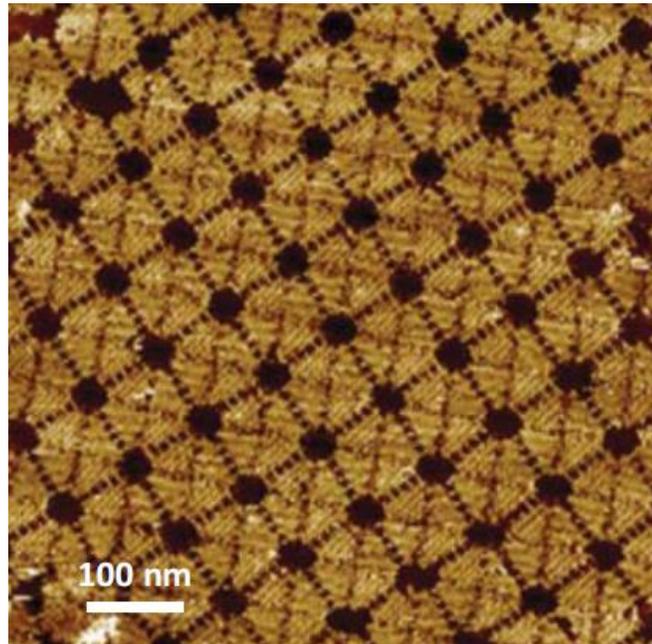
DNA tile self-assembly

monomers (“tiles” made from DNA) bind into a crystal lattice

tile

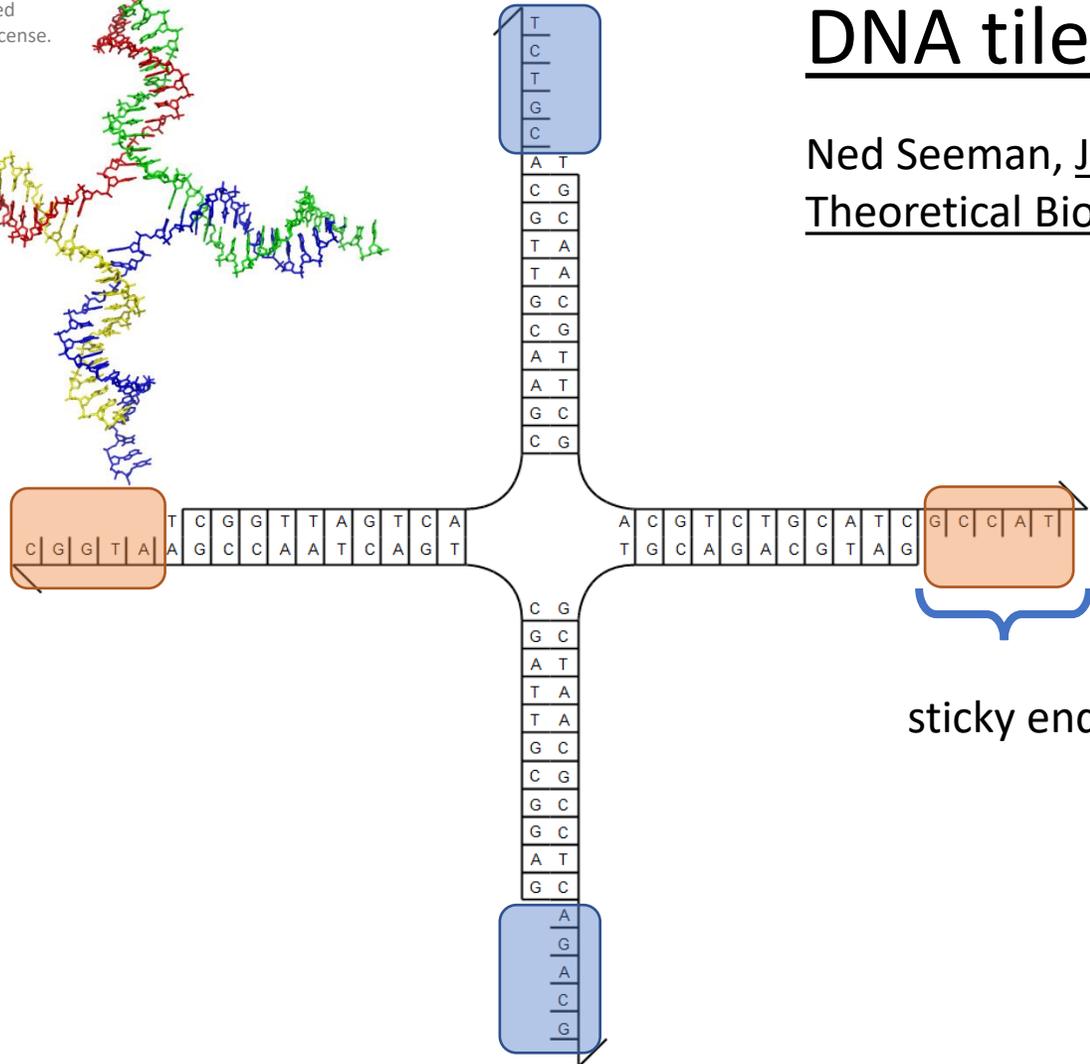
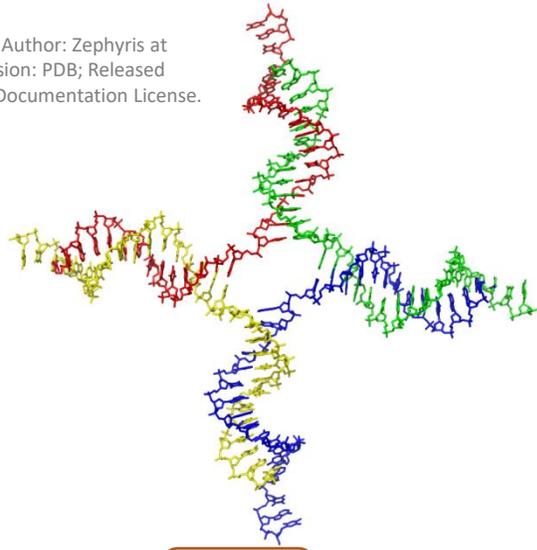


lattice



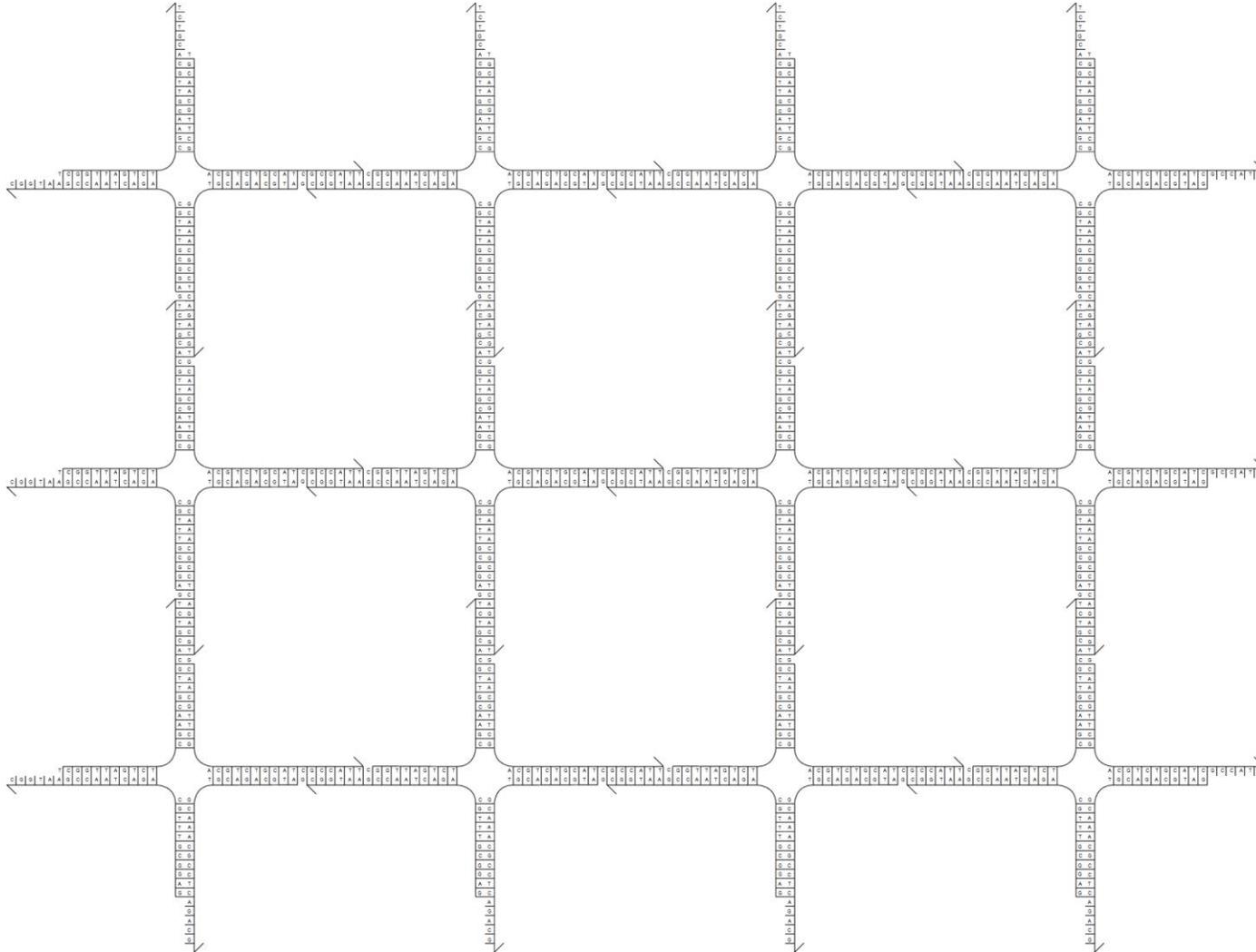
Practice of DNA tile self-assembly

Source:en.wikipedia; Author: Zephyris at en.wikipedia; Permission: PDB; Released under the GNU Free Documentation License.

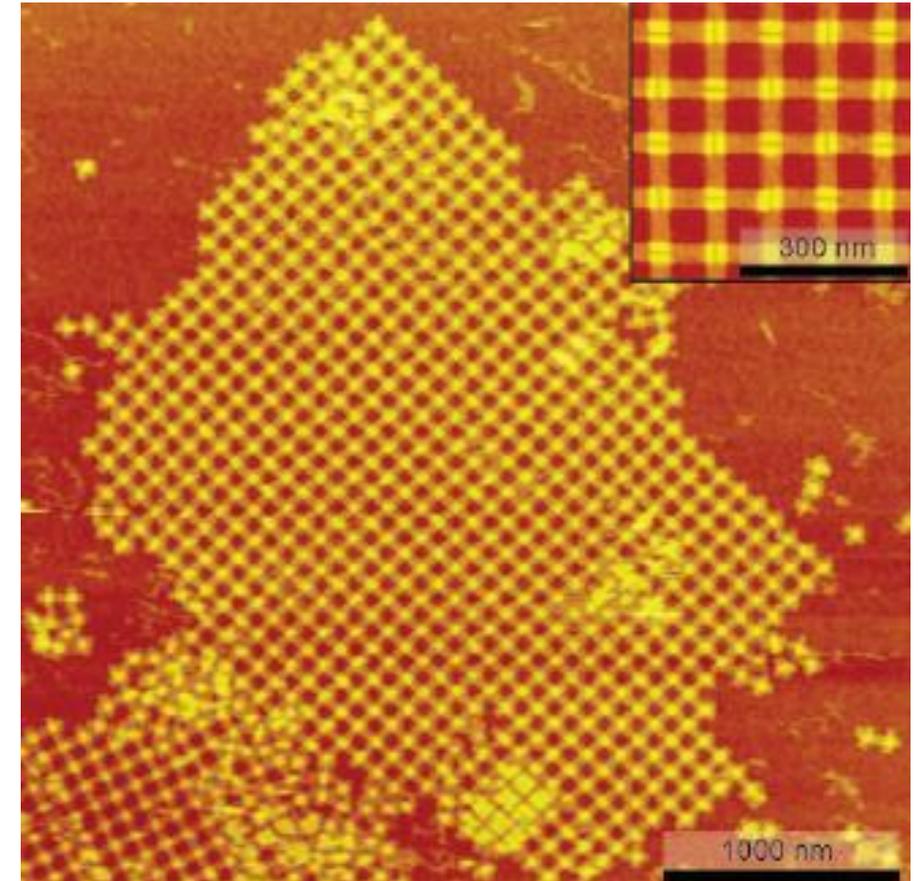


Practice of DNA tile self-assembly

Place many copies of DNA tile in solution...



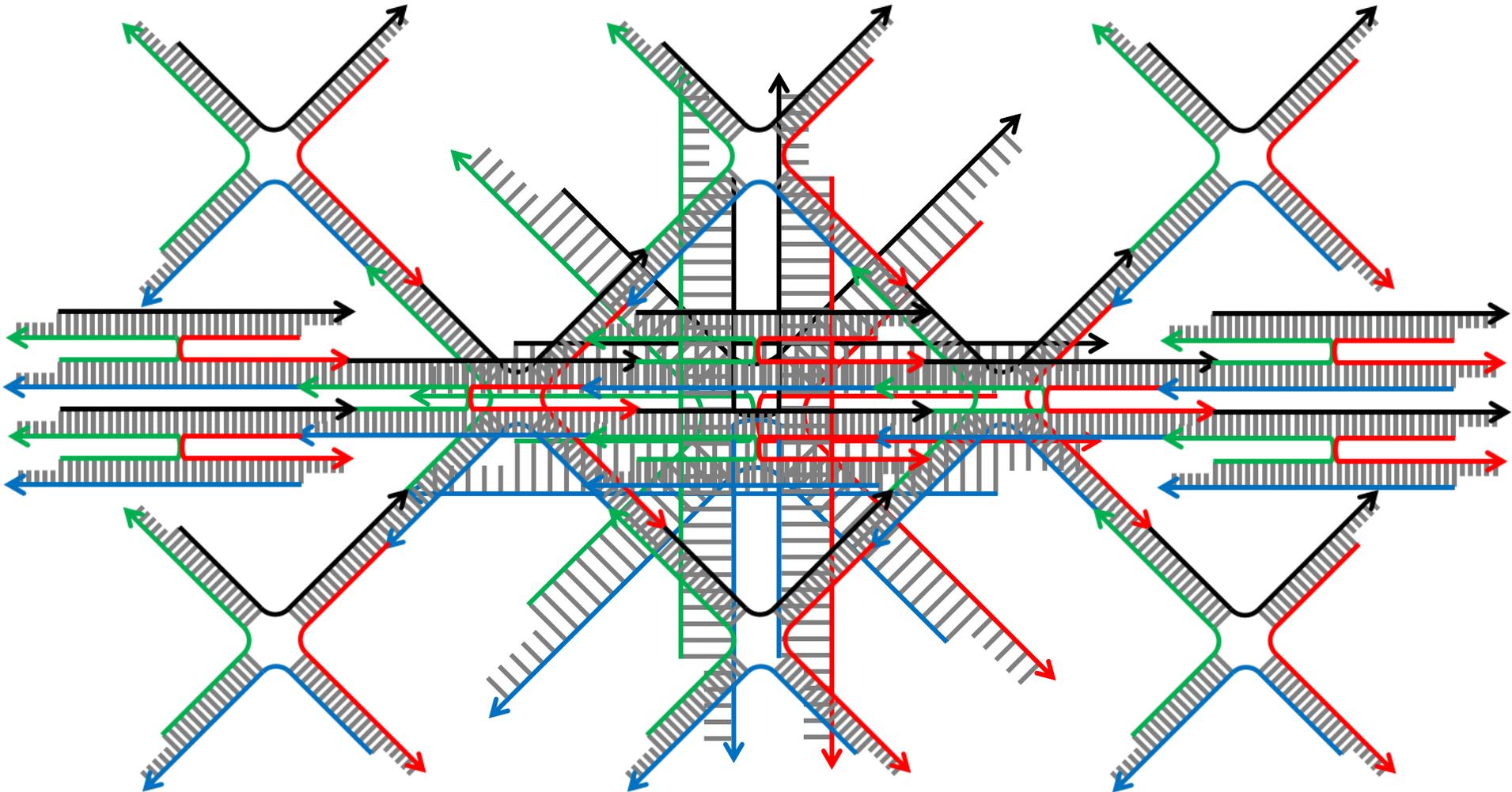
(not the same tile motif in this image)



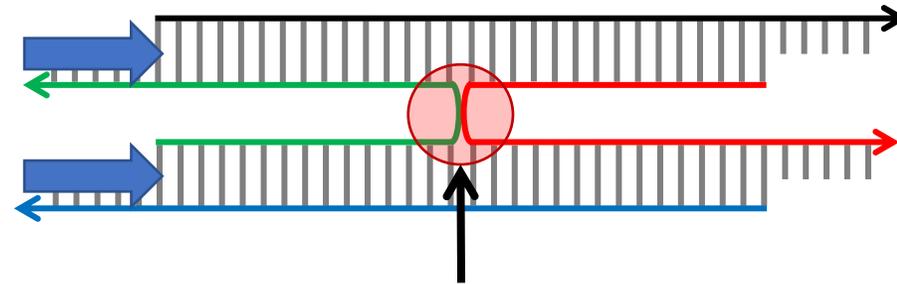
Liu, Zhong, Wang, Seeman, *Angewandte Chemie* 2011

Practice of DNA tile self-assembly

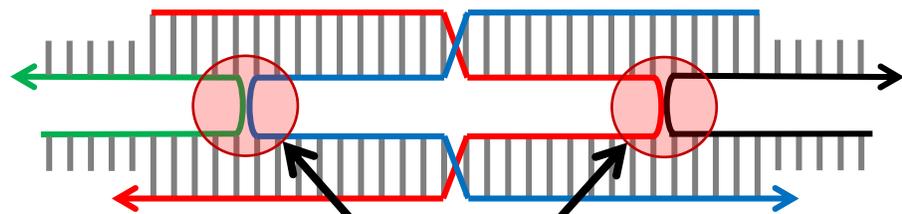
What really happens in practice to Holliday junction (“base stacking”)



Practice of DNA tile self-assembly



single crossover



double crossover

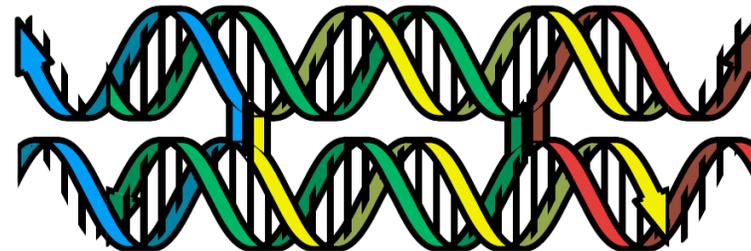
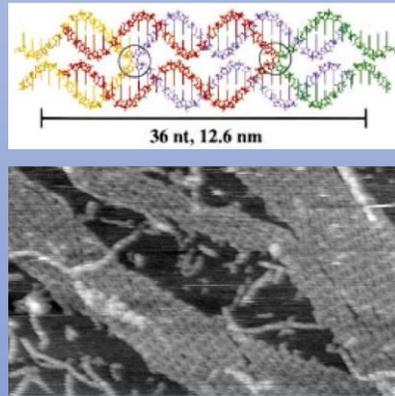


Figure from Schulman, Winfree, *PNAS* 2009

Practice of DNA tile self-assembly

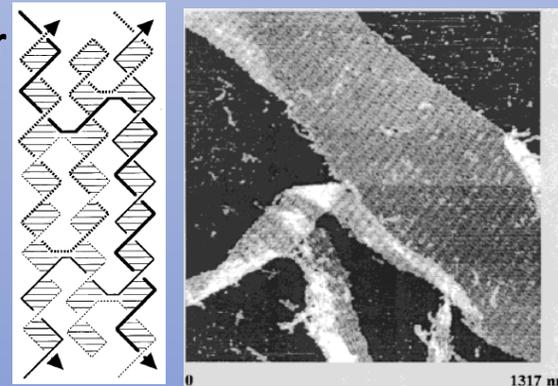
double-crossover tile

(Winfree, Liu, Wenzler, Seeman, *Nature* 1998)



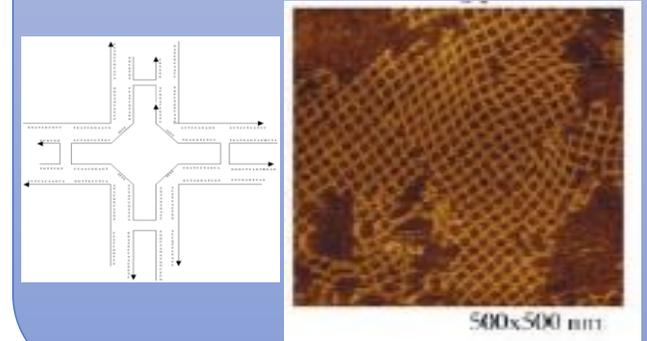
triple-crossover tile

(LaBean, Yan, Kopatsch, Liu, Winfree, Reif, Seeman, *JACS* 2000)



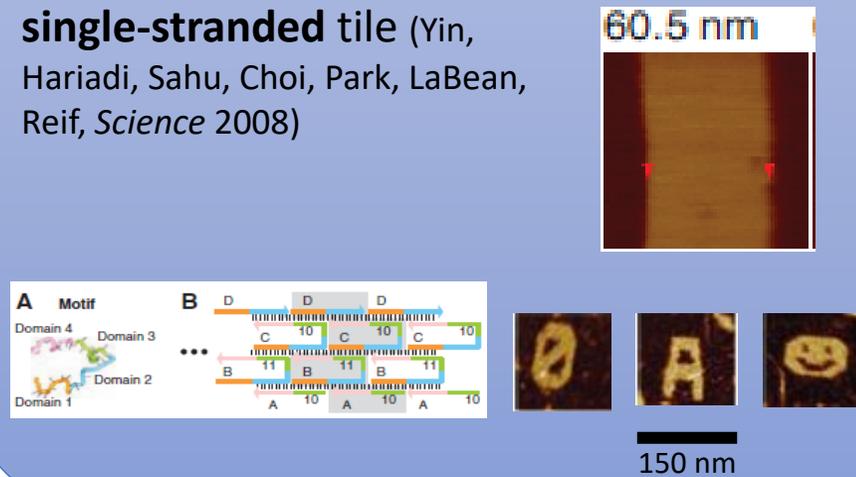
4x4 tile

(Yan, Park, Finkelstein, Reif, LaBean, *Science* 2003)



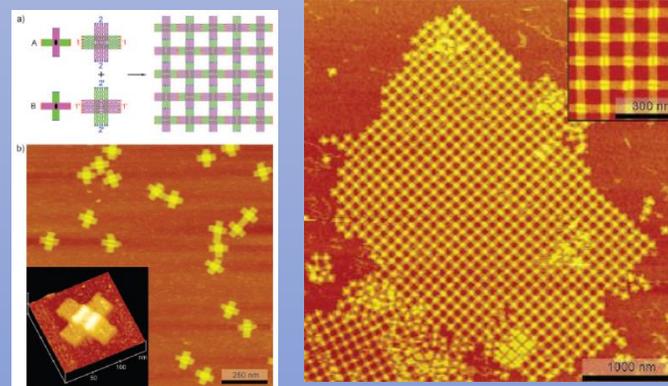
single-stranded tile

(Yin, Hariadi, Sahu, Choi, Park, LaBean, Reif, *Science* 2008)



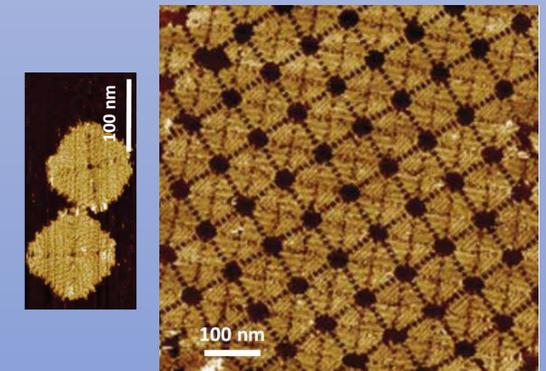
DNA origami tile

(Liu, Zhong, Wang, Seeman, *Angewandte Chemie* 2011)



Tikhomirov, Petersen, Qian

(*Nature Nanotechnology* 2017)



Theory of *algorithmic* self-assembly

What if...

... there is more than one tile type?

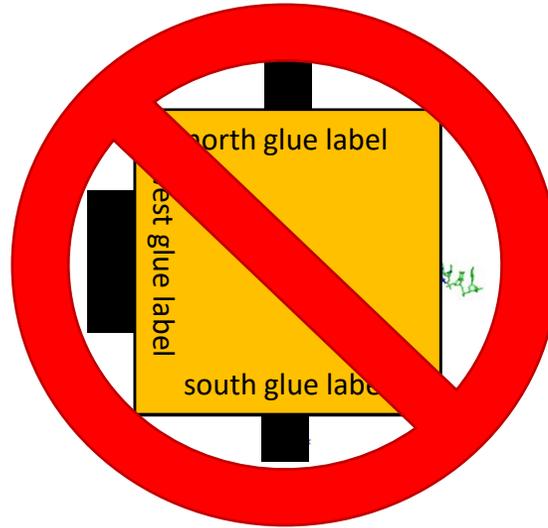
... some sticky ends are “weak”?



Erik Winfree

abstract Tile Assembly Model (aTAM)

- **tile type** = unit square
- each side has a **glue** with a **label** and **strength** (0, 1, or 2)
- tiles cannot rotate



strength 0



strength 1 (weak)



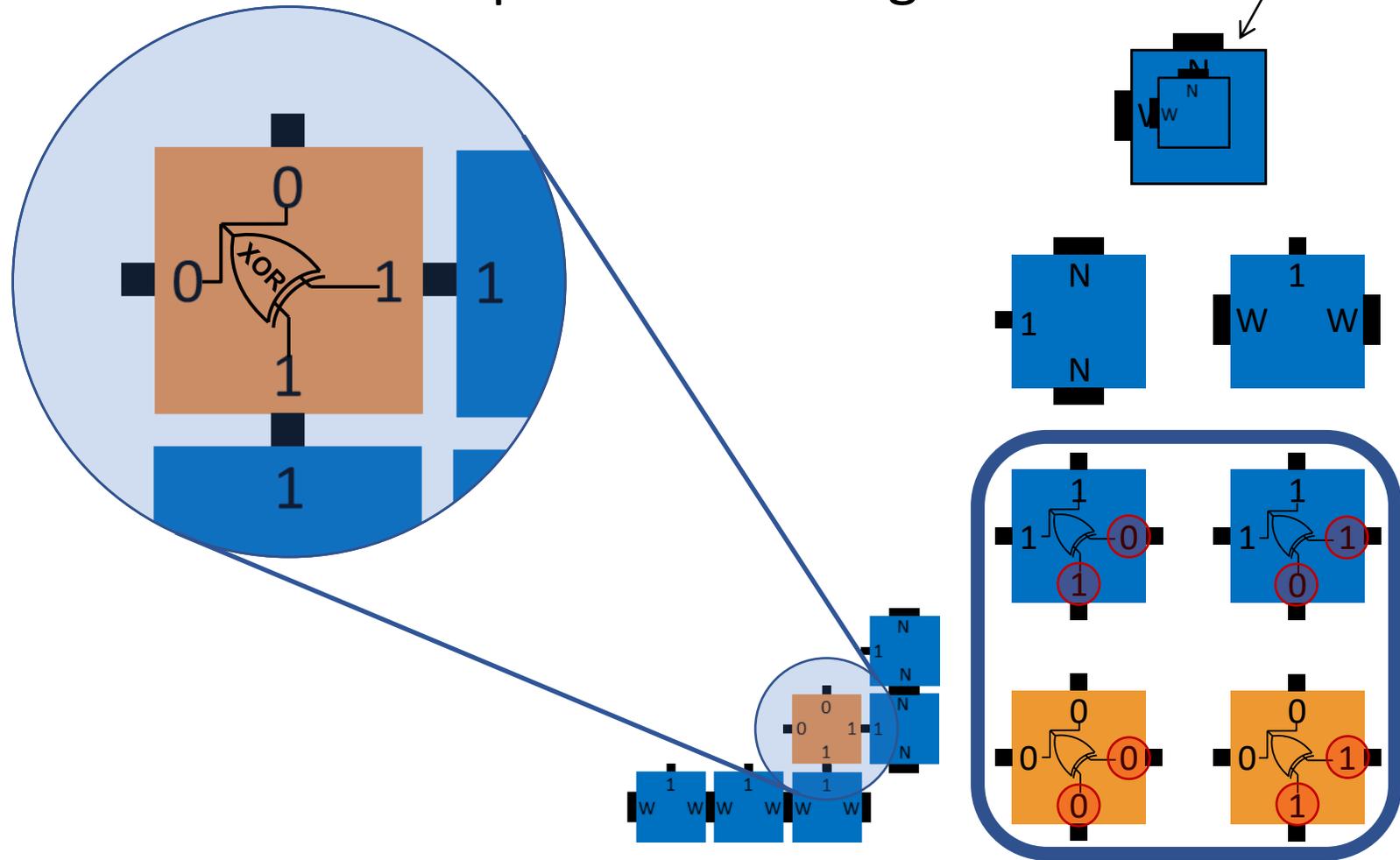
strength 2 (strong)

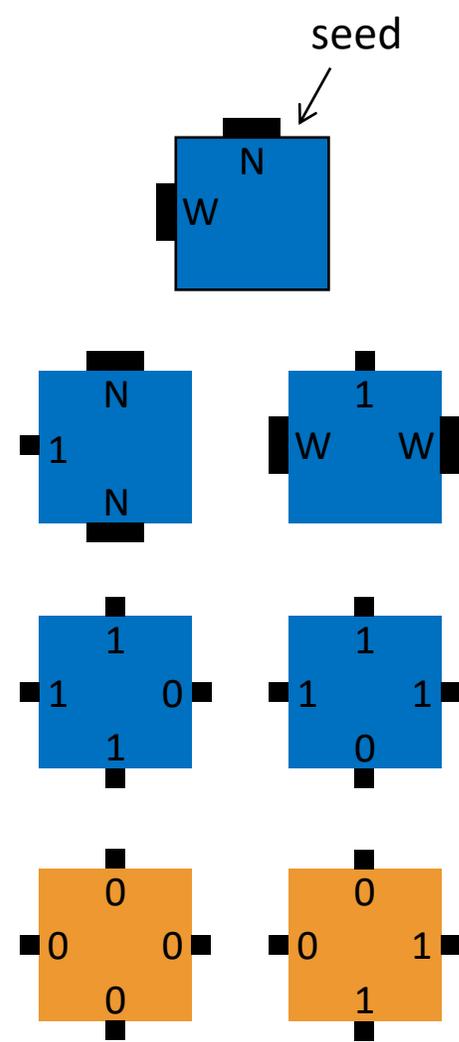
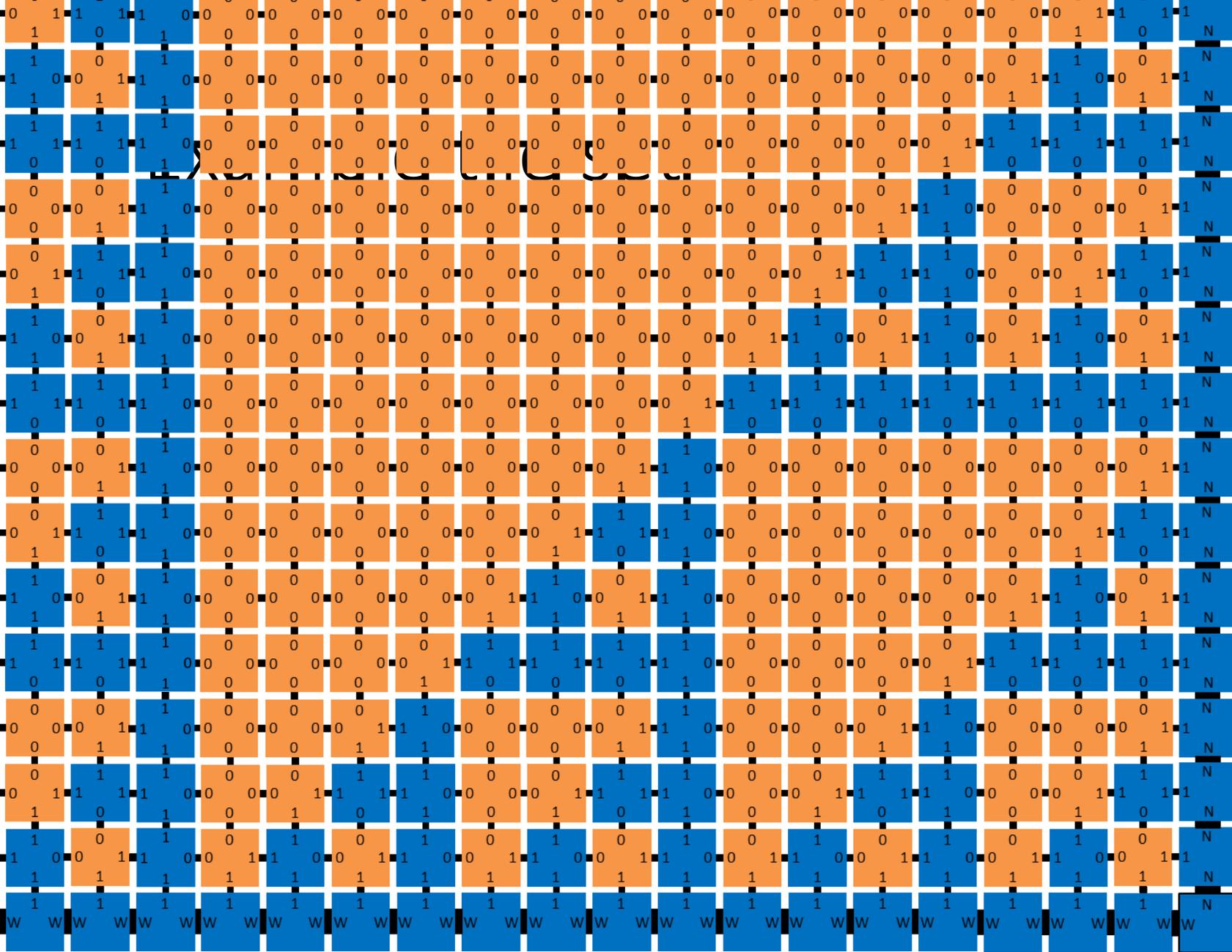


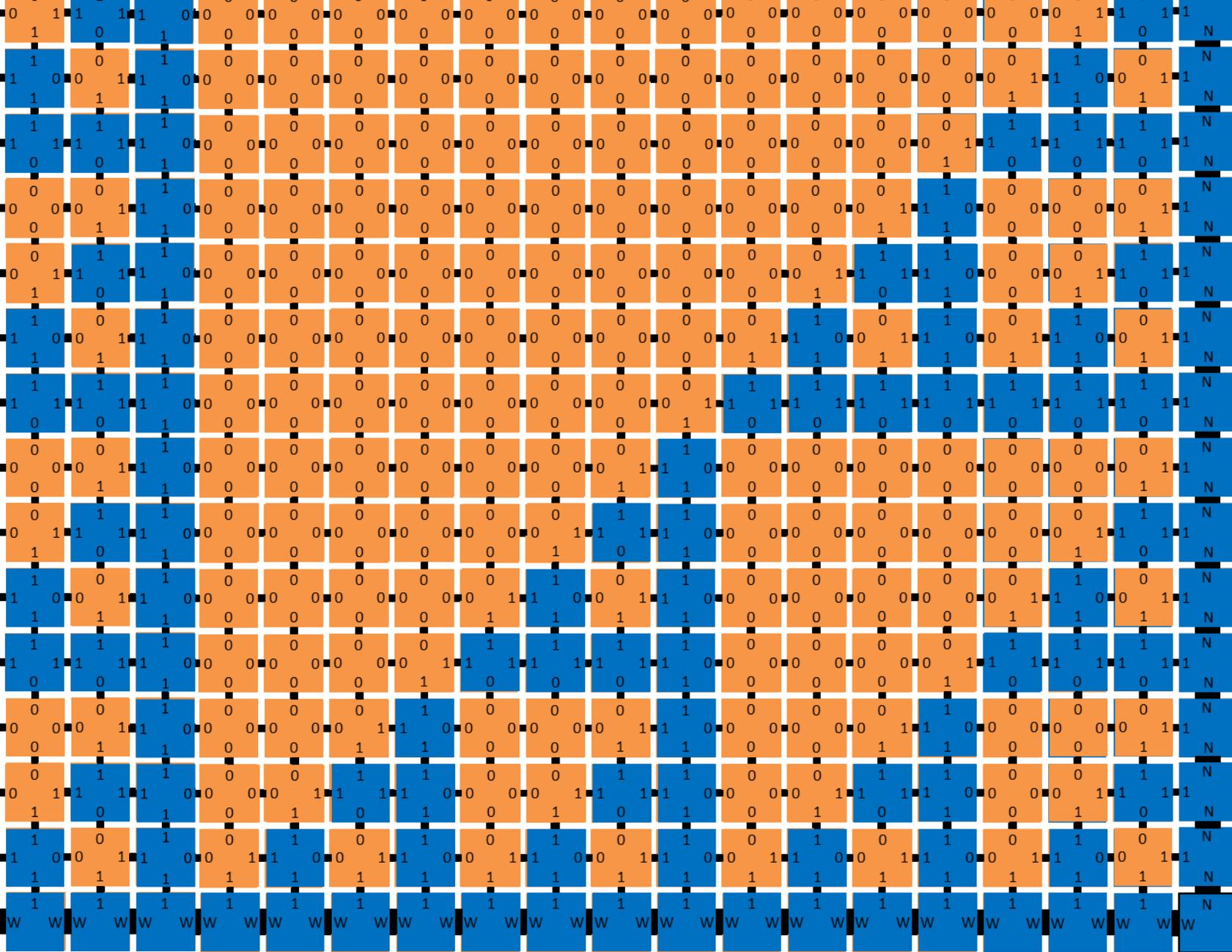
- finitely many tile **types**
- infinitely many **tiles**: copies of each type
- assembly starts as a single copy of a special **seed** tile
- tile can bind to the assembly if total binding strength ≥ 2 (**two weak glues** or **one strong glue**)

Example tile set

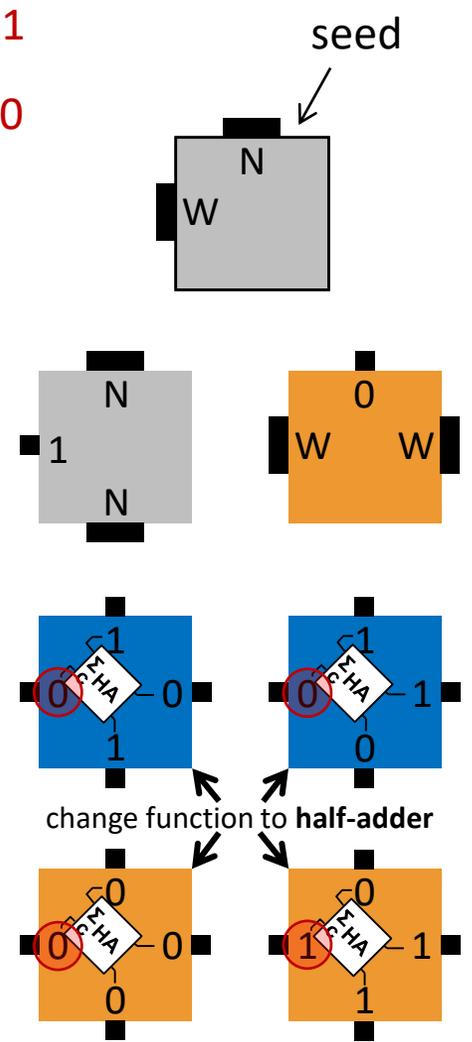
“cooperative binding”



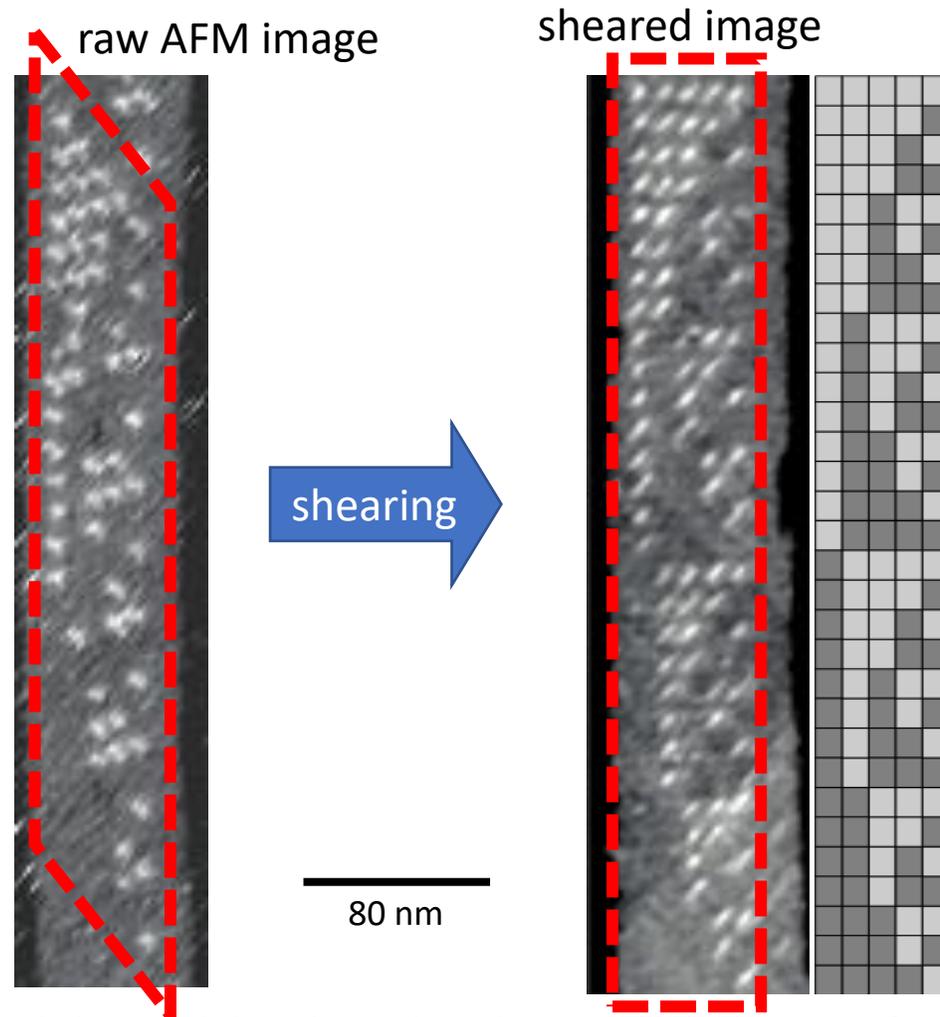




14
13
12
11
10
9
8
7
6
5
4
3
2
1
0



Algorithmic self-assembly in action



[Crystals that count! Physical principles and experimental investigations of DNA tile self-assembly, Constantine Evans, Ph.D. thesis, Caltech, 2014]

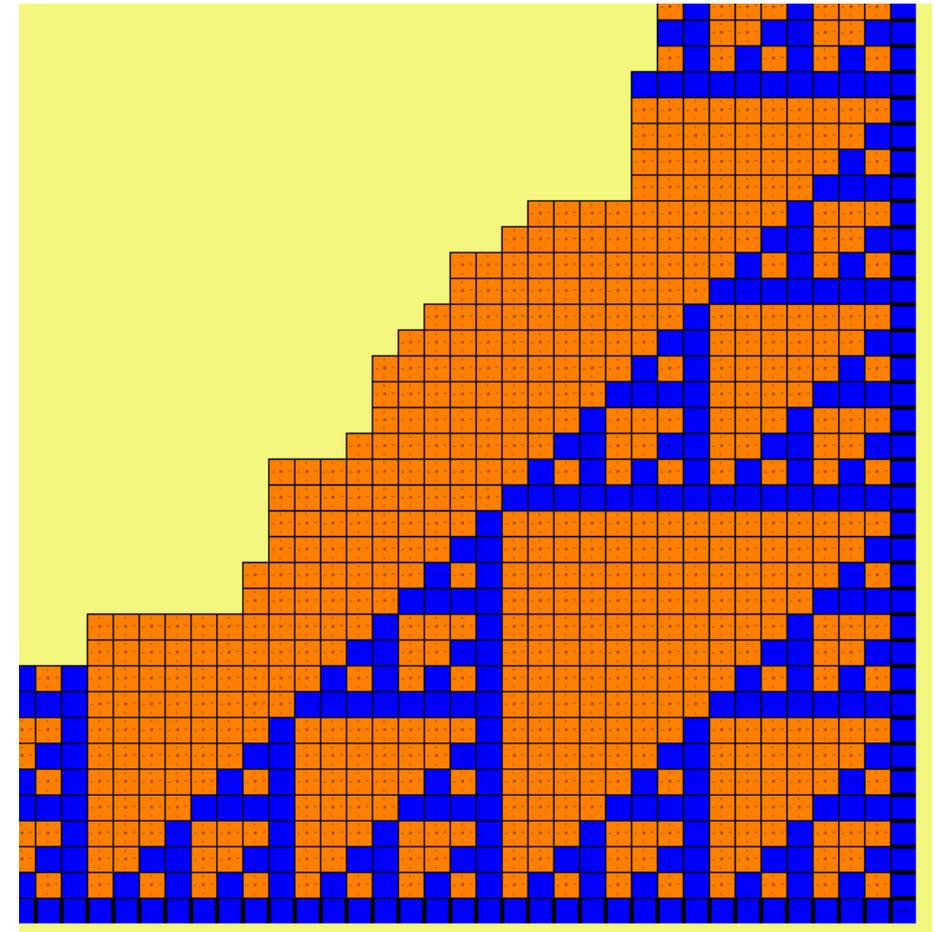
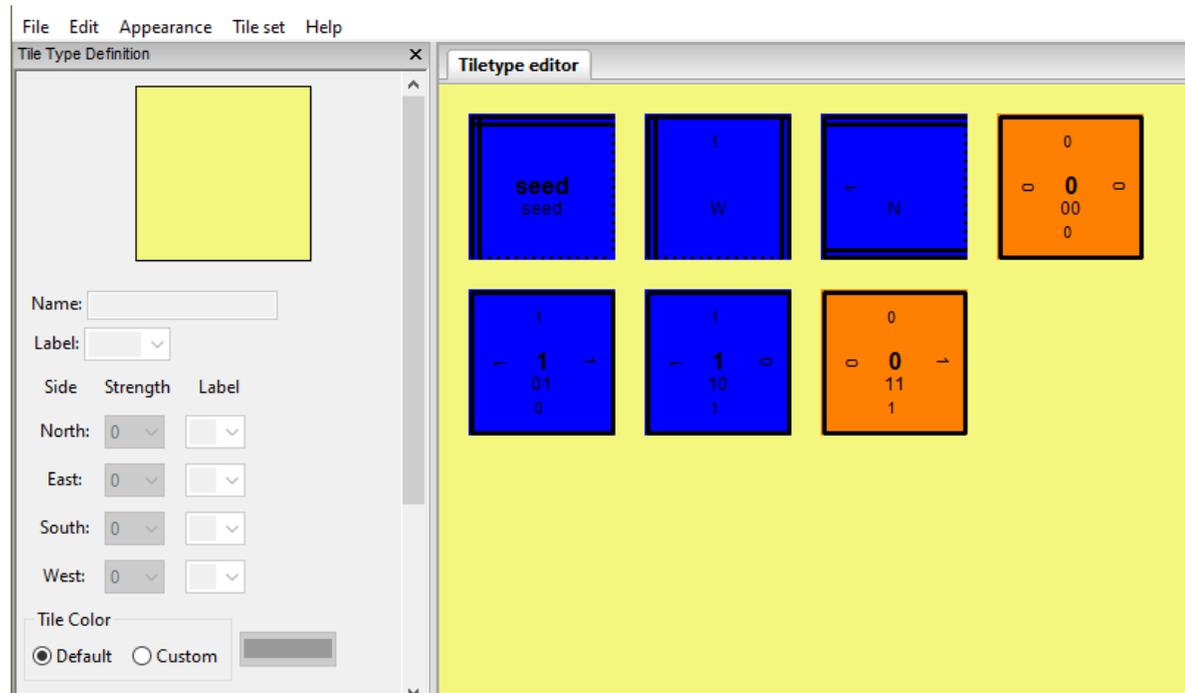
aTAM simulator (ISU TAS by Matt Patitz)

http://self-assembly.net/wiki/index.php?title=ISU_TAS

http://self-assembly.net/wiki/index.php?title=ISU_TAS_Tutorials

See also WebTAS by the same group:

<http://self-assembly.net/software/WebTAS/WebTAS-latest/>



VersaTile (by Eric Martinez and Cameron Chalk) <https://github.com/ericmichael/polyomino>
and xgrow (by Erik Winfree) <https://www.dna.caltech.edu/Xgrow/>

Tile complexity of squares

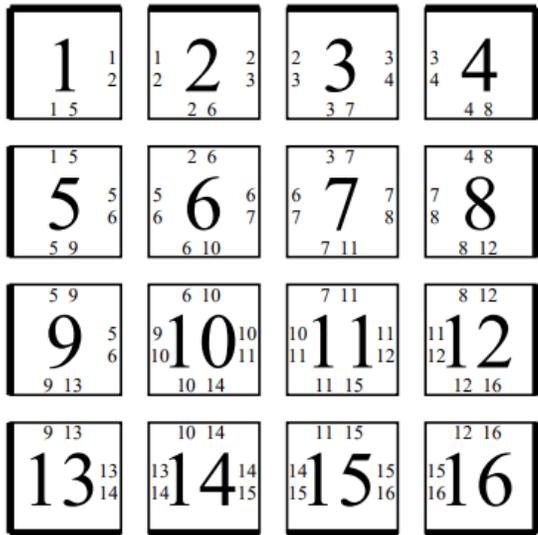
Tile complexity

- Resource bound to minimize, like time or memory with a traditional algorithm.
- Why minimize number of tile types?
 - Physically synthesizing new tile types is difficult.
 - Designing DNA sequences for new tile types is difficult. (DNA sequence design is tougher when more DNA sequences are present.)
 - But due to how modern synthesis technologies work, once a tile type is designed, making 50 quadrillion copies of the tile is as easy as making one copy.
- So, we ask: how many unique tile types do we need to self-assemble some shapes?
- We start with $n \times n$ squares as the “simplest” benchmark shape.
 - Why not a $1 \times n$ line as an even simpler shape? What is its tile complexity?
- *[Note: we have not formally defined the aTAM yet... first let's build intuition.]*

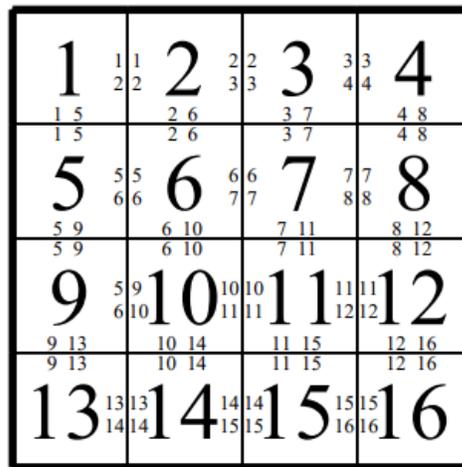
The program size complexity of self-assembled squares

Question: How many tile types do we need to self-assemble an $n \times n$ square?

Concretely: how to assemble a 4×4 square?



All glues are strength 2
(alternately: all are strength 1 and *temperature* $\tau = 1$)



How many tile types does this construction need in general to assemble an $n \times n$ square?

$$n^2$$

Tile complexity at temperature $\tau = 1$ (i.e., no cooperative binding allowed)

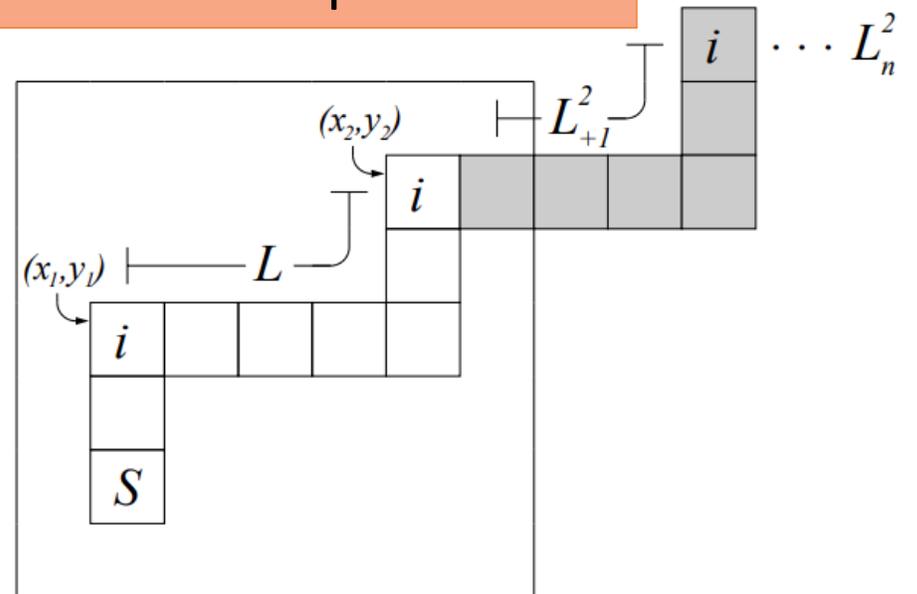
Is n^2 optimal?
Can we do better?

Note all pairs of adjacent tiles bind with positive strength:

1 <small>1 5 1 5</small>	2 <small>2 2 2 6</small>	3 <small>3 3 3 7</small>	4 <small>4 4 4 8</small>
5 <small>5 5 5 9</small>	6 <small>6 6 6 10</small>	7 <small>7 7 7 11</small>	8 <small>8 8 8 12</small>
9 <small>9 9 9 13</small>	10 <small>10 10 10 14</small>	11 <small>11 11 11 15</small>	12 <small>12 12 12 16</small>
13 <small>13 13 14 14</small>	14 <small>14 14 15 15</small>	15 <small>15 15 16 16</small>	16 <small>16 16</small>

Theorem: At temperature $\tau = 1$, if all pairs of adjacent tiles bind with positive strength, then for every positive integer n , n^2 tile types are necessary to self-assemble an $n \times n$ square.

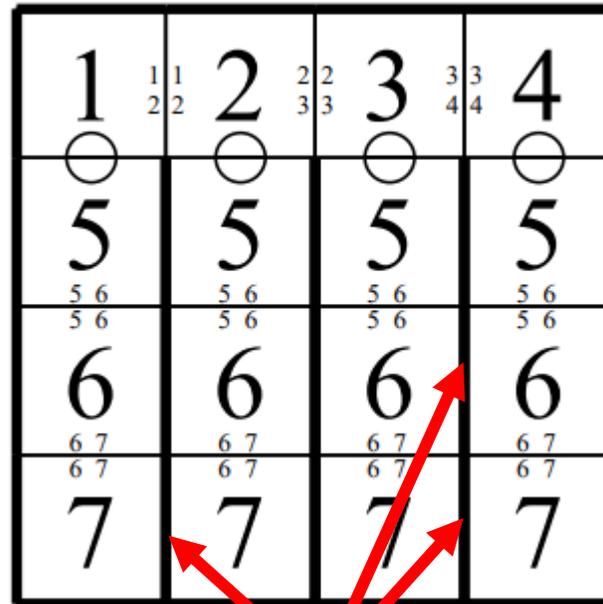
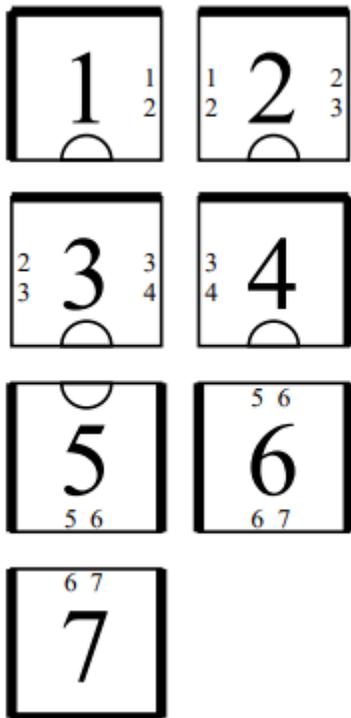
Proof: Suppose for contradiction we use the same tile type i at positions (x_1, y_1) and (x_2, y_2) . Then they have a path L between them with all positive-strength glues, and this can happen instead:



Tile complexity at temperature $\tau = 1$, where not all adjacent tiles are bound

Is n^2 still optimal?

No!



strength-0 glues

Tile complexity of
this construction?

$$2n - 1 = O(n)$$

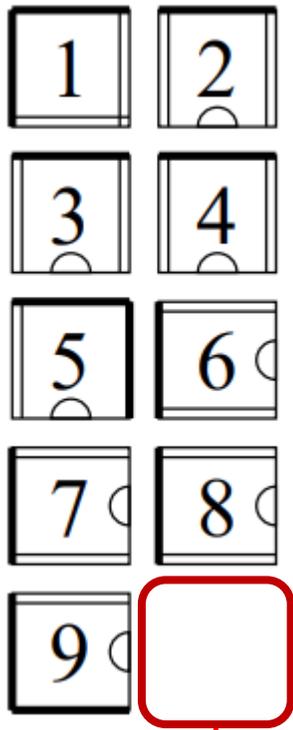
Conjecture: The temperature $\tau = 1$ tile complexity of an $n \times n$ square is $\Omega(n)$.

(most recent progress:

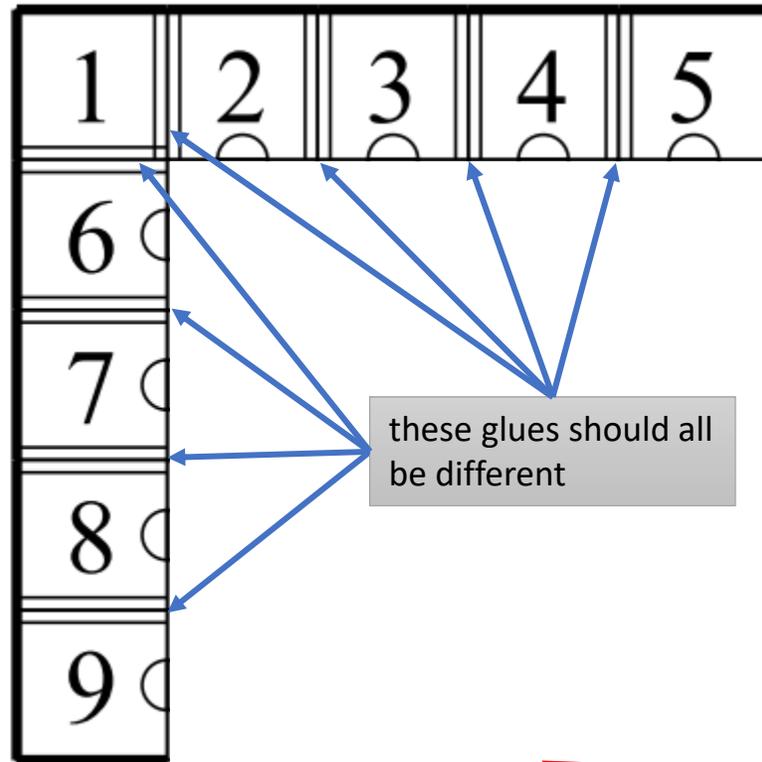
<https://arxiv.org/abs/1902.02253>

<https://arxiv.org/abs/2002.04012>)

Tile complexity at temperature $\tau = 2$ (i.e., cooperative binding allowed)



This tile completes an $n \times n$ "L shape" into an $n \times n$ square.



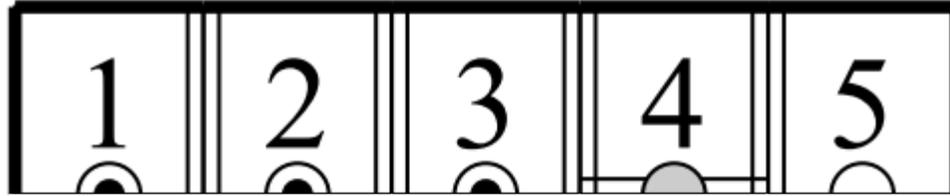
these glues should all be different

Tile complexity = $2n$

strength-1 glues (with no other glues to cooperate with)

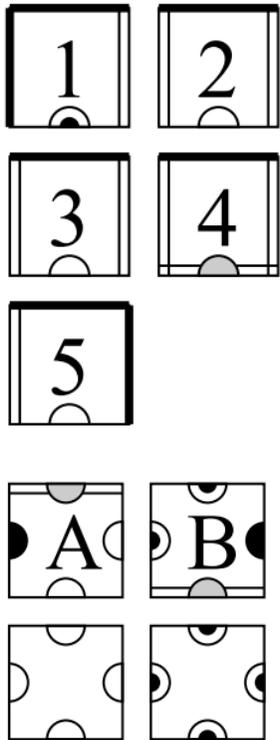
Tile complexity at temperature $\tau = 2$

Goal: complete a $1 \times n$ line
into an $n \times n$ square



Tile complexity = $n + 4$

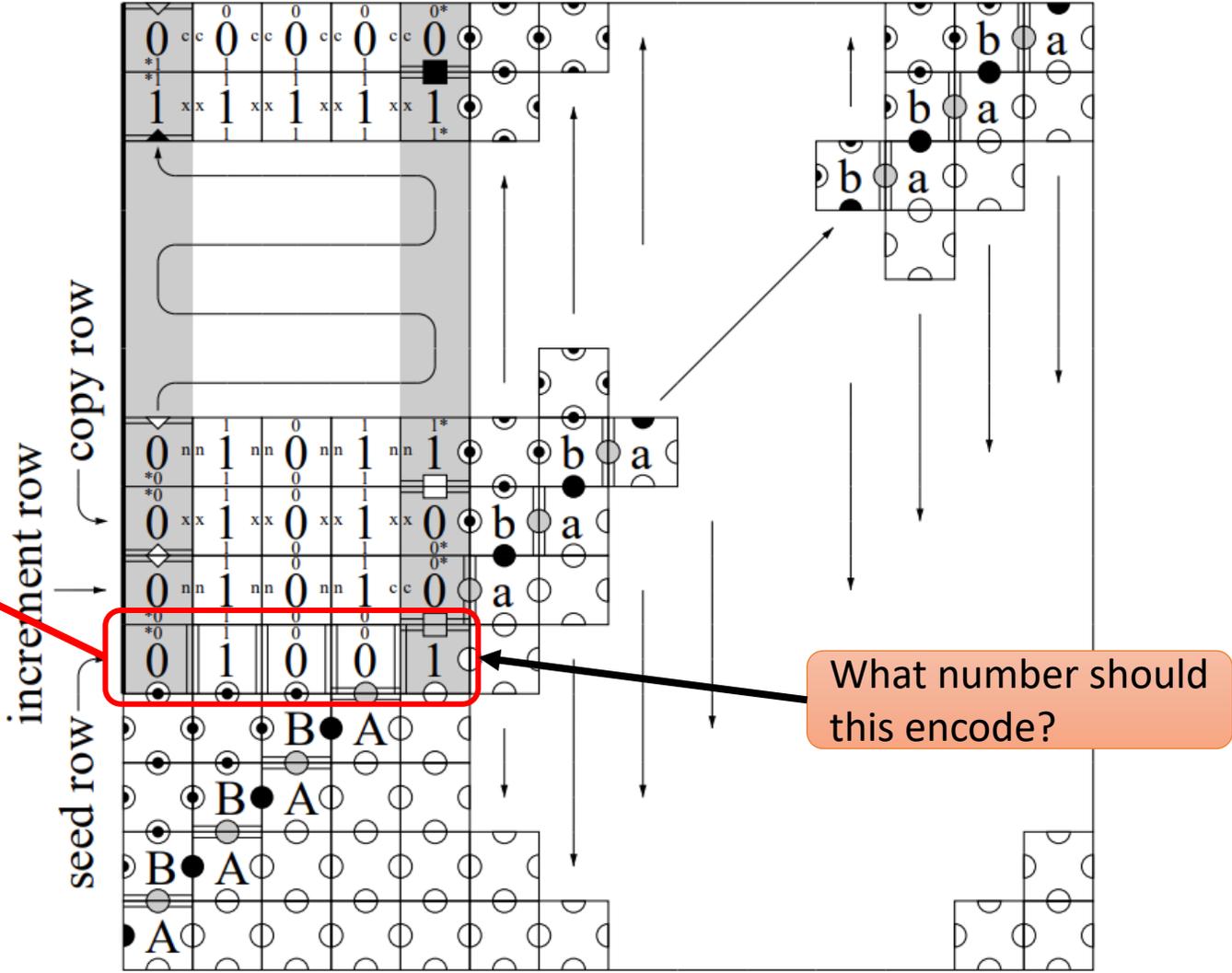
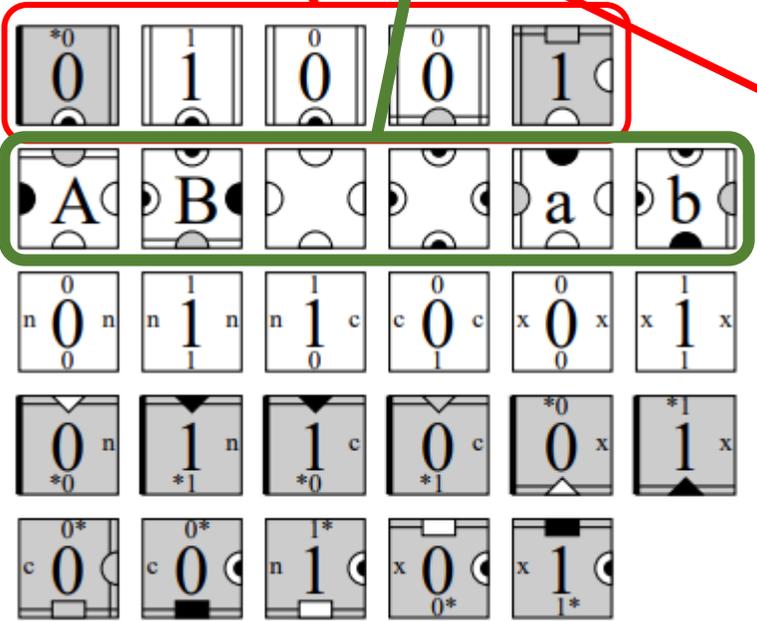
How to get *sublinear*
tile complexity?



Logarithmic tile complexity at temperature $\tau = 2$

A few more "filler" tiles complete the $\approx n \times \log n$ rectangle into an $n \times n$ square.

tile complexity = $\log n + 23$



What number should this encode?

$\Omega(\log n / \log \log n)$ tile complexity lower bound for $n \times n$ squares

- What does $\Omega(\log n / \log \log n)$ tile complexity lower bound mean?
 - First let's think about what we already showed: what does $O(\log n)$ tile complexity upper bound mean? **For all n , $O(\log n)$ tile types is enough to self-assemble an $n \times n$ square.**
 - A lower bound looks like: **For infinitely many n , $o(\log n / \log \log n)$ tile types is not enough to self-assemble an $n \times n$ square.**
- How to prove? It's a counting argument:
 - Count number of (functionally distinct) tile systems with fewer than $\frac{1}{4} \log p / \log \log p$ tile types.
 - We'll show that it's fewer than p .
 - There are p squares with width n between $p+1$ and $2p$; each needs a different tile system.
 - By pigeonhole, some $n \times n$ square cannot be assembled with $< \frac{1}{4} \log p / \log \log p$ tile types.
 - Since $p \leq n/2$, we have $\frac{1}{4} \log p / \log \log p \leq \frac{1}{4} \log n / \log \log n$.
 - Since we can do this for every positive integer p , there are infinitely many n that require more than $\frac{1}{4} \log n / \log \log n$ tile types (a stronger result holds: "most" values of n require that many)

How many tile systems with k tile types?

- **Goal:** show that there are fewer than p (“functionally distinct”) tile systems with $k = \frac{1}{4} \log p / \log \log p$ tile types.
- How many have exactly k tile types? Count each of the ways to define the tile system:
 - a) How many different glues can we have? $4k$
 - b) How many ways can we choose the 4 glues for one tile type? $a^4 = (4k)^4$
 - c) How many ways to choose the glues for all k tile types? $b^k = (4k)^{4k}$
 - d) How many ways to choose the seed tile? k
- How many tile systems? $c \cdot d = k(4k)^{4k}$

How many tile systems with k tile types?

- Number of tile systems with exactly k tile types: $\leq k(4k)^{4k}$
- Number of tile systems with at most k tile types: $\leq k^2(4k)^{4k}$
- Recall $k = \frac{1}{4} \log p / \log \log p$; by algebra (see notes), $k^2(4k)^{4k} < p$.
- By pigeonhole principle, for some width n with $p < n \leq 2p$, the $n \times n$ square is not self-assembled by one of these $k^2(4k)^{4k}$ tile systems. Since those are **all the tile systems with at most k tile types**, the $n \times n$ square requires **more** than $\frac{1}{4} \log p / \log \log p$ tile types to self-assemble. **QED**

“Descriptive Complexity” proof

- Can be formalized with *Kolmogorov complexity*
 - https://en.wikipedia.org/wiki/Kolmogorov_complexity
- We can “describe” n with a tile system that self-assembles an $n \times n$ square.
- How many bits do we need to describe a tile system with k tile types?
 - $\log(4k)$ to describe one of the $4k$ glues, e.g., 8 glues: 000, 001, 010, 011, 100, 101, 110, 111
 - $4 \log(4k)$ to describe one tile type consisting of 4 glues, e.g., tile $b = (010, 011, 111, 100)$
 - $4k \log(4k)$ to describe all k tile types, plus $\log k$ to give index of the seed.
 - So $O(k \log k)$ bits total.
- For any n in the Fact, $\log n = O(k \log k)$, i.e., $k = \Omega(\log n / \log \log n)$.

Fact: “most” integers n require $\geq \log n$ bits to “describe”.

(Though some require fewer:
111111111111111111111111
can be described by its length
22 in binary: 10110)

Note: we’re ignoring glue strengths here; adds 2 bits per glue to describe at temperature 2. (since there are 3 possible strengths 0, 1, 2); see <http://doi.org/10.1007/s00453-014-9879-3> for handling higher-temperature systems.

Which bound is tight?

1. All $n \times n$ squares can be assembled with $O(\log n)$ tile types; can we get it down to $O(\log n / \log \log n)$?
2. Or do we need $\Omega(\log n)$ tile types to assemble infinitely many $n \times n$ squares?

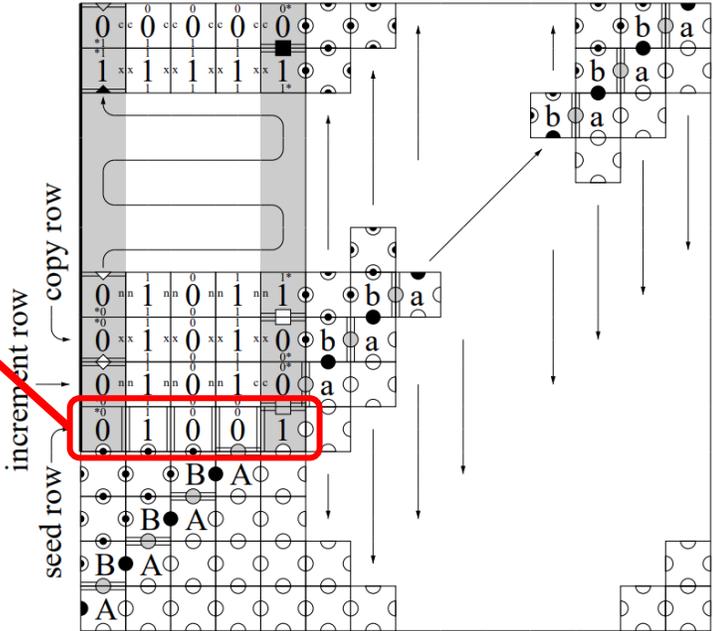
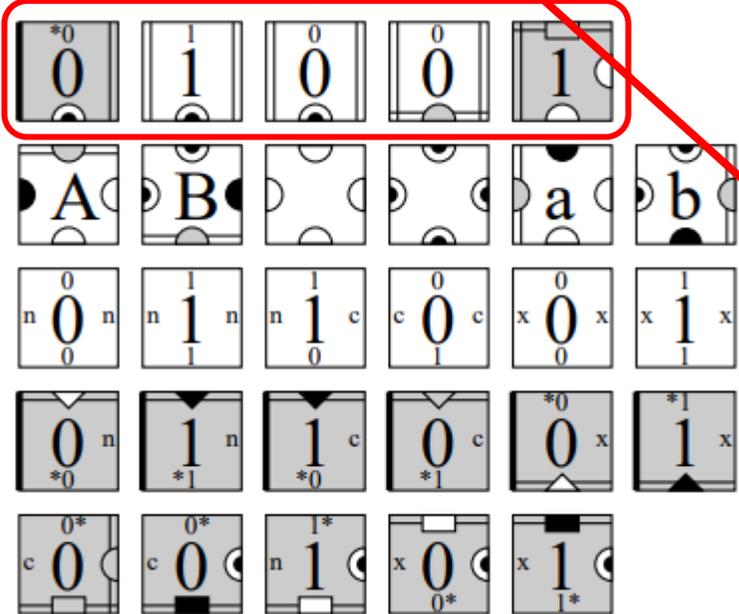
Improved upper bound: self-assembling an $n \times n$ square with $O(\log n / \log \log n)$ tile types

Recall:

Idea:

- 1) Use same 23 tiles that turn the seed row encoding a binary integer n' (related to n) into an $n \times n$ square.
- 2) Create the binary seed row from only $\log n / \log \log n$ tiles.

tile complexity = $O(\log n) + 23$



Creating a row of $\log n$ glues with arbitrary bit string $s \in \{0,1\}^{\log n}$ using $O(\log n / \log \log n)$ tile types

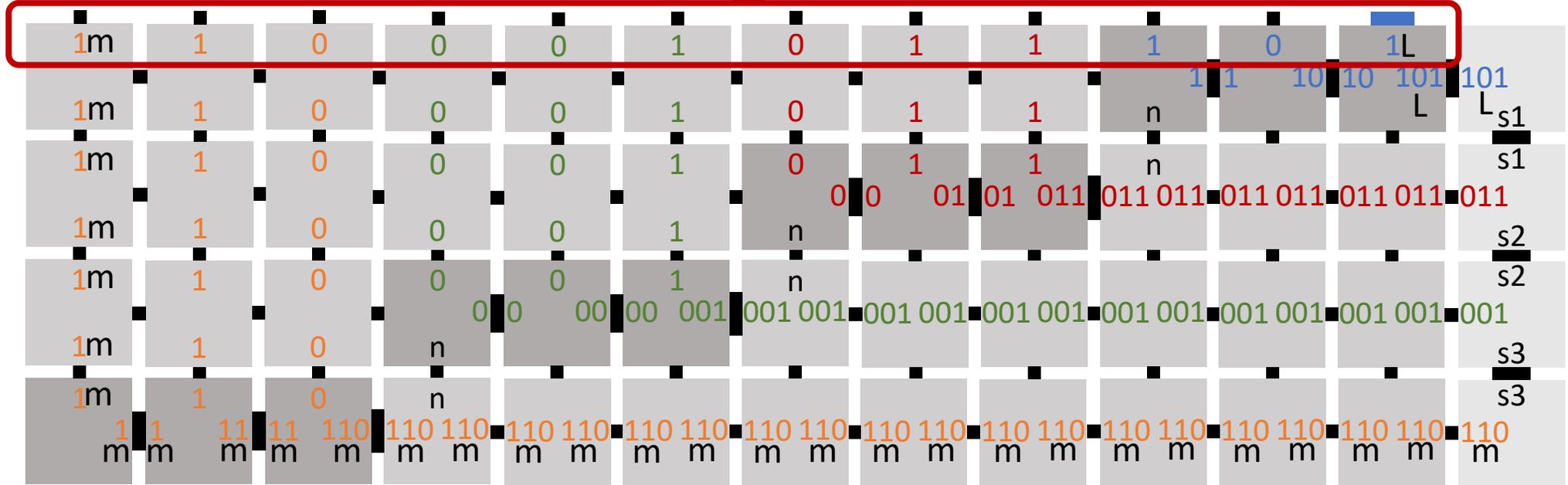
- Key idea: choose larger power-of-two base $b = 2^k$, with $b \approx \log n / \log \log n$, and convert from base b to base 2.
- How many base- b digits needed to represent a $\log(n)$ -bit integer?
- Each base- b digit is k bits
 - e.g., if $b=2^3=8$, then $0=000$ $1=001$ $2=010$ $3=011$ $4=100$ $5=101$ $6=110$ $7=111$
 - e.g., the octal number 7125_8 in binary is 111001010101_2
 - need $\log(n) / k = \log(n) / \log(\log n / \log \log n) = \log(n) / (\log \log n - \log \log \log n) \approx \log(n) / \log \log n$ base- b digits.

Creating a row of $\log n$ glues with arbitrary bit string $s \in \{0,1\}^*$ using $\log n / \log \log n$ tile types (i.e., base conversion from b to 2)

$s = 110\ 001\ 011\ 101$

$b = 2^3 = 8$

hard-coded tiles:



“almost” works... what’s missing?

mark glues of most and least significant bit

Formal definition of aTAM

abstract Tile Assembly Model (aTAM), formal definition

- Fix a finite alphabet Σ . A **glue** is a pair $g = (\ell, s) \in \Sigma^* \times \mathbb{N}$, with **label** ℓ and **strength** s .
- A **tile type** is a 4-tuple of glues $t \in (\Sigma^* \times \mathbb{N})^4$, with each glue listed in order north, east, south, west.
 - Define unit vectors $N = (0,1)$, $S = (0,-1)$, $E = (1,0)$, $W = (-1,0)$
 - For $d \in \{N, E, S, W\}$, let d^* denote the **opposite direction** of d , i.e., $N^* = S$, $S^* = N$, $E^* = W$, $W^* = E$.
 - Let $t[N]$, $t[E]$, $t[S]$, $t[W]$ be the glues of t in order.
 - T denotes the set of tile types.
- An **assembly** is a partial function $\alpha: \mathbb{Z}^2 \dashrightarrow T$, such that $\text{dom } \alpha$ (set of points where α is defined) is connected.
 - a partial function indicating, for each $(x,y) \in \mathbb{Z}^2$, which tile is at (x,y) , with $\alpha(x,y)$ undefined if no tile appears there.
- Let $S_\alpha = \text{dom } \alpha$ denote the **shape** of α . Let $|\alpha| = |S_\alpha|$.
- Given $p, q \in S_\alpha$, two tiles $t_p = \alpha(p)$ and $t_q = \alpha(q)$ **interact** (a.k.a. **bind**) if:
 - $\|p - q\|_2 = 1$ (*positions $p \in \mathbb{Z}^2$ and $q \in \mathbb{Z}^2$ are adjacent*)
 - letting $d = q - p$ (*the direction pointing from p to q*), $t_p[d] = t_q[d^*]$ (*the glues match where t_p and t_q touch*)
 - $t_p[d]$ has positive strength (*the glues are not zero-strength*)
- Let $B_\alpha = (V, E)$ denote the **binding graph** of α , where
 - $V = S_\alpha$
 - $E = \{ (p, q) \mid \alpha(p) \text{ and } \alpha(q) \text{ interact} \}$
 - B_α is a *weighted, undirected* graph: Each edge's weight is the strength of the glue it represents.
- Given $\tau \in \mathbb{N}^+$, α is **τ -stable** if the minimum weight cut of B_α is at least τ .
 - i.e., to separate α into two pieces requires breaking bonds of strength at least τ .

abstract Tile Assembly Model (aTAM), formal definition

- Given assemblies $\alpha, \beta: \mathbb{Z}^2 \rightarrow T$, we say α is a **subassembly** of β , written $\alpha \sqsubseteq \beta$ if
 - $S_\alpha \subseteq S_\beta$ (α is contained in β), and
 - for all $p \in S_\alpha$, $\alpha(p) = \beta(p)$ (α and β agree on tile types wherever they share a position)
- We say $\Theta = (T, \sigma, \tau)$ is a **tile system**, where T is a finite set of tile types, $\tau \in \mathbb{N}^+$ is the **temperature**, and $\sigma: \mathbb{Z}^2 \rightarrow T$ is the finite, τ -stable **seed assembly**.
- We say **α produces β in one step**, denoted $\alpha \rightarrow_1 \beta$, to denote that $\alpha \sqsubseteq \beta$, $|S_\beta \setminus S_\alpha| = 1$, and letting $\{p\} = S_\beta \setminus S_\alpha$ be the point in β but not α , the cut $(\{p\}, S_\alpha)$ of the binding graph B_β has weight $\geq \tau$.
 - (one new tile $\beta(p)$ attaches to α with strength at least τ to create β)
 - If the tile type added is t , write $\beta = \alpha + (p \mapsto t)$.
- The **frontier** of α is denoted $\partial\alpha = \bigcup_{\alpha \rightarrow_1 \beta} (S_\beta \setminus S_\alpha)$ (empty locations adjacent to α where a tile can stably attach to α .)
- A sequence of $k \in \mathbb{N} \cup \{\infty\}$ assemblies $\alpha_0, \alpha_1, \dots$ is an **assembly sequence** if for all $0 \leq i < k$, $\alpha_i \rightarrow_1 \alpha_{i+1}$.
- We say that **α produces β** (in 0 or more steps), denoted $\alpha \rightarrow \beta$, if there is an assembly sequence $\alpha_0, \alpha_1, \dots$ of length $k \in \mathbb{N} \cup \{\infty\}$ such that
 - $\alpha = \alpha_0$
 - for all $0 \leq i < k$, $\alpha_i \sqsubseteq \beta$, and
 - $S_\beta = \bigcup_i S_{\alpha_i}$
- We say β is the **result** of the assembly sequence.
- If k is finite, it is routine to verify that $\beta = \alpha_k$, and \rightarrow is the reflexive, transitive closure \rightarrow_1^* of \rightarrow_1 .

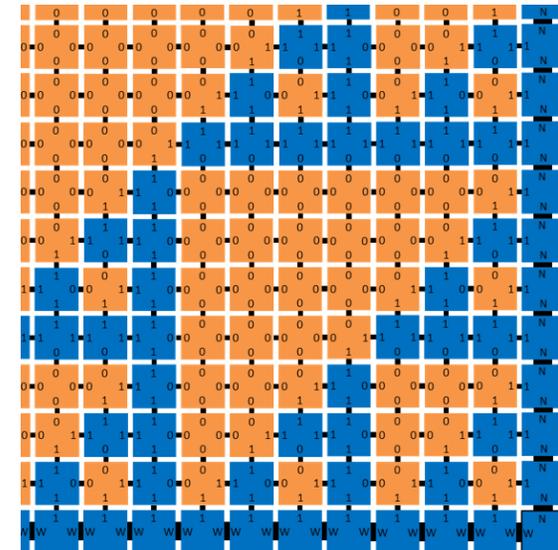
Question: If $\alpha \sqsubseteq \beta$, can α grow into β ?

Why can't we just say \rightarrow is the reflexive, transitive closure \rightarrow_1^* of \rightarrow_1 ?

Sometimes we write $\alpha \xrightarrow{\Theta} \beta$ to emphasize this is with respect to a particular tile system Θ .

abstract Tile Assembly Model (aTAM), formal definition

- Given tile system $\Theta = (T, \sigma, \tau)$, we say α is **producible** if $\sigma \rightarrow \alpha$.
 - Write $A[\Theta]$ to denote the set of all producible assemblies.
- We say α is **terminal** if α is stable and $\partial\alpha = \emptyset$. (*no tile can stably attach to it*)
 - Write $A_{\square}[\Theta] \subseteq A[\Theta]$ to denote the set of all producible, terminal assemblies.
- We say Θ is **directed** (a.k.a., **deterministic**) if
 - $|A_{\square}[\Theta]| = 1$. (*this is what we want it to mean: only one terminal producible assembly*)
 - equivalently, the partially ordered set $(A[\Theta], \rightarrow)$ is *directed*: for each $\alpha, \beta \in A[\Theta]$, there exists $\gamma \in A[\Theta]$ such that $\alpha \rightarrow \gamma$ and $\beta \rightarrow \gamma$.
 - equivalently, for all $\alpha, \beta \in A[\Theta]$ and all $p \in S_{\alpha} \cap S_{\beta}$, $\alpha(p) = \beta(p)$.
- Let X be a **shape**, a connected subset of \mathbb{Z}^2 . Θ **strictly self-assembles** X if, for all $\alpha \in A_{\square}[\Theta]$, $S_{\alpha} = X$. (*every terminal producible assembly has shape X*)
 - Note X can be infinite.
 - Example: strict self-assembly of entire second quadrant $X = \{ (x,y) \in \mathbb{Z}^2 \mid x \geq 0 \text{ and } y \leq 0 \}$
 - Example of tile system Θ that does not strictly self-assemble any shape?
- Let $X \subseteq \mathbb{Z}^2$. Θ **weakly self-assembles** X if there is a subset $B \subseteq T$ (the “blue tiles”) such that, for all $\alpha \in A_{\square}[\Theta]$, $X = \alpha^{-1}(B)$. (*every terminal producible assembly puts blue tiles exactly on X.*)
 - example: weak self-assembly of the discrete Sierpinski triangle.



Basic stability result

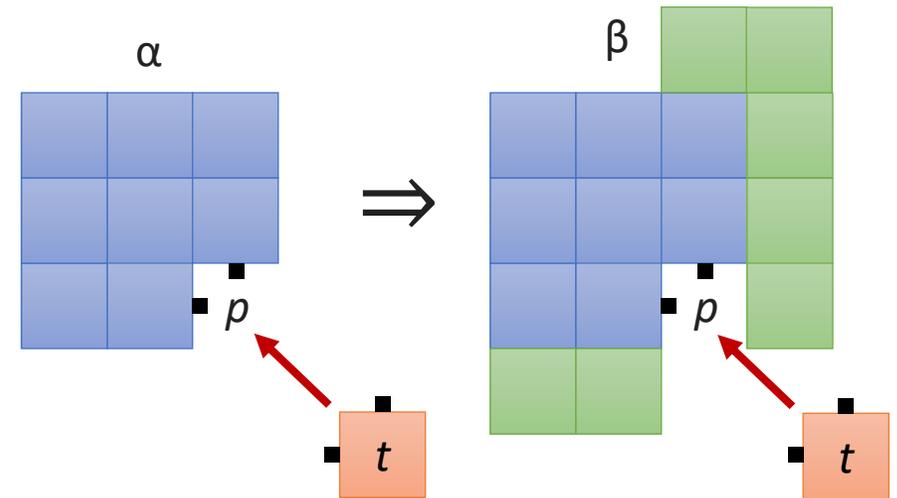
Observation: Let $\alpha \sqsubseteq \beta$ be stable assemblies and $p \in \mathbb{Z}^2 \setminus S_\beta$ such that $\alpha + (p \mapsto t)$ is stable. Then $\beta + (p \mapsto t)$ is also stable.

Proof:

1. Since β is stable and glue strengths are nonnegative, the only *potentially* unstable cut is $(\{p\}, S_\beta)$.
2. But:
 1. $\alpha \sqsubseteq \beta$,
 2. $\alpha + (p \mapsto t)$ is stable,
 3. compared to α , β only has extra tiles on the other side of the cut (t, S_β) .
 4. so the cut (t, S_β) is also stable. **QED**

Intuition: if a tile can attach to α , it can attach in the presence of extra tiles on α .

example:



Basic reachability result

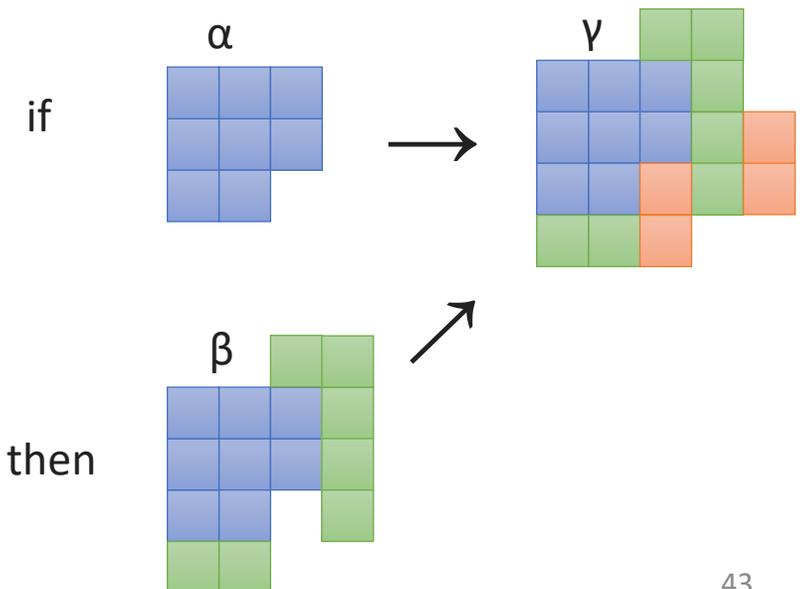
Rothmund's Lemma: Let $\alpha \sqsubseteq \beta \sqsubseteq \gamma$ be stable assemblies such that $\alpha \rightarrow \gamma$. Then $\beta \rightarrow \gamma$.

Proof:

1. Let $\alpha = \alpha_0, \alpha_1, \dots$ be an assembly sequence with result γ .
2. For each i , let $p_i = S_{\alpha_{i+1}} \setminus S_{\alpha_i}$ (i 'th attachment position) and t_i the i 'th tile added.
3. Let $i(0) < i(1) < \dots$ such that $S_\gamma \setminus S_\beta = \{i(0), i(1), \dots\}$ (subsequence of indices of tile attached outside of β).
4. Define assembly sequence $\beta = \beta_0, \beta_1, \dots$ by $\beta_{j+1} = \beta_j + (p_{i(j)} \mapsto t_{i(j)})$. (adding tiles to $S_\gamma \setminus S_\beta$ in order they were added to α , skipping tiles already in S_β .)
5. Then for each j , $\alpha_{i(j)} \sqsubseteq \beta_j$, so previous Observation implies that $\beta_j + (p_{i(j)} \mapsto t_{i(j)})$ is stable.
6. Thus the assembly sequence is valid (each tile attachment is stable), showing $\beta \rightarrow \gamma$. **QED**

Intuition: if α can grow into γ , then if some of what will attach is already present (β), the remaining tiles can still attach.

example:



example of usefulness of Rothemund's Lemma

- Recall two alternate characterizations of deterministic tile systems:
 - (a) $|A_{\square}[\Theta]| = 1$.
 - (b) for all $\alpha, \beta \in A[\Theta]$ and all $p \in S_{\alpha} \cap S_{\beta}$, $\alpha(p) = \beta(p)$.
- Rothemund's Lemma can be used to show that (b) implies (a)
 - will skip in lecture (optional problem on homework 1)

Fair assembly sequences

Definition: Let $\alpha_0, \alpha_1, \dots$ be an assembly sequence. We say it is **fair** if, for all $i \in \mathbb{N}$ and all $p \in \partial\alpha_i$, there exists $j > i$ such that $p \in S_{\alpha_j}$.

Lemma: Let $\alpha_0, \alpha_1, \dots$ be a fair assembly sequence. Then its result γ is terminal.

Proof:

1. Suppose for the sake of contradiction that γ is not terminal, i.e., it has frontier location $p \in \partial\gamma$; note in particular $p \notin S_\gamma$.
2. Simpler if assembly sequence is finite:
 1. in this case, $\gamma = \alpha_{k-1}$, so p never receives a tile.
 2. Thus the assembly sequence is not fair. (*there is no $j > k-1$ such that $p \in S_{\alpha_j}$*)
3. Now assume assembly sequence is infinite. (*actually, rest of proof works in finite case*)
4. Since $p \in \partial\gamma$, there are positions adjacent to p with enough strength to bind a tile t . Let N be the set of these positions. Note N is finite since p has at most four neighbors.
5. Since $S_\gamma = \bigcup_i S_{\alpha_i}$, there exists i such that $N \subseteq \partial\alpha_i$ (*after some finite number of tile attachments, all of the positions in N are on the frontier of the current assembly*)
6. Thus $p \in \partial\alpha_i$. (*the tile t can attach to α_i , reached after only i steps*)
7. By fairness, there exists j such that $p \in S_{\alpha_j} \subseteq S_\gamma$ (*eventually p gets a tile*), which contradicts the claim that $p \notin S_\gamma$. **QED**

Intuition: Every frontier location eventually gets a tile; none are “starved”

Corollary: For every assembly α , there is a terminal assembly γ such that $\alpha \rightarrow \gamma$.

Proof: Pick any fair assembly sequence $\alpha = \alpha_0, \alpha_1, \dots$; its result γ is terminal and $\alpha \rightarrow \gamma$. **QED**

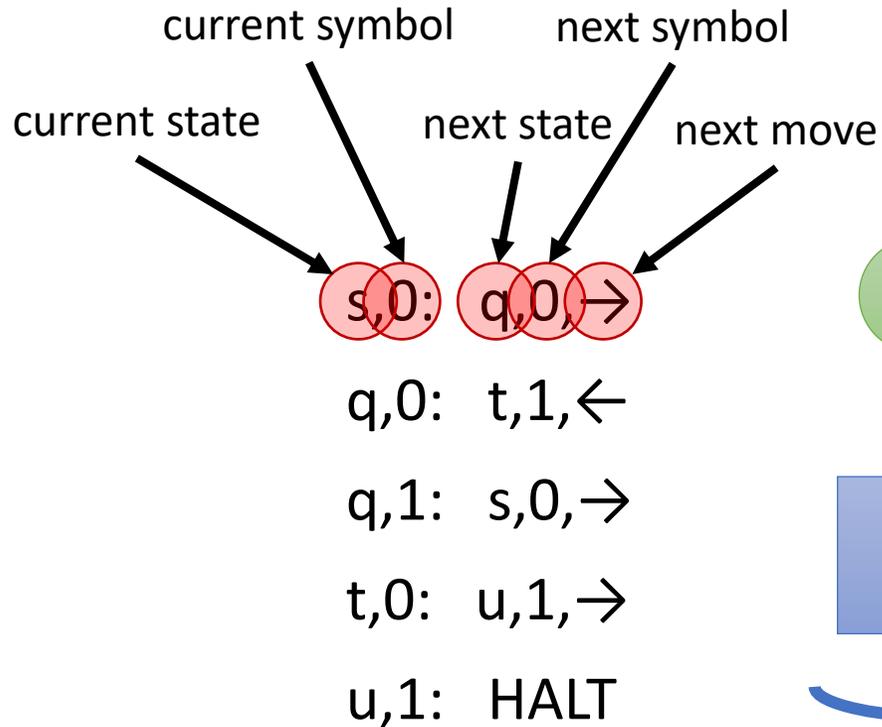
Concrete example of simulation algorithm creating a fair assembly sequence?

How computationally powerful
are self-assembling tiles?

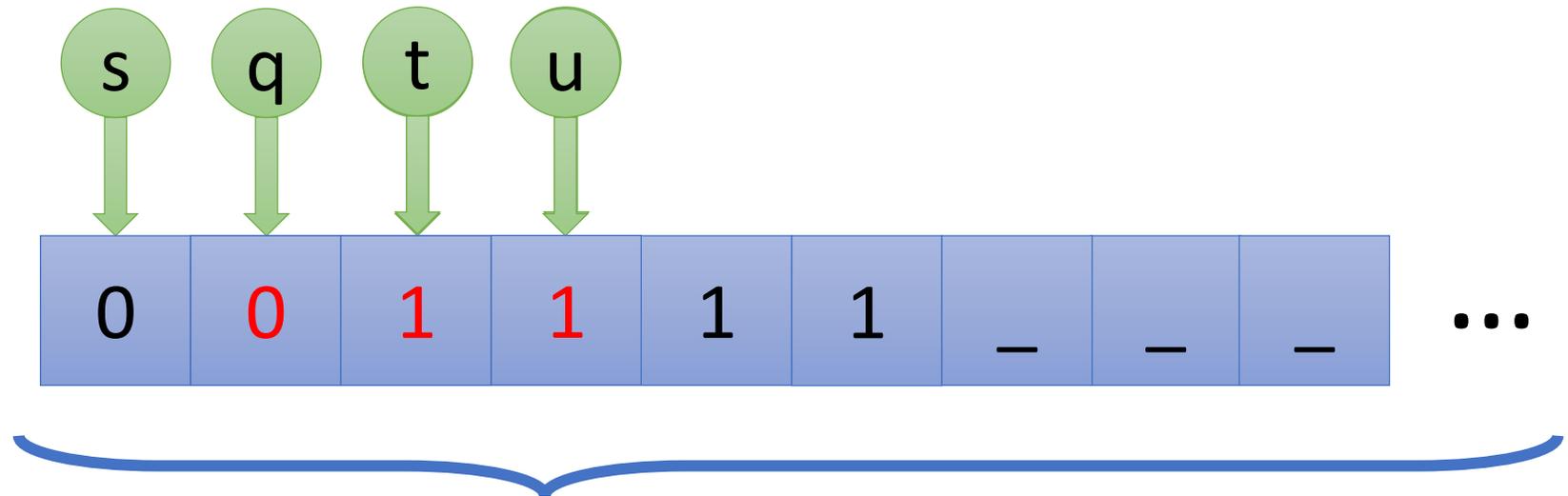
Turing machines

state \approx line of code

initial state = s

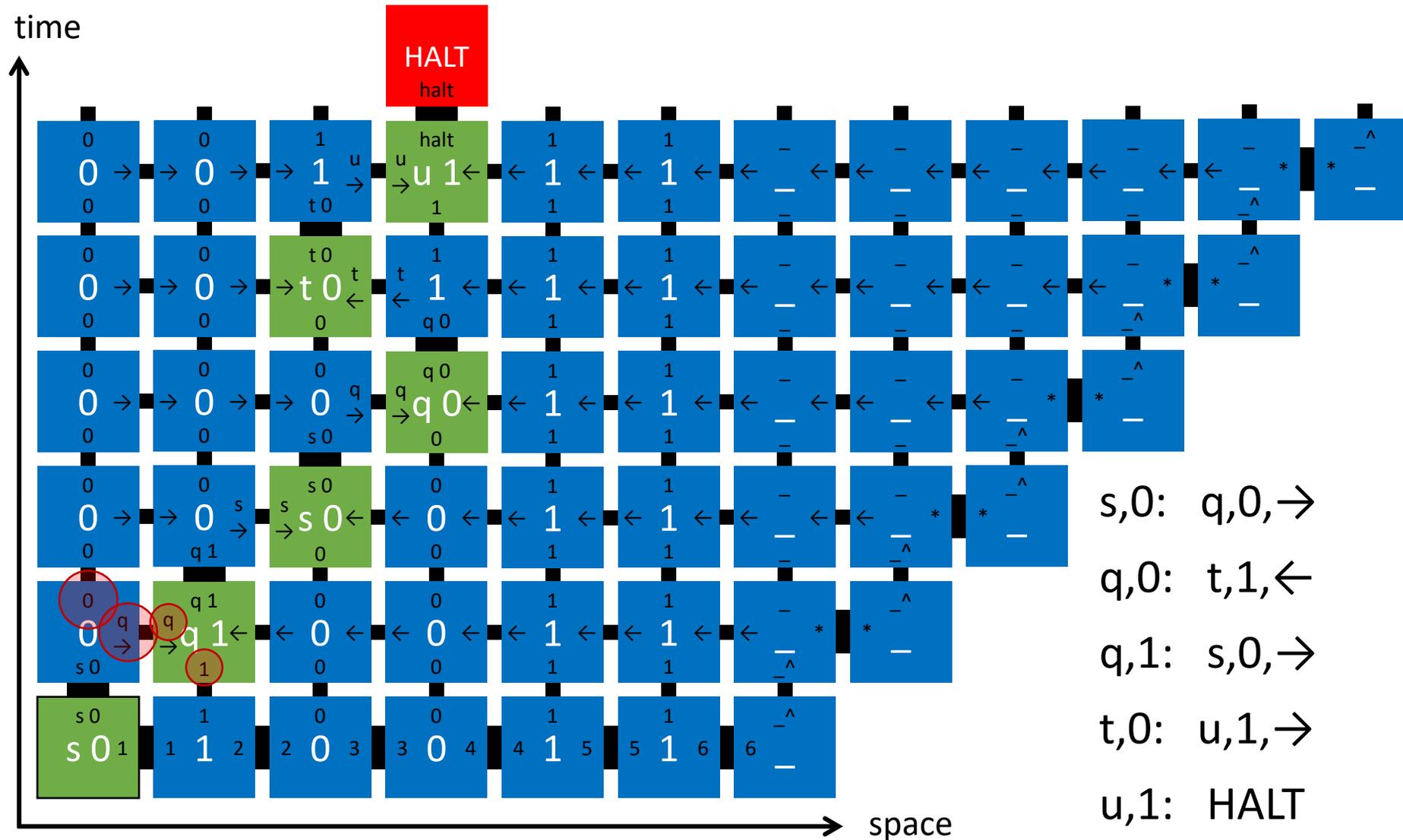


transitions
(instructions)



tape \approx memory

Tile assembly is Turing-universal



Complexity of self-assembled shapes

- We've seen how use algorithmic tiles to:
 - self-assemble $n \times n$ squares with "few" tile types $O(\log n / \log \log n)$
 - simulate a Turing machine that grows a "wedge" describing its space-time configuration history

- What other shapes can be self-assembled?
 - Define a **shape** to be a finite, connected subset of \mathbb{N}^2 .
 - Any shape with n points can be self-assembled with at most how many tile types? n

0,2	1,2	2,2
0,1	1,1	2,1
0,0	1,0	2,0

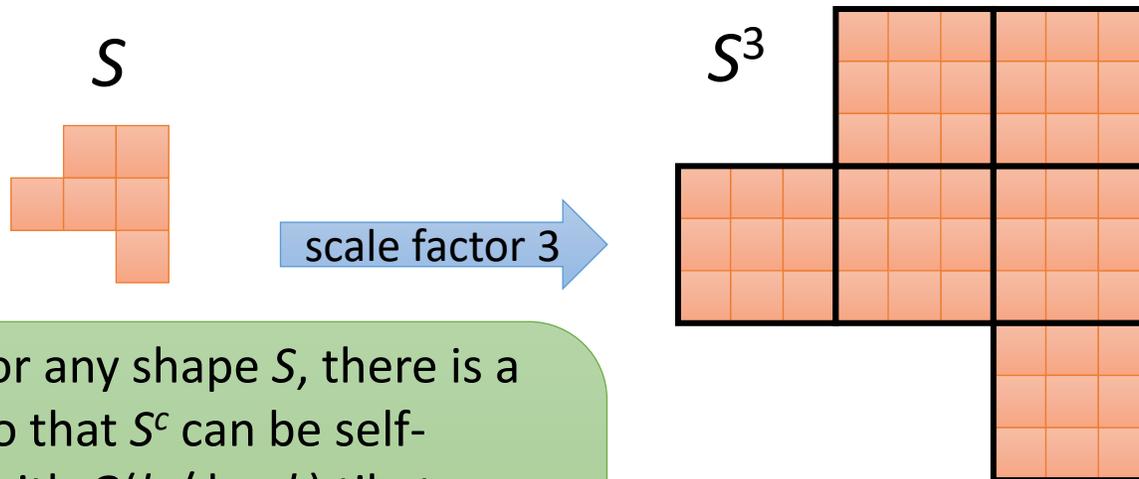
		2,3
	1,2	2,2
0,1	1,1	2,1
		2,0

- Is there an infinite family of shapes S_1, S_2, \dots , with $|S_n| = n$, such that each S_n requires at least n tile types to self-assemble?



Complexity of self-assembled shapes

Suppose we are content to create a scaled up version of the shape:



Theorem: For any shape S , there is a constant c so that S^c can be self-assembled with $O(k / \log k)$ tile types, where k is the length in bits of the shortest program (input to a universal Turing machine) that, on input (x,y) , indicates whether $(x,y) \in S$.

Theorem (that we won't prove): This is optimal! No smaller tile system could self-assemble any scaling of S . If one existed, we could turn it into a program with $< k$ bits "describing" S in this way. (*Why?*)

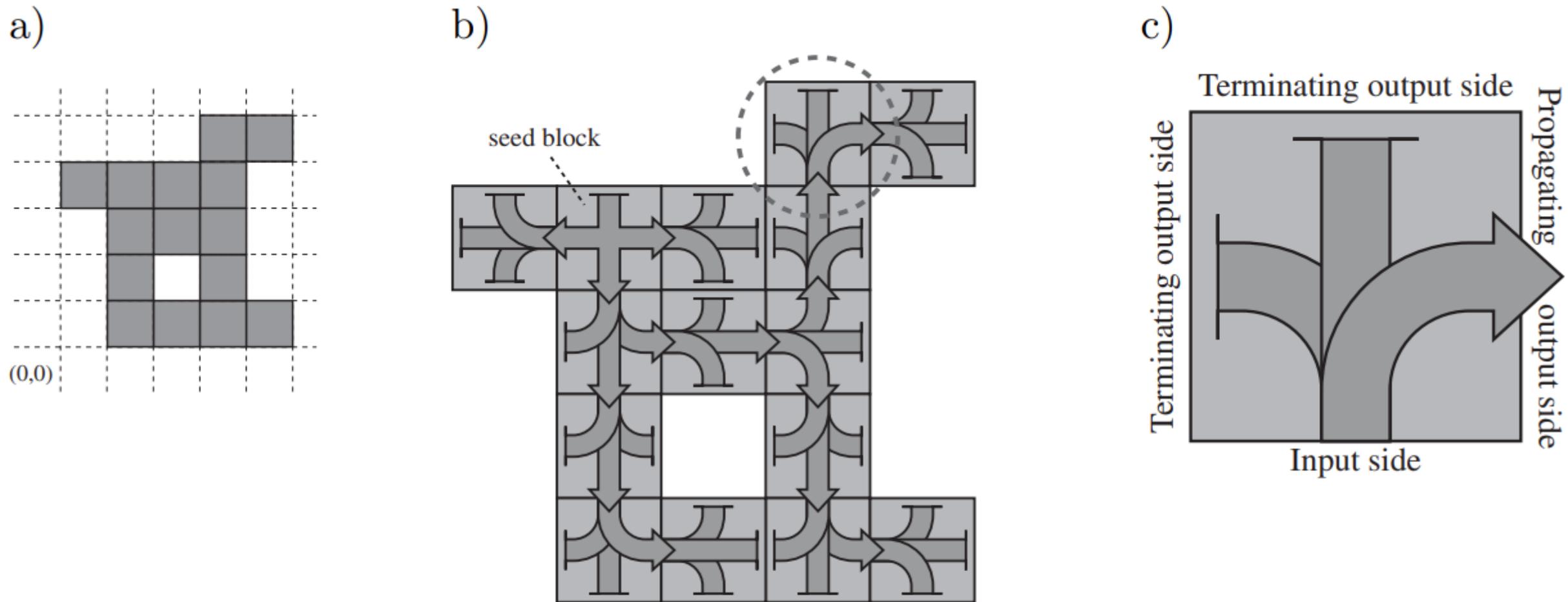
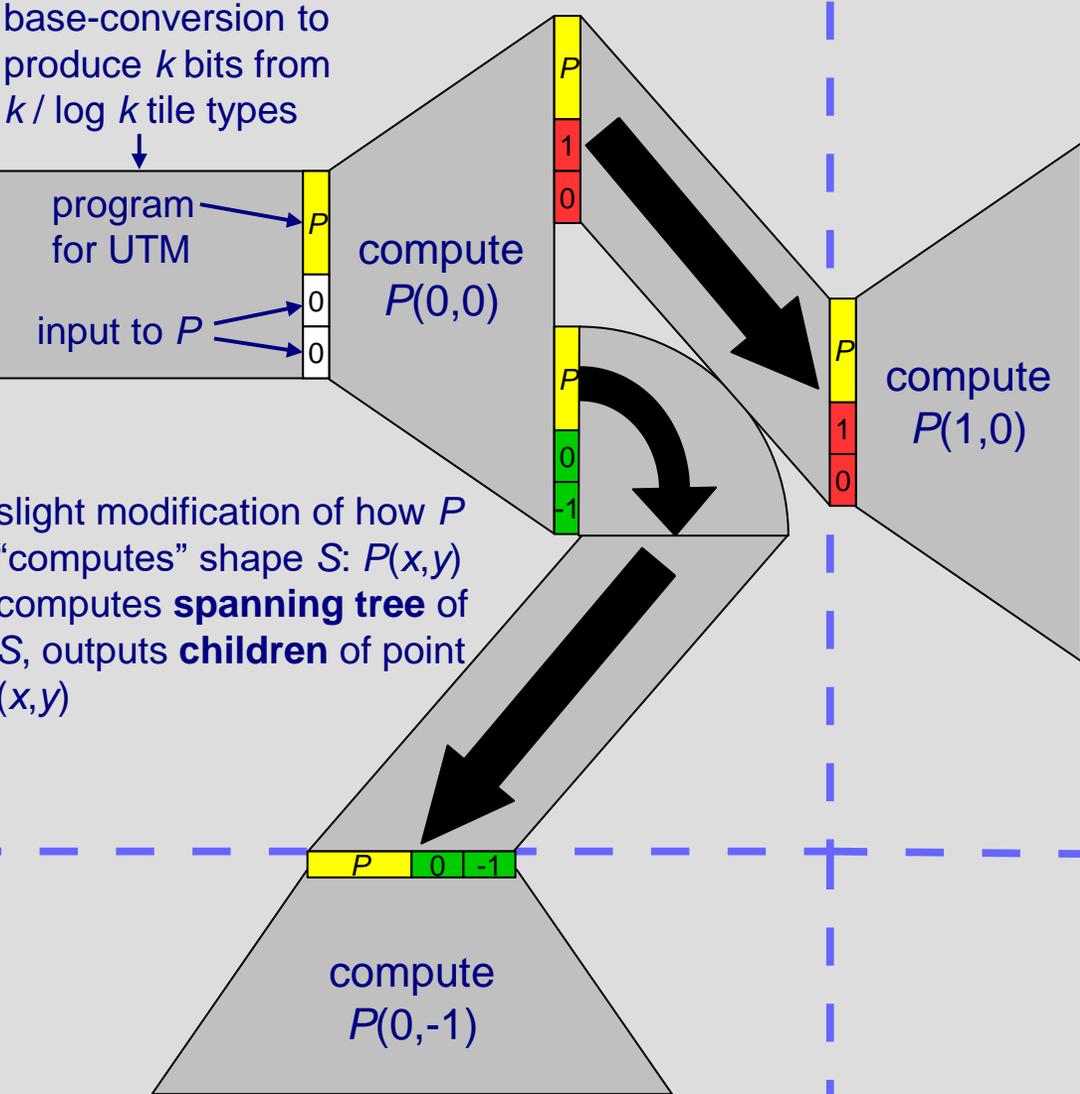
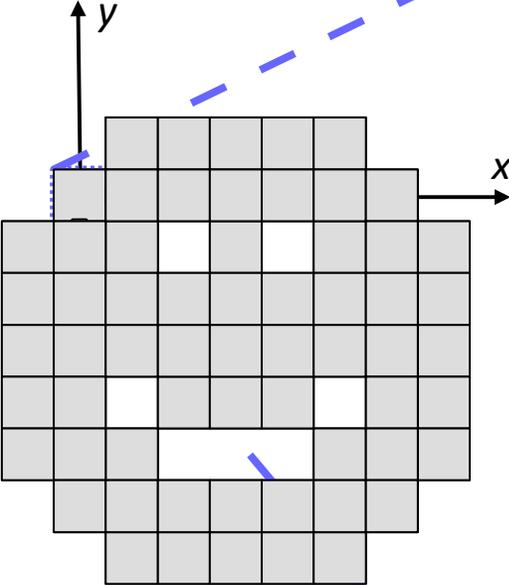


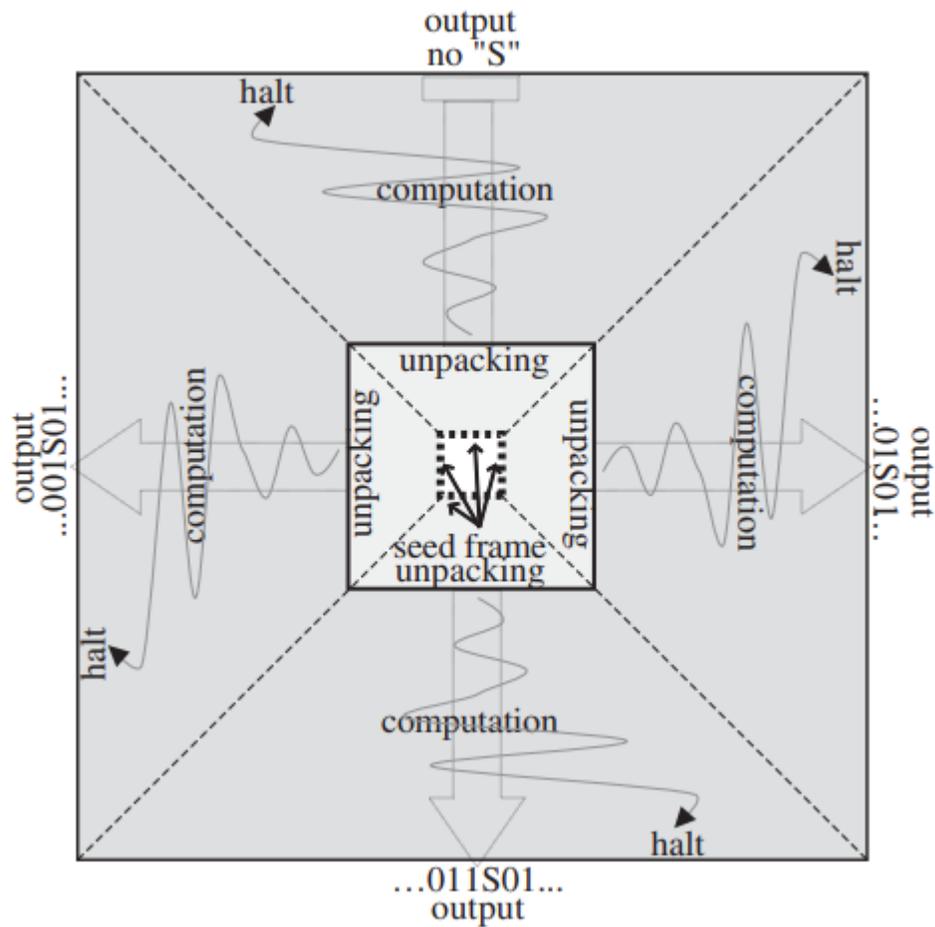
FIG. 5.1. *Forming a shape out of blocks: (a) A coordinated shape S . (b) An assembly composed of $c \times c$ blocks that grow according to transmitted instructions such that the shape of the final assembly is \tilde{S} (not drawn to scale). Arrows indicate information flow and order of assembly. The seed block and the circled growth block are schematically expanded in Figure 5.2. (c) The nomenclature describing the types of block sides.*

Programming a shape (inaccurate cartoonish overview)

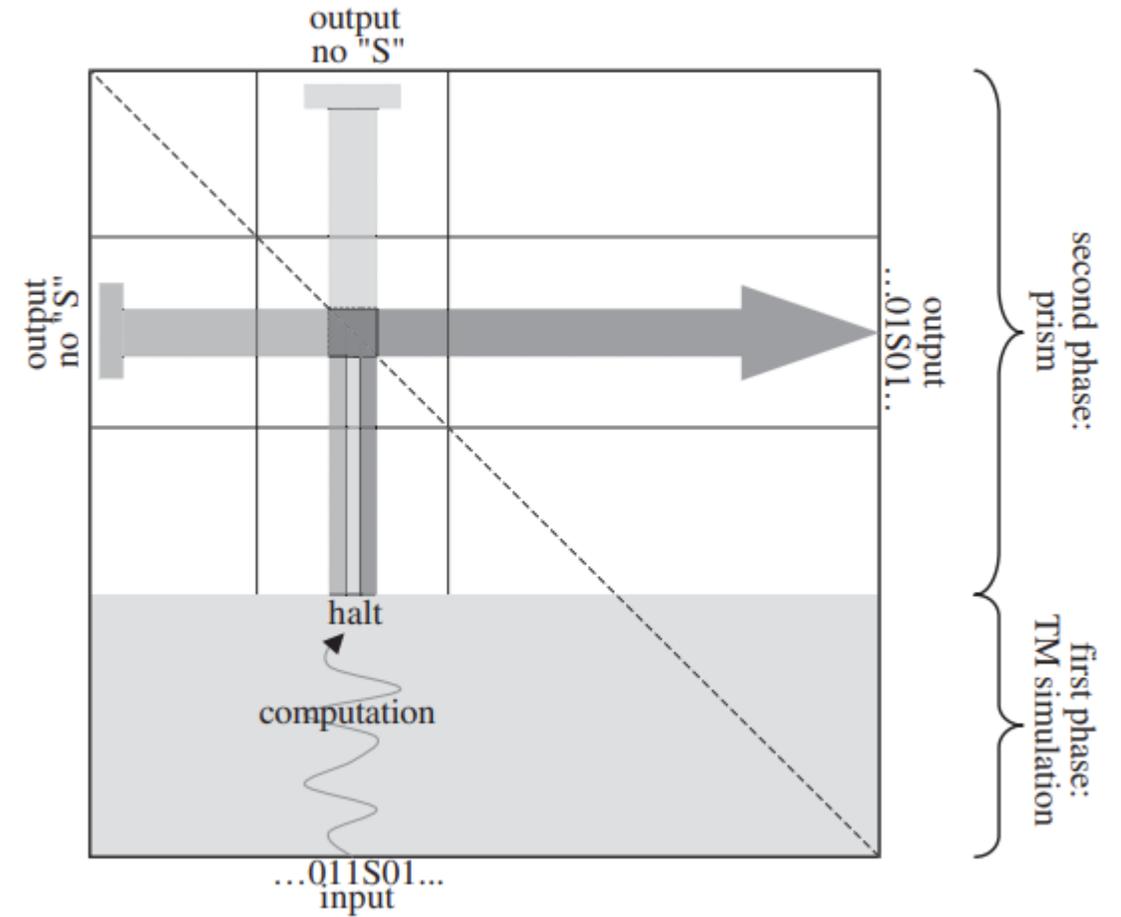


More accurate detailed overview

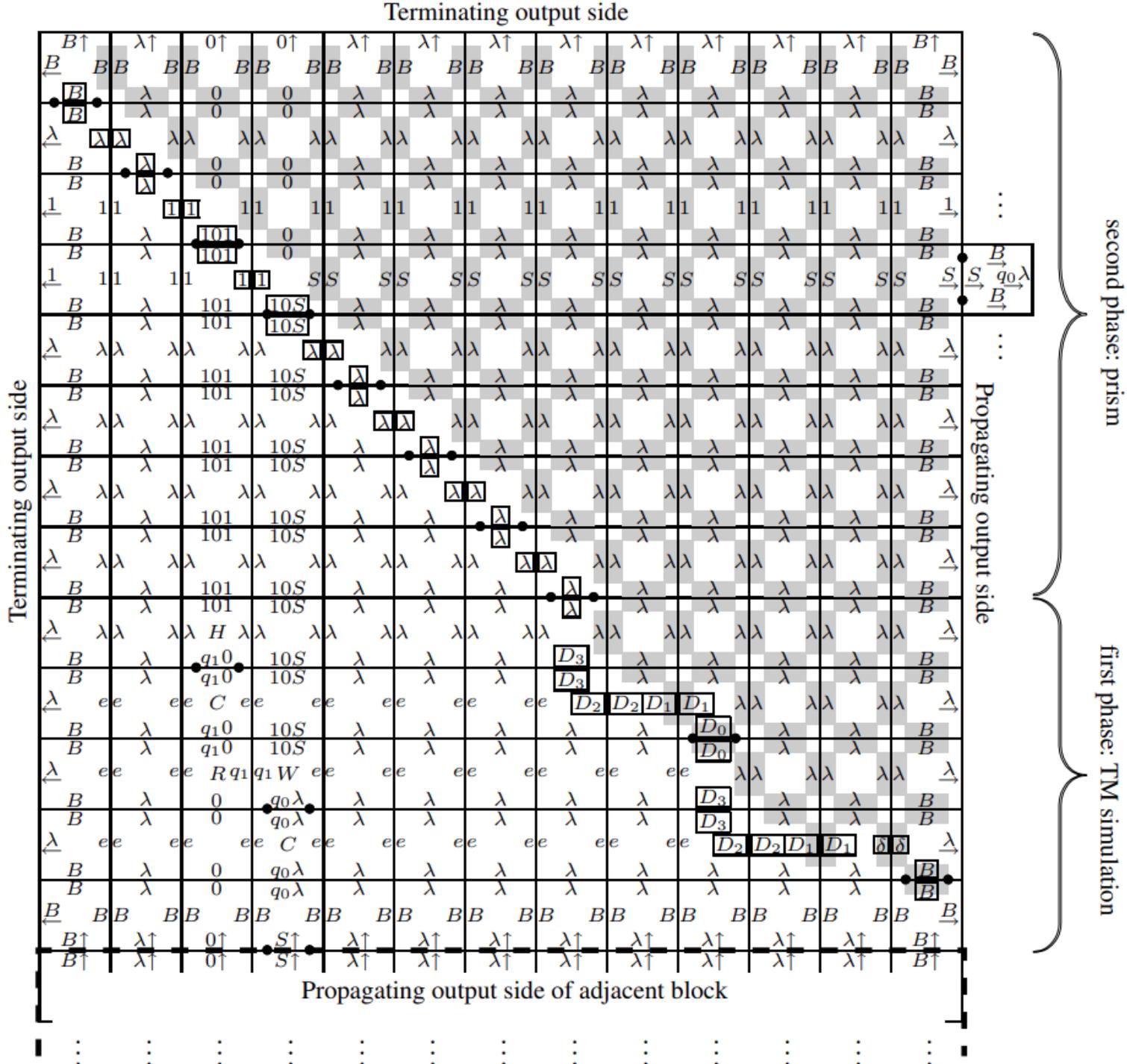
seed block



growth block



fully-detailed
example of
growth block



Two interpretations

as stated for single seed tile:

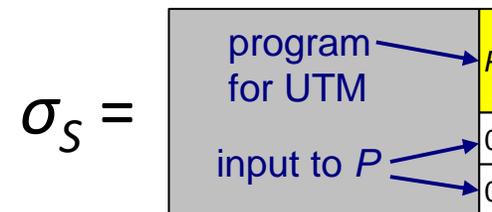
Theorem: For any shape S , there is a constant c so that S^c can be self-assembled with $O(k / \log k)$ tile types, where k is the length in bits of the shortest program (input to a universal Turing machine) that, on input (x,y) , indicates whether $(x,y) \in S$.

most of the tile complexity is encoding the binary string representing the program P that encodes shape S , and $O(1)$ tile types can read that string and self-assemble S^c from it.

i.e., T is a **universal** set of tile types that can self-assemble any shape, by giving it the right seed.

alternative statement for larger seed:

Theorem: There is a single set T of tile types ($O(1)$ tile types), so that, for any finite shape S , there a constant c and a seed assembly σ_S "encoding" S , so that T self-assembles S^c from σ_S .



Strict and weak self-assembly

Computability-theoretic questions about self-assembly

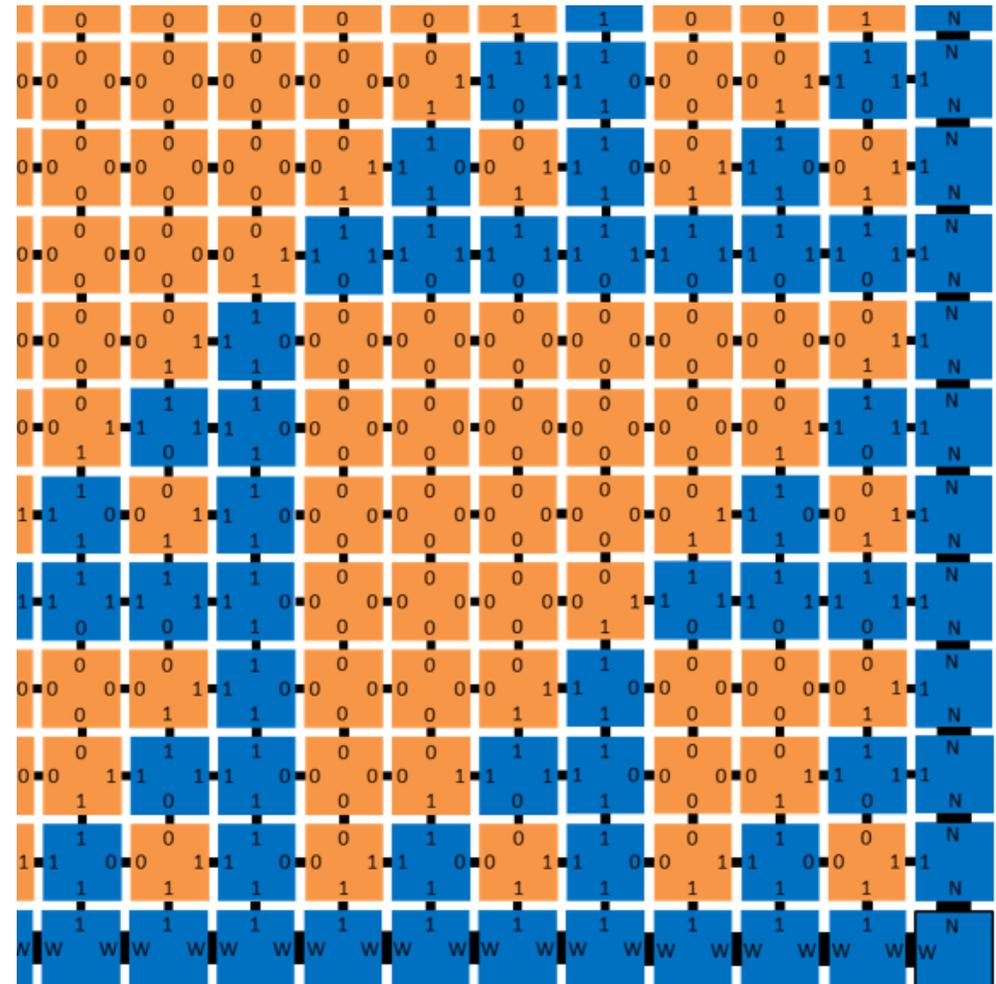
Strict and weak self-assembly

Recall:

Let $X \subseteq \mathbb{Z}^2$ be a **shape**, a connected subset of \mathbb{Z}^2 . Θ **strictly self-assembles** X if, for all $\alpha \in A_{\square}[\Theta]$, $S_{\alpha} = X$.
(every terminal producible assembly has shape X)

Let $X \subseteq \mathbb{Z}^2$. Θ **weakly self-assembles** X if there is a subset $B \subseteq T$ (the “blue tiles”) such that, for all $\alpha \in A_{\square}[\Theta]$, $X = \alpha^{-1}(B)$.
(every terminal producible assembly puts blue tiles exactly on X .)

Tile system on right strictly self-assembles the whole second quadrant, and it weakly self-assembles the discrete Sierpinski triangle.



A famous fractal

- Let $S_0 = \{ (0,0) \}$
- Let $V = \{ (0,0), (0,1), (1,0) \}$ be three vectors for “recursive translation”.
- S is known as the *discrete Sierpinski triangle*...

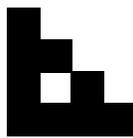
Observation: S is computable (easily).



S_0

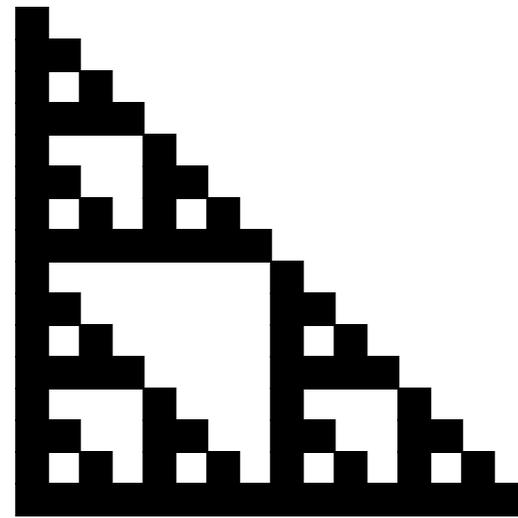


S_1



S_2

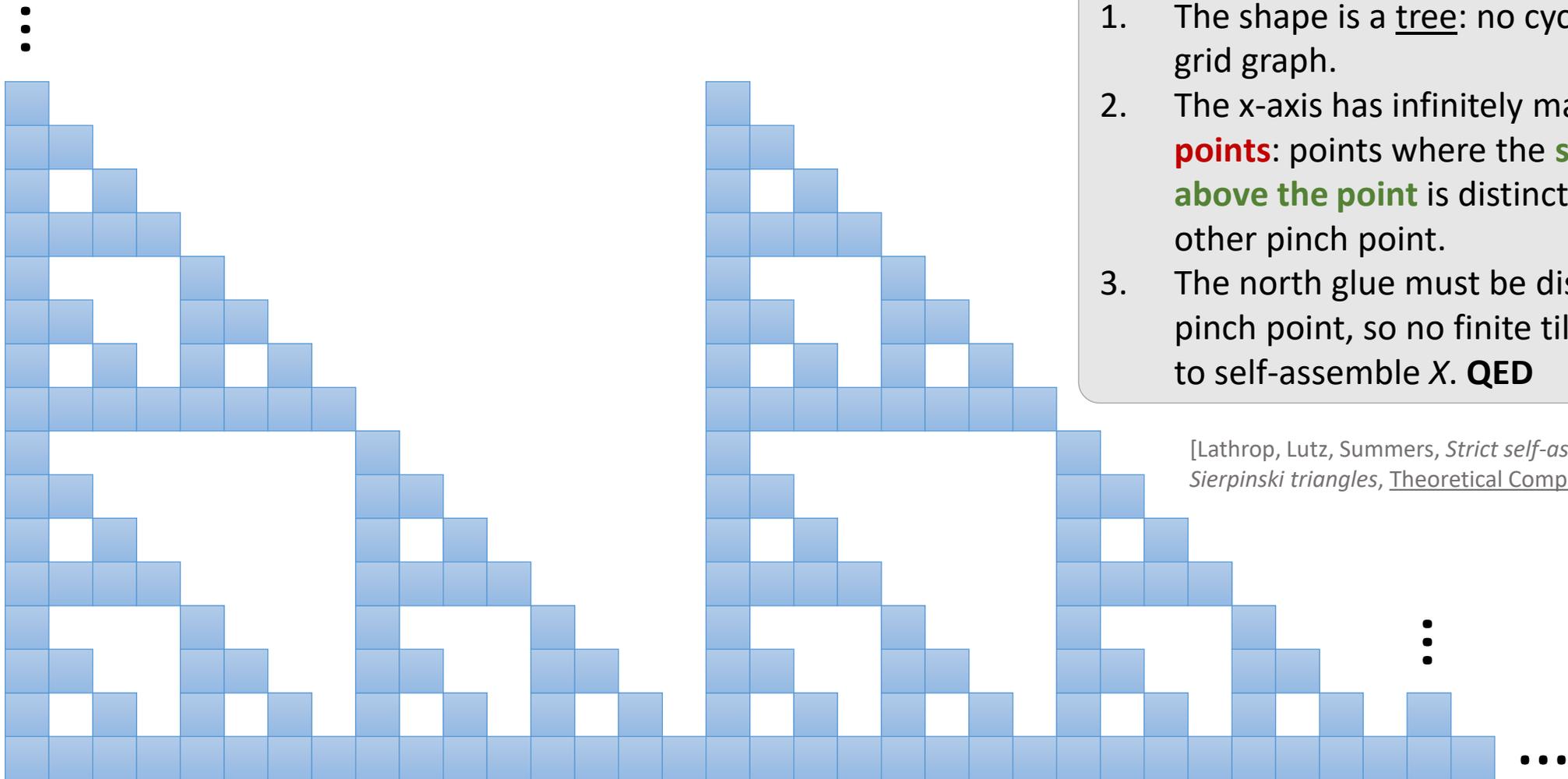
S_3



S_4

...

The discrete Sierpinski triangle cannot be strictly self-assembled



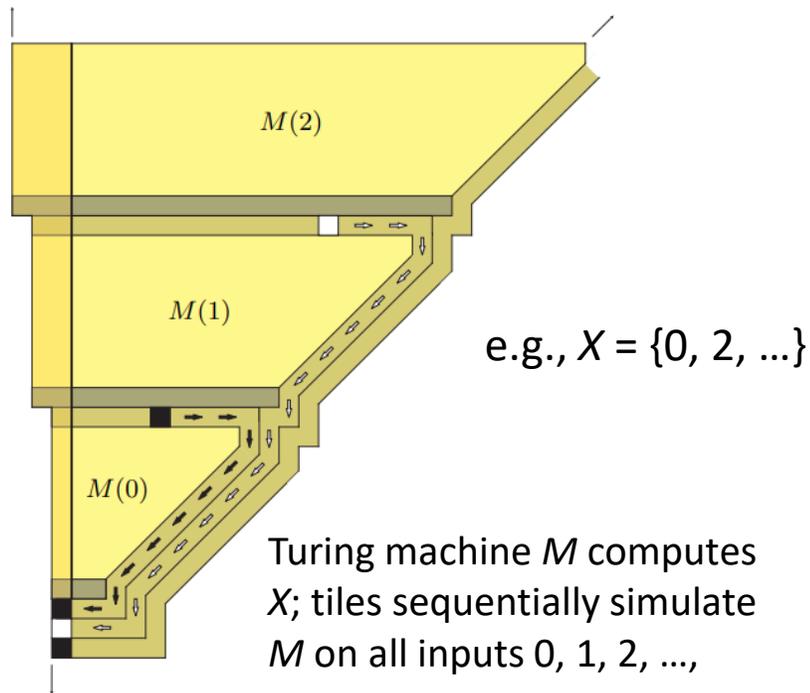
Proof:

1. The shape is a tree: no cycles in the grid graph.
2. The x-axis has infinitely many **pinch points**: points where the **subtree above the point** is distinct from any other pinch point.
3. The north glue must be distinct at each pinch point, so no finite tile set suffices to self-assemble X. **QED**

[Lathrop, Lutz, Summers, *Strict self-assembly of discrete Sierpinski triangles*, [Theoretical Computer Science](#) 2009.]

Weak self-assembly

Theorem: Every computable set $X \subseteq \mathbb{N}$, “embedded straightforwardly” in \mathbb{Z}^2 , can be weakly self-assembled.

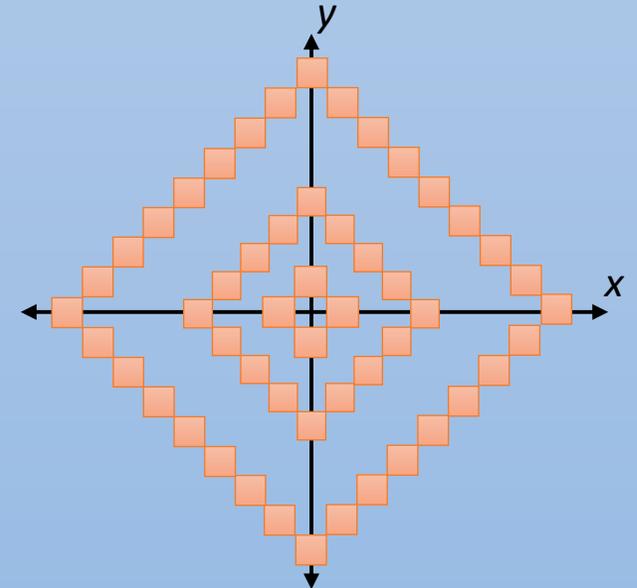


[Patitz, Summers, *Self-assembly of decidable sets*, UCNC 2008.]

Theorem: Some computable sets $X \subseteq \mathbb{Z}^2$ cannot be weakly self-assembled.

Proof:

1. The Time Hierarchy Theorem says there is a computable set $A \subseteq \{1\}^*$ not computable in $O(n^4)$ time.
2. Let $R = \{|x| : x \in A\}$ be the set of lengths of strings in A .
3. Define $X \subseteq \mathbb{Z}^2$ to be the set of “concentric diamonds” whose L_1 radii are in R , e.g., if $R = \{1, 4, 8, \dots\}$



4. Suppose X could be weakly self-assembled. Then simulating self-assembly for $(2n)^2$ steps necessarily places a tile at some point at L_1 radius n from the origin; the tile’s color tells us whether $n \in R \Leftrightarrow 1^n \in A$.
5. This can be done in time $O(n^4)$ time (why?), a contradiction. **QED**

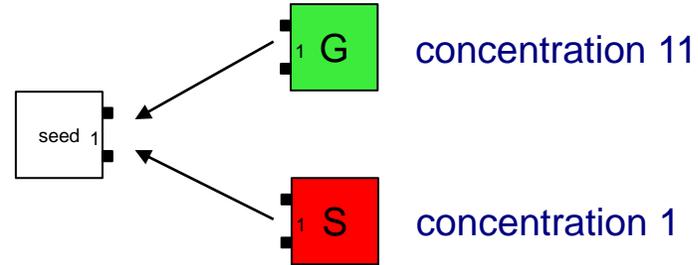
[Lathrop, Lutz, Patitz, Summers, *Computability and Complexity in Self-Assembly*, CiE 2008.]

Randomized self-assembly

Tile complexity of universal shape construction

- Recall: if we can have a seed structure encoding a shape S (in a binary string $x \in \{0,1\}^*$, in glues on one side), we can self-assemble some scaling S^c of S with $O(1)$ additional tile types that read and interpret x .
- $\Theta(K(x) / \log K(x))$ tile types are necessary and sufficient to create x from a single seed tile in the aTAM. ($K(x)$ = length in bits of shortest program for universal Turing machine that prints x)
- We'll see how to get this down to $O(1)$ with high probability by *concentration programming*.
 - i.e., move the effort from designing new tile types to (*the plausibly simpler lab step of*) altering concentrations of existing tile types

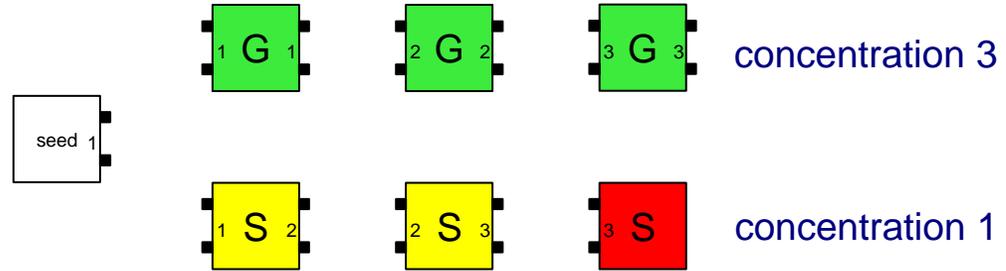
Nondeterministic binding



$$\Pr[\text{seed 1} \text{ } \text{1 G}] = 11/12$$

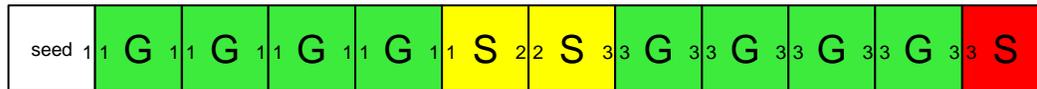
$$\Pr[\text{seed 1} \text{ } \text{1 S}] = 1/12$$

Programming polymer length (improved)



expected length 12

3 "stages", each of expected length 4



Lower variance...
how much lower?

Bounding the probability the length deviates much from its mean

- r total stages, each with $\Pr[\text{next tile } i \text{ increments stage}] = p$.
- Let $\mathbf{L}(r,p)$ = total length; number of tile attachments until attaching r tiles.
- Expected total length $E[\mathbf{L}(r,p)] = r / p$.
- Recall: a binomial random variable $\mathbf{B}(n,p)$ = number of heads when flipping a coin n times, with $\Pr[\text{heads}] = p$. $E[\mathbf{B}(n,p)] = np$.

- for any n,r,p : $\Pr[\mathbf{L}(r,p) \leq n] = \Pr[\mathbf{B}(n,p) \geq r]$

flipping a coin until the r 'th heads requires $\leq n$ flips



flipping a coin n times results in $\geq r$ heads

- similarly, $\Pr[\mathbf{L}(r,p) \geq n] = \Pr[\mathbf{B}(n,p) \leq r]$

Chernoff bound

Chernoff bound: For a binomial random variable $\mathbf{B}(n,p)$ (recall $E[\mathbf{B}(n,p)] = np$), and for any $0 < \delta < 1$,

$$\Pr[\mathbf{B}(n,p) > (1+\delta)np] < \exp(-\delta^2 np/3)$$
$$\Pr[\mathbf{B}(n,p) < (1-\delta)np] < \exp(-\delta^2 np/2)$$

Let $\delta \approx 0.27$ and set p such that $r/p(1-\delta) = 2^k$.
Let $\delta' \approx 0.44$: then $r/p(1+\delta') \approx 2^{k-1}$.
Applying this to our setting gives
 $\Pr[\mathbf{L}(r,p) \text{ is not between } 2^{k-1} \text{ and } 2^k] < 2 \cdot 0.9421^r$

Programming polymer length (improved)

if $r = 90$ stages, expected length midway in $[2^{k-1}, 2^k)$

➔ with probability $> 99\%$, **actual** length in $[2^{k-1}, 2^k)$

$$[G] \approx 7 \quad [S] = [s] \approx 2$$

GGSGGGGSRS

GGGGS SGGGG SGGGS

GGGS SGGGS S

1 2 4 8

16

32

GGGGGGGG SGGGGGG SGGGGGGGGGG S

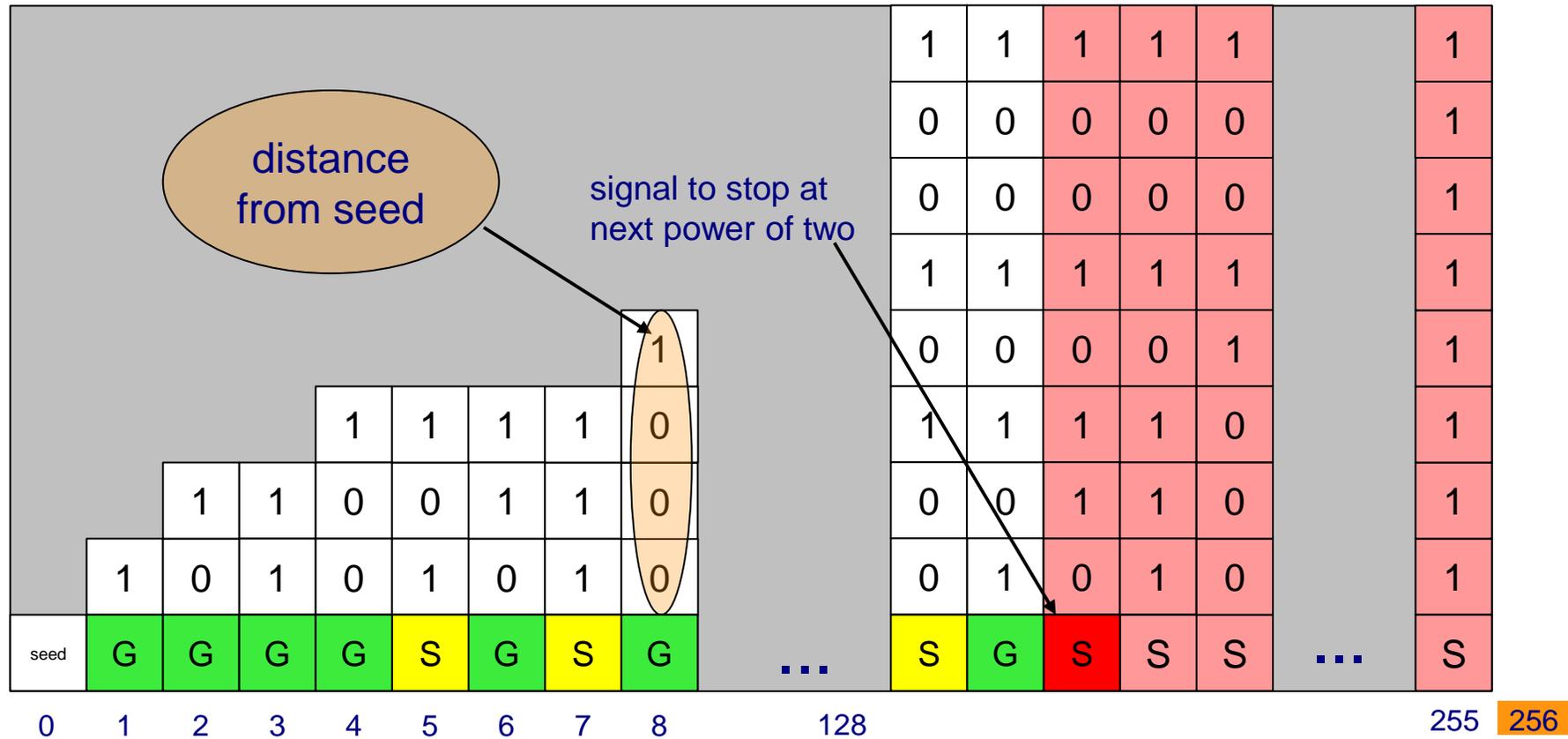
GGGGGG SGGGGGGGGGG SGGGGGG S

GGGGGS SGGGGGGGGGG SGGGG S

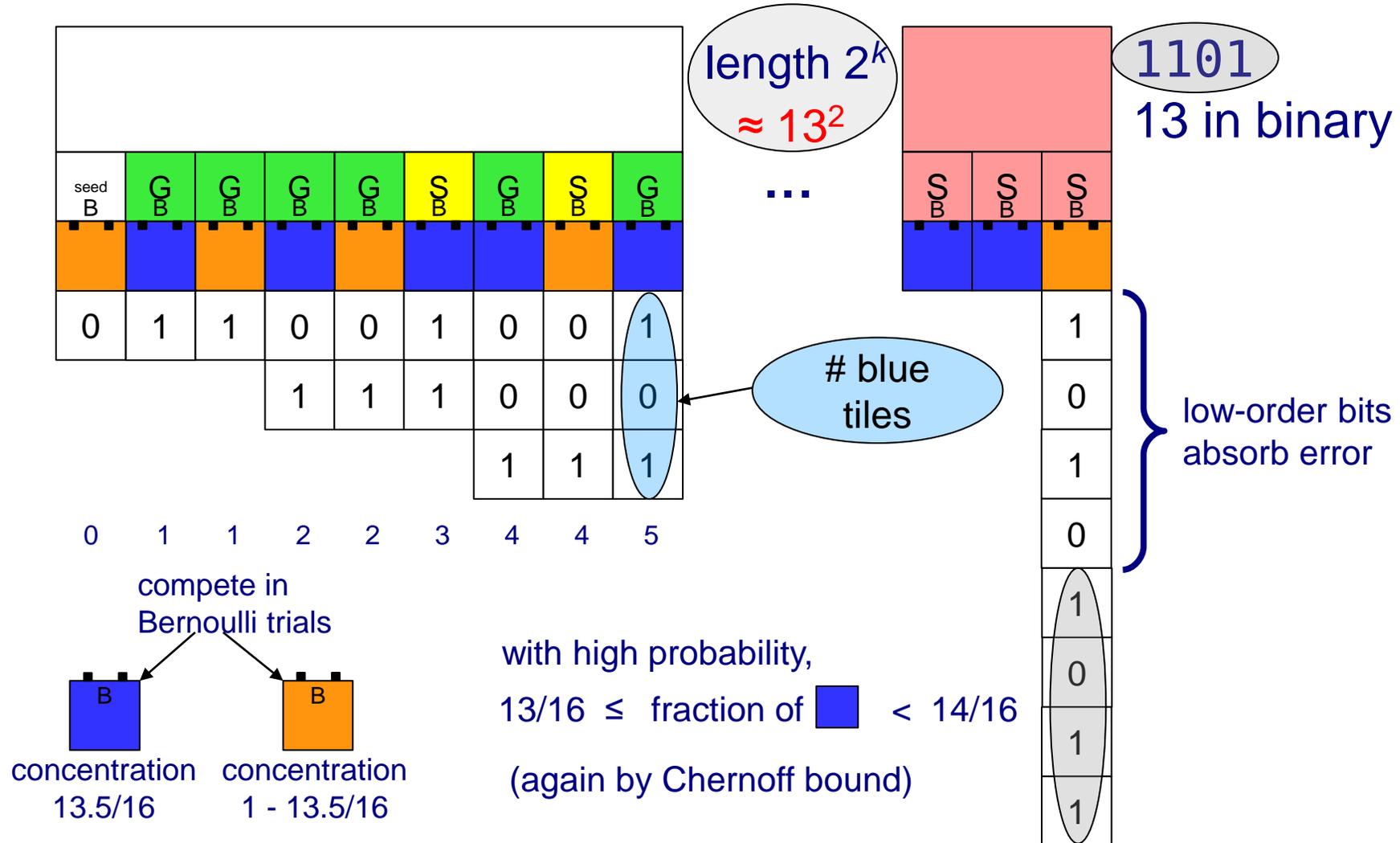
$$[G] \approx 7 \quad [S] = [s] \approx 1$$

i.e., we can't target a precise length L , but we can target precisely the number of bits $\lceil \log L \rceil$ in L 's binary expansion.

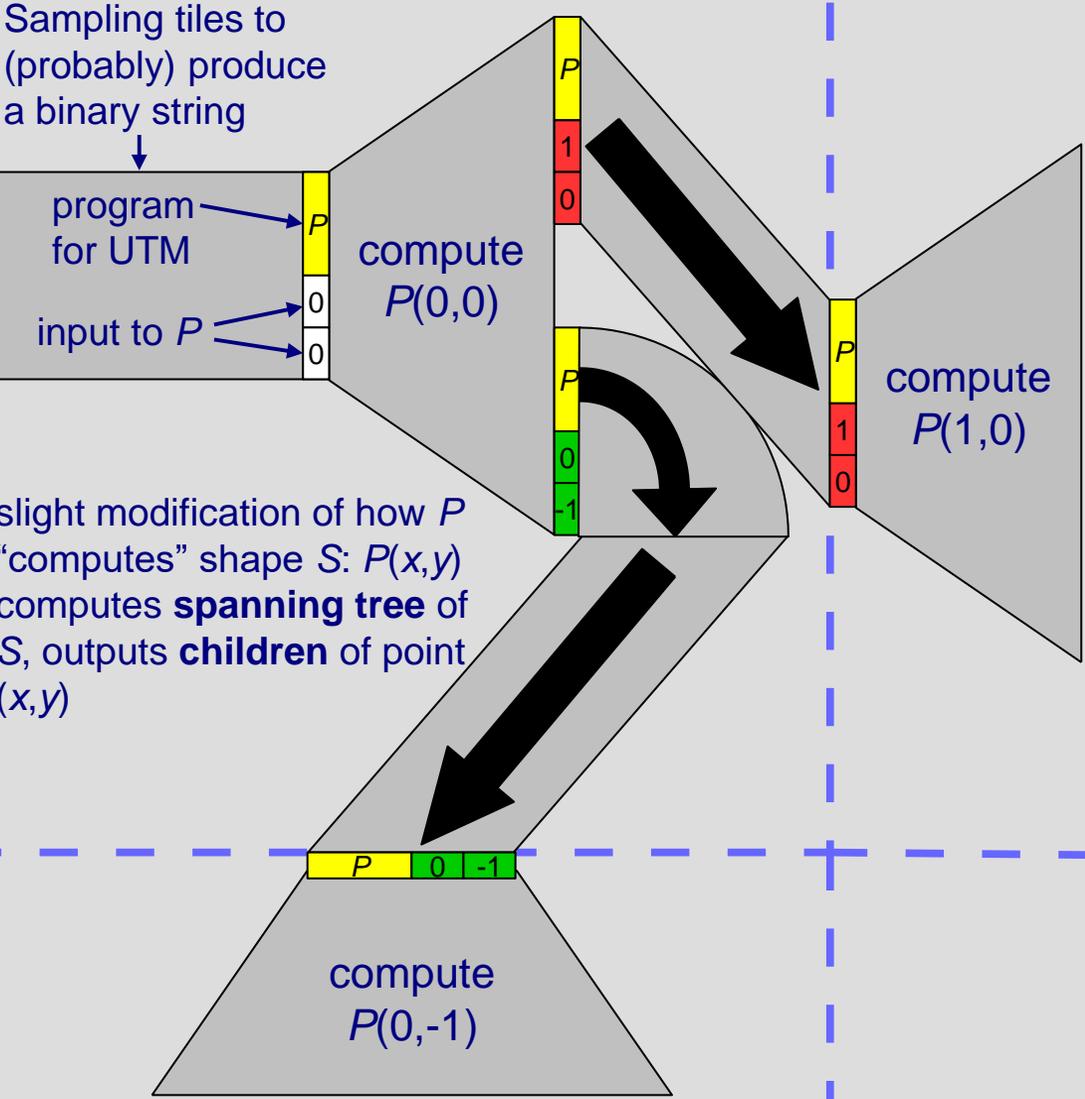
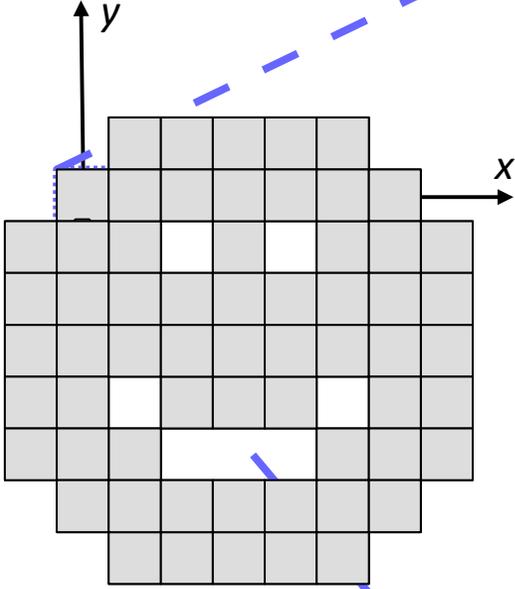
Programming polymer length 2^k precisely



Programming a binary string

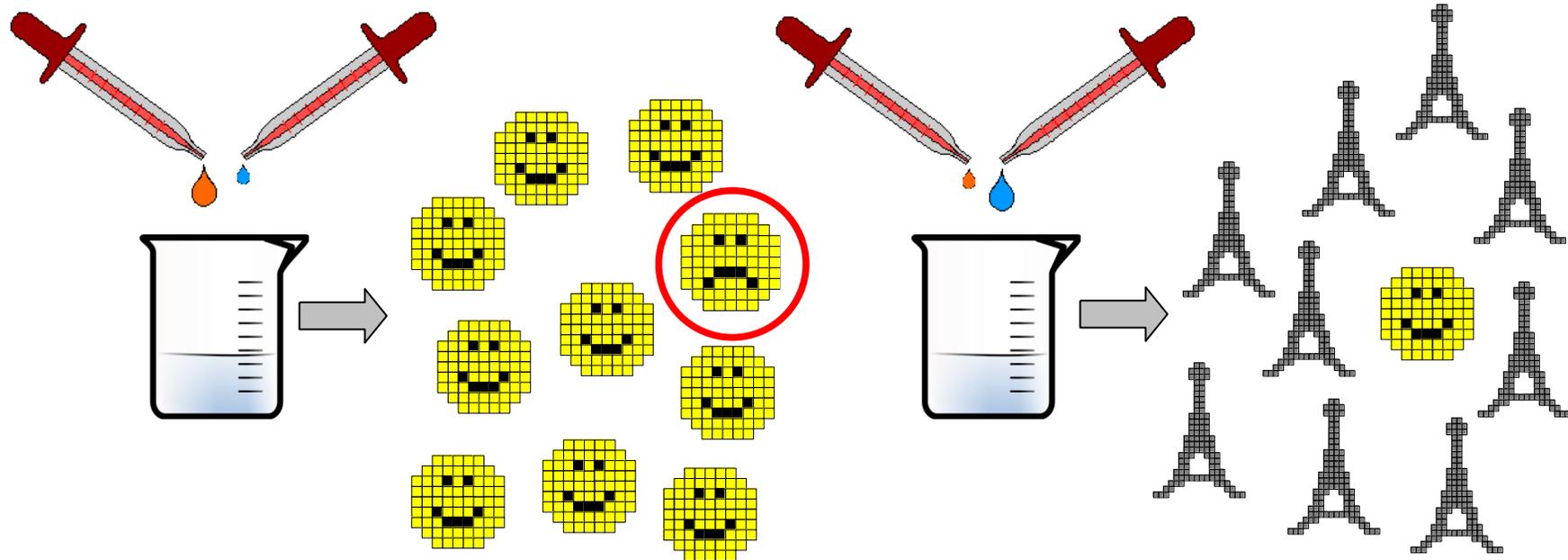


Programming a shape (inaccurate cartoonish overview)



Universal self-assembling molecules

A **fixed** set of tile types can assemble *any* finite (scaled) shape (with high probability) by mixing them in the right concentrations.



[Doty, *Randomized self-assembly for exact shapes*, SICOMP 2010, FOCS 2009]

Other plausible modifications of aTAM model that can reduce tile complexity

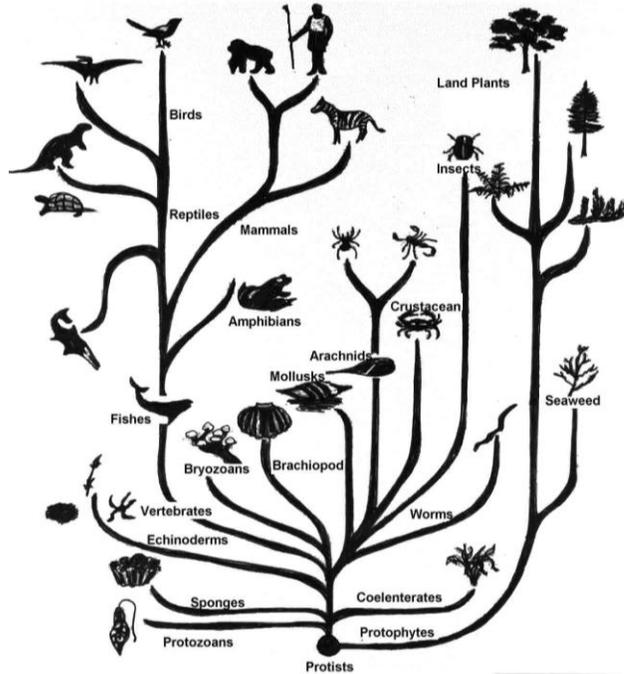
- staged self-assembly:
 - <https://doi.org/10.1007/s11047-008-9073-0>
- temperature programming:
 - <https://dl.acm.org/doi/10.5555/1109557.1109620>

The power of nondeterminism in self-assembly

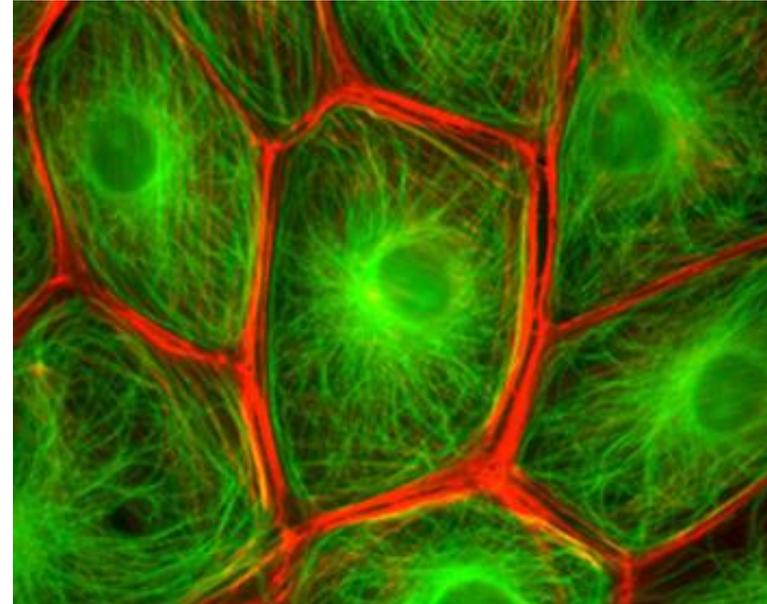
Can nondeterminism help to
self-assemble shapes?

Nondeterminism in Biology

Genetic mutation



Cytoskeleton formation



Nondeterminism can allow complex structures to be created from a compact encoding.

Nondeterminism in Computer Science

Algorithm types:

Nondeterministic:
flips coins; magical

Randomized:
flips coins; realistic

Trivially nondeterministic
(“pseudodeterministic”):
flips coins, but *final output*
independent of flip results

Deterministic: entire
computation uniquely
determined by input

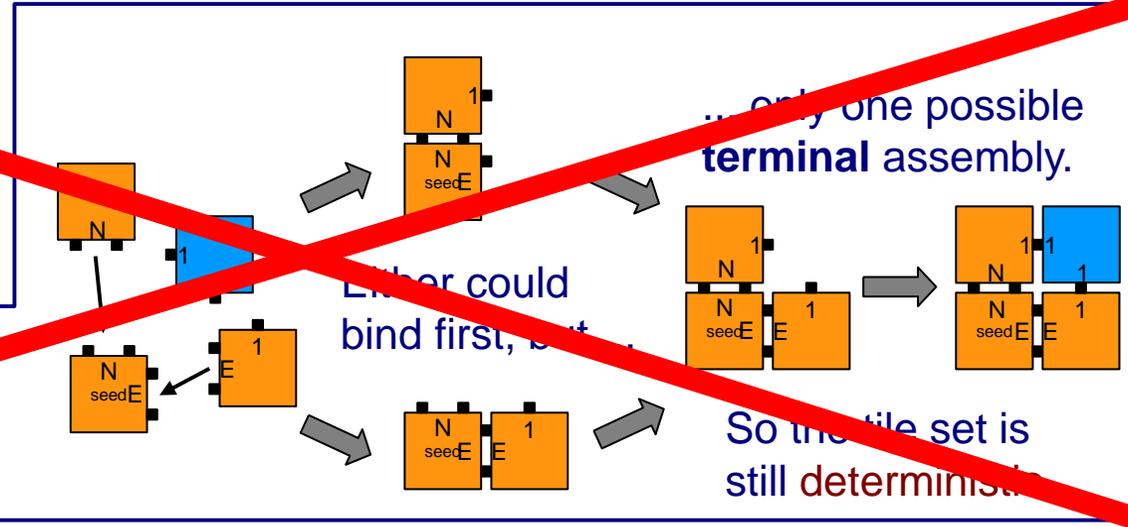
Power



Nondeterminism in Self-Assembly

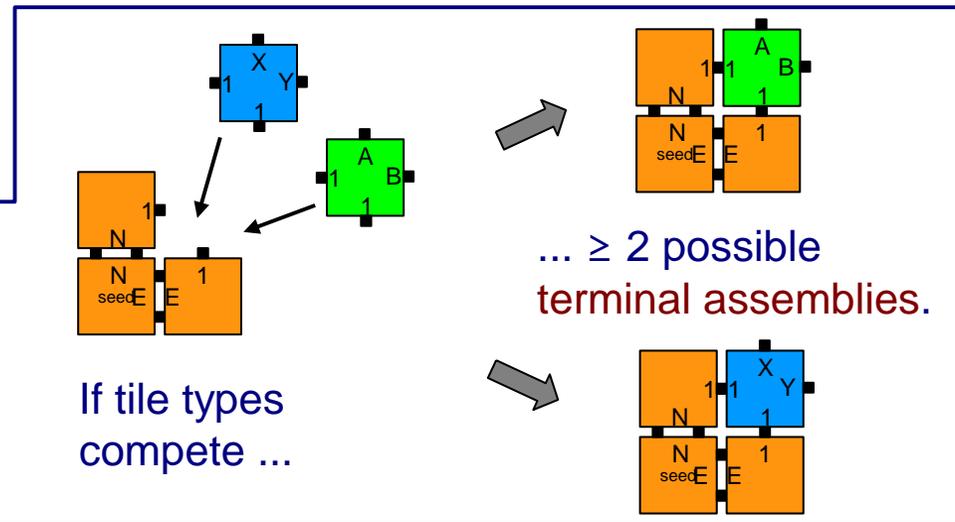
Perhaps:

≥ 2 potential binding sites



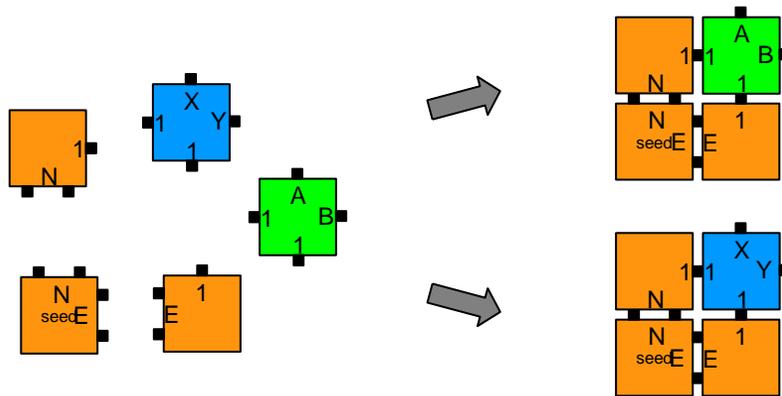
More meaningful:

at a *single* binding site, ≥ 2 tile types attachable



Nondeterminism in Self-Assembly

- A tile set is **deterministic** if it has only one terminal **assembly** (map of tile types to points).
- This tile set has multiple terminal assemblies, *but* they all have the same **shape**.

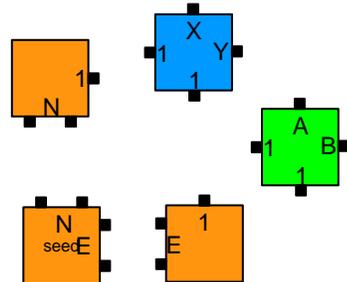


- The tile set **self-assembles** a 2 x 2 square.

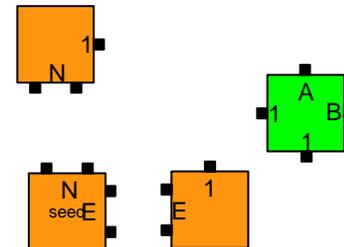
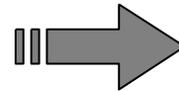
Power of Nondeterminism

Question: Let S be a finite shape self-assembled by some nondeterministic tile set. Does some deterministic tile set also self-assemble S ?

In this example, we can convert this nondeterministic tile set that self-assembles a 2 x 2 square ...



... to this deterministic tile set that self-assembles the same shape.



In general???

Power of Nondeterminism

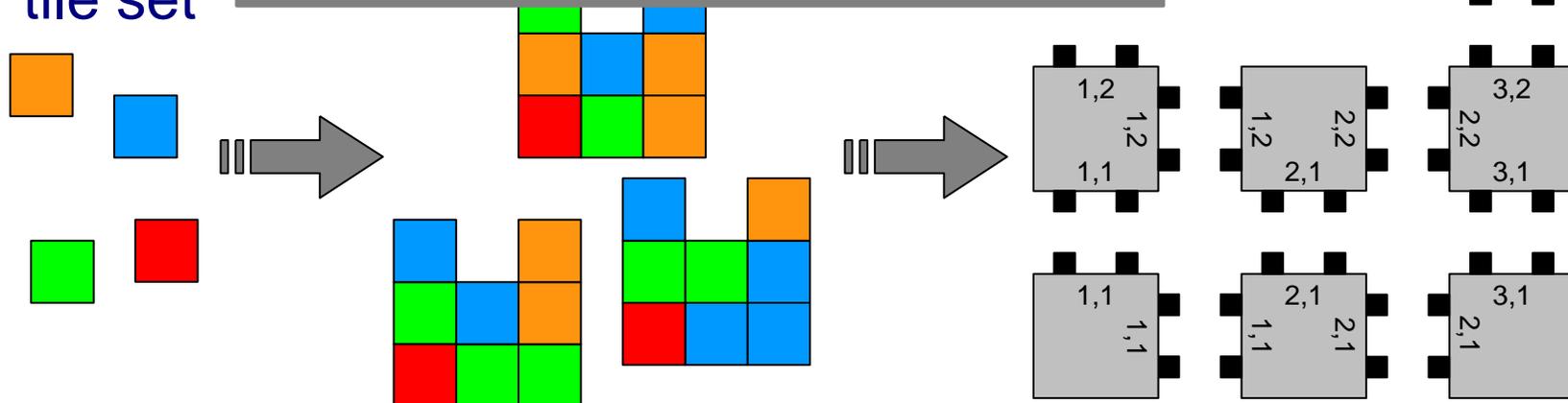
Question: Let S be a finite shape self-assembled by some nondeterministic tile set. Does some deterministic tile set also self-assemble S ?

Answer: T

Is there **some** way that nondeterminism helps to self-assemble shapes?

deterministic tile set (encoding S)

nondeterministic tile set



Power of Nondeterminism

Question 1: Let S be an infinite shape strictly self-assembled by some nondeterministic tile system. Does some deterministic tile set also self-assemble S ?

Is tile computability unaffected by nondeterminism?

Answer: No

Remainder of talk



Question 2: Let S be a finite shape strictly self-assembled by some nondeterministic tile system with k tile types. Does some deterministic tile system with at most k tile types also self-assemble S ?

Is tile complexity unaffected by nondeterminism?

Answer: No

There is an infinite shape S strictly self-assembled by only nondeterministic tile systems.

There is a finite shape S strictly self-assembled with at most k tile types by only nondeterministic tile systems.

Optimization Problems

MINTILESET

Given: finite shape S

Find: size of smallest tile system that self-assembles S

MINDETTILESET

Given: finite shape S

Find: size of smallest **deterministic** tile system that self-assembles S

False statement: **Nondeterminism does not affect tile complexity**:

for every nondeterministic tile set of size k that self-assembles a shape S , there is a deterministic tile set of size at most k that self-assembles S .

if true, would imply $\text{MINDETTILESET} = \text{MINTILESET}$

Main Result

- We show: MINTILESET is **NP^{NP}**-complete.
a.k.a., Σ_2^P
- MINDETILESET is **NP**-complete. (Adleman, Cheng, Goel, Huang, Kempe, Moisset de Espanés, Rothmund, *STOC* 2002)
- **NP** \neq **NP^{NP}** \Rightarrow MINTILESET \neq MINDETILESET

Nondeterminism in Algorithms and Self-Assembly

Algorithm that flips
coins but always
produces same output

- coin flips **useless**

Tile set that flips
coins but always
produces same shape

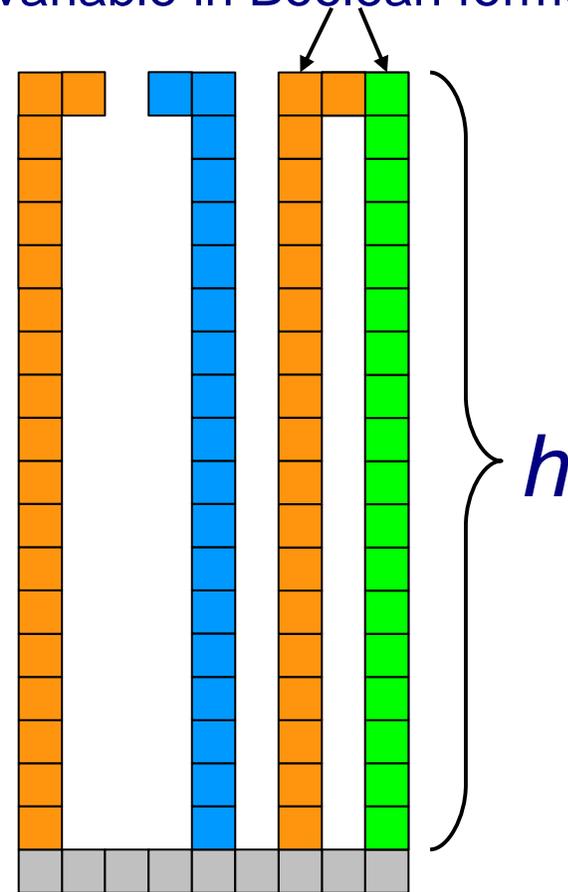
- coin flips **useful**

But ... **finding** smallest tile
set is harder if it flips coins.

A Finite Shape for which Nondeterminism Affects Tile Complexity

in $\mathbf{NP}^{\mathbf{NP}}$ -hardness reduction, compete to assign bits to variable in Boolean formula

- Smallest tile set: $\approx 2h$ tile types
- Smallest *deterministic* tile set: $\approx 3h$ tile types



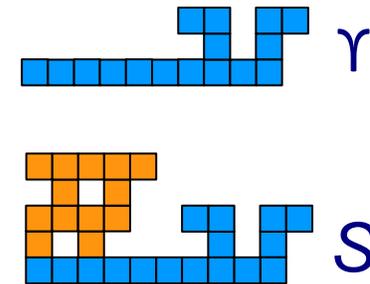
NP^{NP} -hardness Reduction

- NP^{NP} -complete problem (Stockmeyer, Wrathall 1976):
 $\exists \text{CNF-UNSAT}$
 - Given: CNF Boolean formula Φ with $k+n$ input bits
 $x=x_1\dots x_k$ and $y=y_1\dots y_n$
 - Question: is $(\exists x)(\forall y)\neg\Phi(x,y)$ true?
- **Reduction goal**: Given Φ , output shape S and integer c such that $(\exists x)(\forall y)\neg\Phi(x,y)$ holds if and only if some tile set of size at most c self-assembles S .

NP^{NP} -hardness Reduction

Main idea (due to Adleman et al. *STOC* 2002):

- Given a tree shape (no simple cycles), it is possible to compute its minimum tile set in polynomial time.
- Create a tree shape Υ that “encodes” Φ .
- Compute Υ 's minimal tile set T . ($c = |T|$)
- Create shape $S \supset \Upsilon$ such that
 - If $(\exists x)(\forall y)\neg\Phi(x,y)$, tiles from T can be altered to assemble S .
 - Otherwise, tiles from T cannot be altered to assemble S .
 - “Since $\Upsilon \subseteq S$,” every tile set that assembles S contains T , so if tiles from T cannot be altered to assemble S then additional tiles are needed; i.e., S requires more than $c = |T|$ tile types.



Evaluation of Formula

- Order variables $w = w_1 \dots w_n$ (both \exists and \forall variables) and clauses $C_1 \dots C_m$ arbitrarily.
- Fix an assignment to variables.
- For each clause C_j and variable w_i , let a_{ij} be the pair (U/S, T/F) representing whether C_j is satisfied by w_k for $k \leq i$, and whether w_k is true or false.
- The matrix $A = (a_{ij})$ looks like

$w = 0011$

$$\Phi = (w_1 \vee w_3) \wedge (w_1 \vee w_2 \vee w_4) \wedge (\neg w_1 \vee w_2)$$

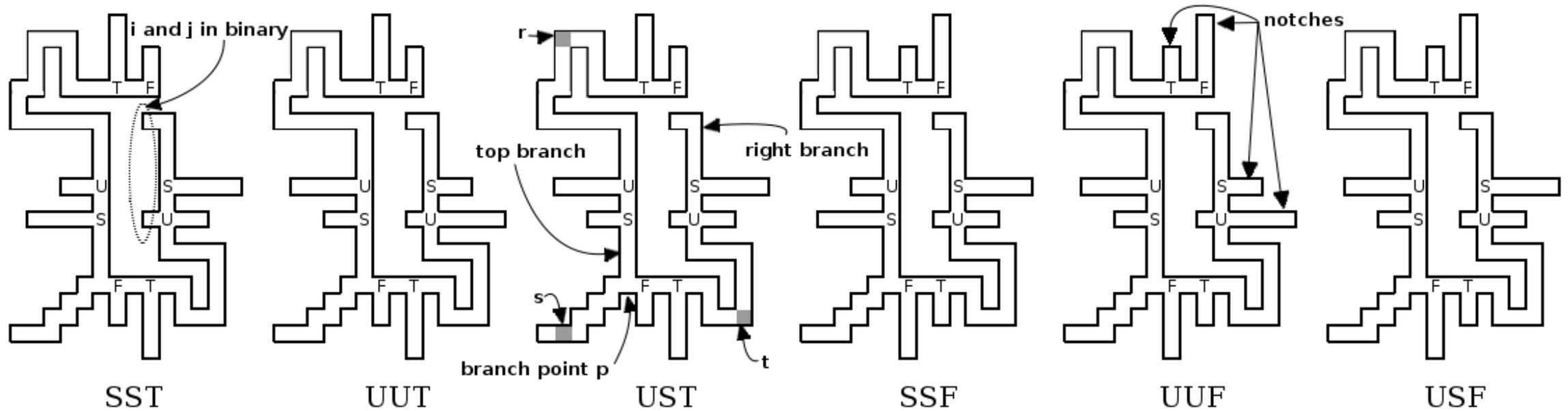
C_3	SF	SF	ST	ST
C_2	UF	UF	UT	ST
C_1	UF	UF	ST	ST
	w_1	w_2	w_3	w_4



highlighting when C_i goes from unsatisfied (U) to satisfied (S)

C_3	USF	SSF	SST	SST
C_2	UUF	UUF	UUT	UST
C_1	UUF	UUF	UST	SST
	w_1	w_2	w_3	w_4

Gadgets (Adleman et al. 2002)



For each variable w_i and clause C_j , value of $w_i = T/F$ and

SS_{ij} – C_j satisfied by a previous variable (w_k for $k < i$)

US_{ij} – C_j unsatisfied by previous variables but is satisfied by w_i

UU_{ij} – C_j unsatisfied by previous variables and by w_i

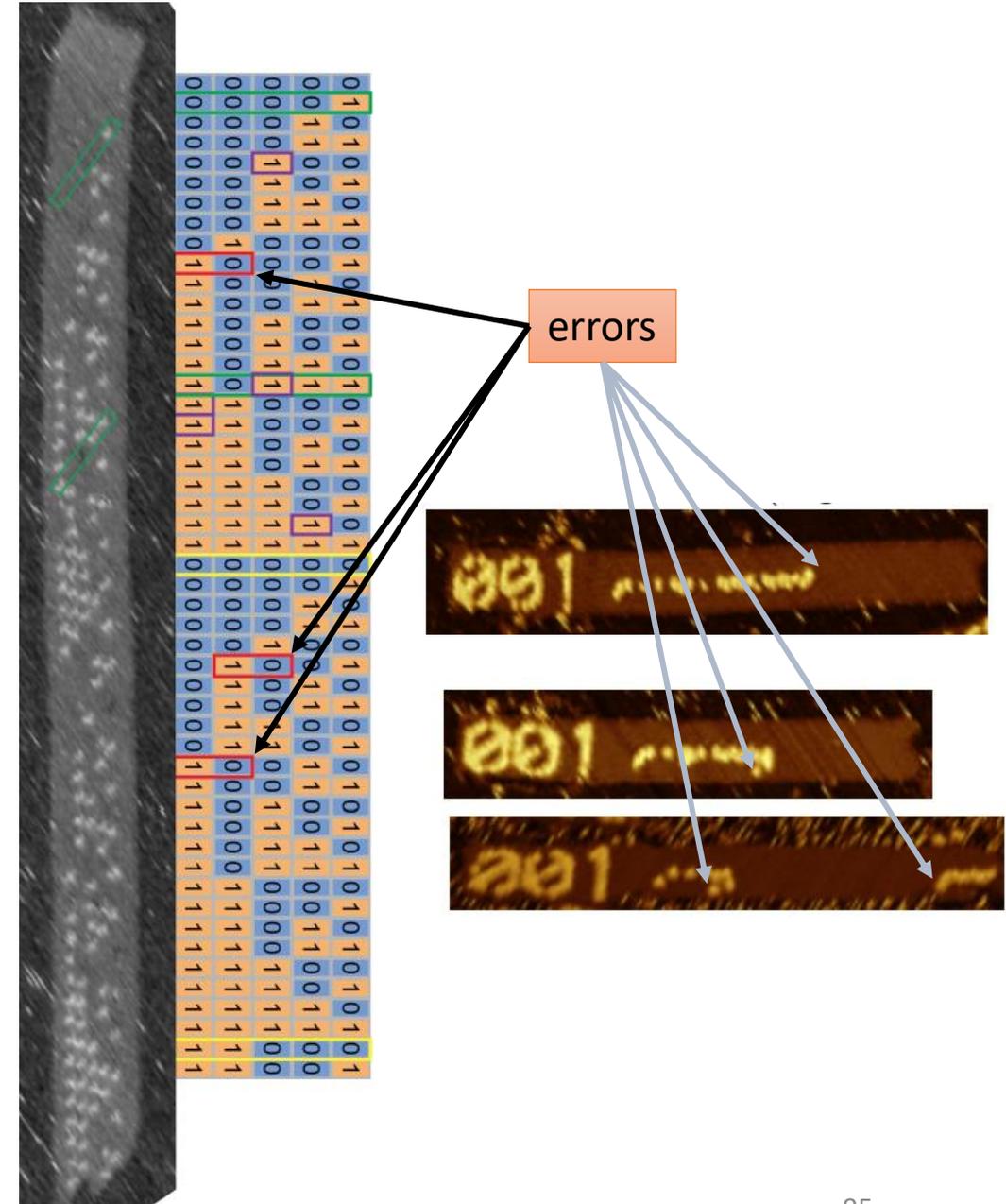
Open Questions

- How large is the gap between deterministic tile complexity and unrestricted tile complexity? our example has ratio $3/2$; Schweller (unpublished) improved to quadratic gap: <https://faculty.utrgv.edu/robert.schweller/papers/TheGap.pdf>
- Hardness of approximation of minimum tile set problem
- Minimum tile set problem when shape is a square
 - deterministic case in **P**; likely not **NP**-hard by Mahaney's theorem (no sparse set is **NP**-hard unless **P=NP**)
- *Weak self-assembly* (pattern painting): paint some tile types “black”, and say “pattern assembled” is set of points with a black tile
 - *Minimum tile set problem*: uncomputable! (**NP**-complete with some restrictions: <https://arxiv.org/abs/1404.0967>)
 - *Power of nondeterminism*: is it possible to uniquely paint a pattern, but only by assembling more than one shape on which the pattern is painted?

Errors in algorithmic self-assembly

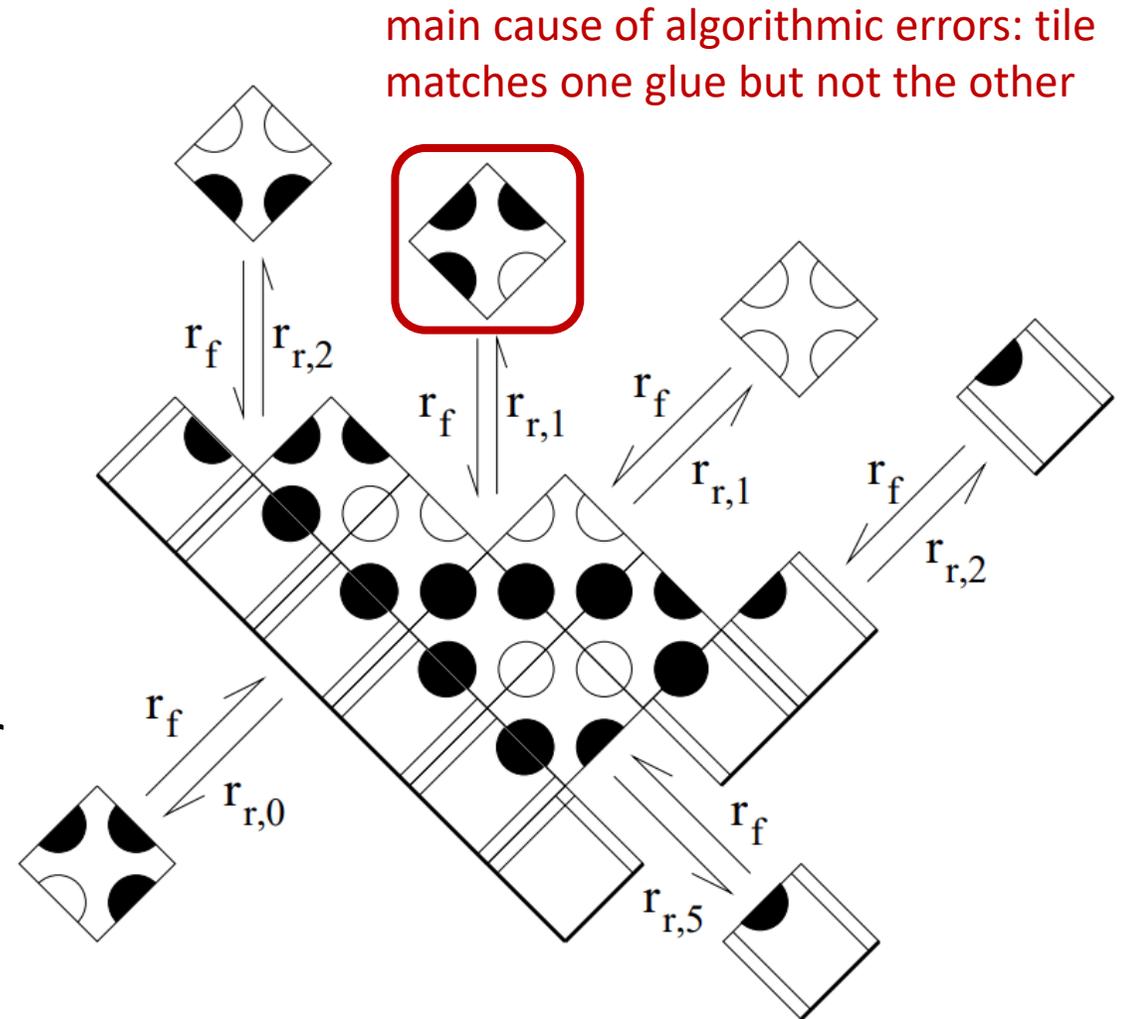
Errors in self-assembly

- abstract Tile Assembly Model (aTAM, the model we've used so far):
 - tiles attach but never detach
 - tiles bind only with strength 2 or higher
- unrealistic... what's a better model?
- kinetic Tile Assembly Model (kTAM); essential differences with aTAM:
 - tiles can detach
 - tiles can bind with strength 1



Modeling errors: kinetic Tile Assembly Model

- All tiles attach with rate r_f (no matter how many glues match)
- Tiles detach with rate $r_{r,b}$, if they are attached by total glue strength b
- “rate” = time until it occurs is exponential random variable with that rate; expected time $1/\text{rate}$
 - a.k.a., continuous time Markov process
- Take home message: tiles bound with fewer glues (potential errors) fall off faster, but could get locked in by subsequent neighboring attachment



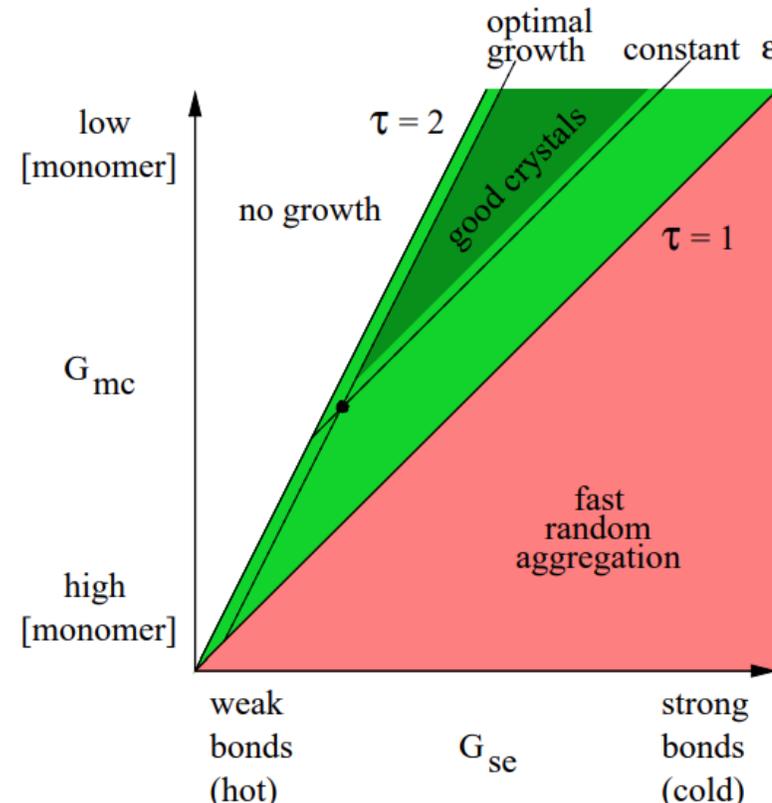
kTAM simulators

- ISU TAS (developed by Matt Patitz) also does kTAM simulation:
 - [http://self-assembly.net/wiki/index.php?title=ISU TAS](http://self-assembly.net/wiki/index.php?title=ISU_TAS)
 - [http://self-assembly.net/wiki/index.php?title=ISU TAS Tutorials](http://self-assembly.net/wiki/index.php?title=ISU_TAS_Tutorials)
- xgrow (developed by Erik Winfree)
 - <https://www.dna.caltech.edu/Xgrow/>
 - older and a bit less intuitive

Tradeoff between assembly speed and errors

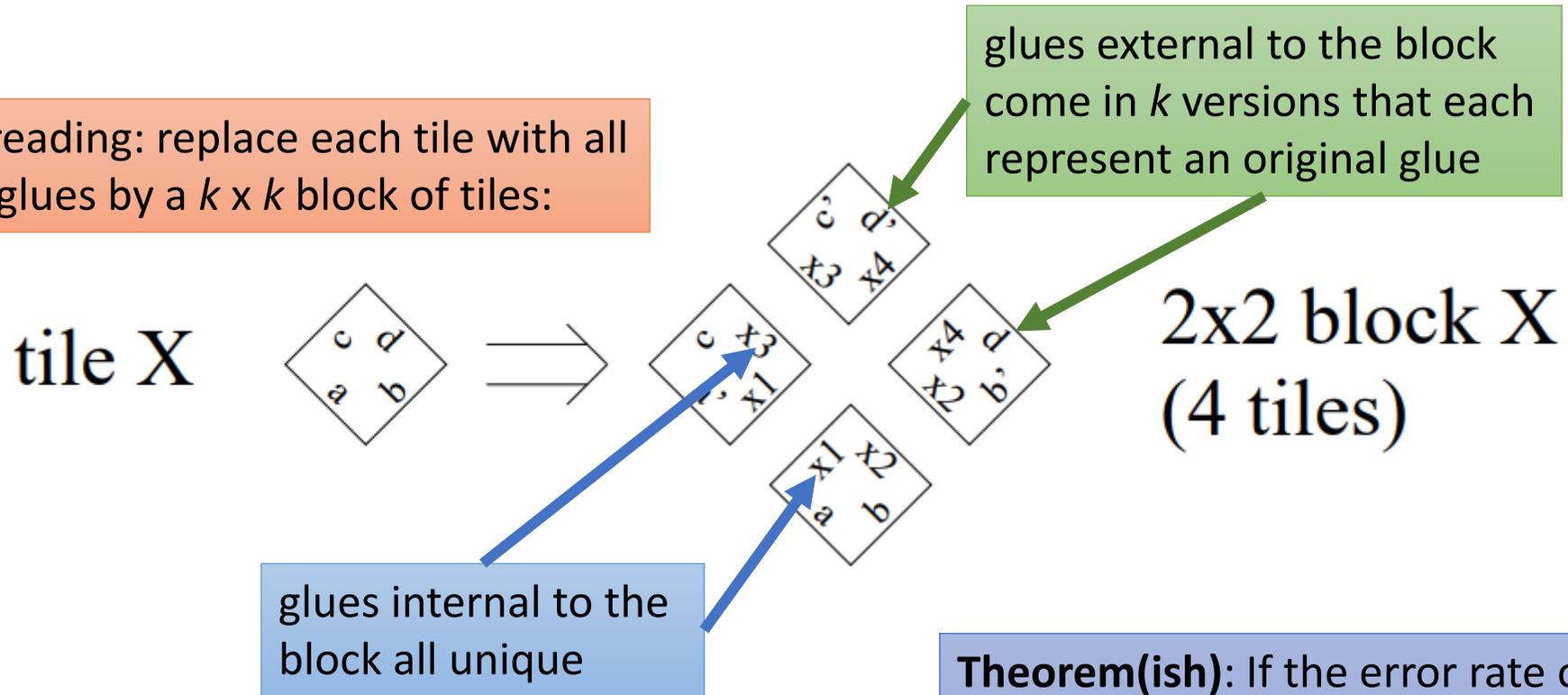
- attach rate r_f can be controlled through concentrations
 - “energy” of attachment is called G_{mc} (monomer concentration): $r_f \propto e^{-G_{mc}}$
- detach rate $r_{r,b}$ can be controlled through temperature
 - “energy” of detachment is called G_{se} (sticky end): $r_{r,b} \propto e^{-b \cdot G_{se}}$
- Intuitively, setting $r_f \approx r_{r,2}$ is like “temperature $\tau = 2$ ” assembly
 - ... but with net zero growth rate
 - make r_f a little larger, and growth is faster, but error rates go up

Theorem [Winfree, 1998]: To have total error rate ϵ , for fastest assembly speed, set $G_{se} = \ln(4/\epsilon)$ and $G_{mc} = \ln(8/\epsilon^2)$, i.e., $G_{mc} = 2G_{se} - \ln 2$, i.e., $r_f/r_{r,2} = 2$



Proofreading: Algorithmic error correction

$k \times k$ proofreading: replace each tile with all strength-1 glues by a $k \times k$ block of tiles:



Proposition: No tiling of the $k \times k$ region with “consistent external glues” (all represent the same glue in original tile set) has m mismatches, where $0 < m < k$, i.e., if any mismatch occurs, then at least k mismatches occur before the $k \times k$ block can be completed to represent the wrong external glue.

Theorem(ish): If the error rate of the original tile system is ε , the error rate of the $k \times k$ proofreading tile system is $O(\varepsilon^k)$, e.g., if $\varepsilon = 0.01$, then 2×2 proofreading gets error rate about $\varepsilon^2 = 0.0001$.

Experimental algorithmic self-assembly

Crystals that think about how they're growing



joint work with Damien Woods, Erik Winfree, Cameron Myhrvold, Joy Hui, Felix Zhou, Peng Yin

slides for ECS 232: Theory of Molecular Computation



Caltech



Inria Paris



UC Davis



Harvard

Acknowledgements



Caltech



Inria Paris



UC Davis



Harvard

Damien Woods
(co-first author)



Erik Winfree



co-authors

Cameron Myhrvold



Peng Yin



Felix Zhou



Joy Hui



lab/science help

Sungwook Woo

Constantine Evans

Sarina Mohanty

Niranjan Srinivas

Deborah Fygenon

Yannick Rondolez

Mingjie Dai

Nikhil Gopalkrishnan

Chris Thachuk

Nadine Dabby

Jongmin Kim

Paul Rothmund

Bryan Wei

Cody Geary

Ashwin Gopinath

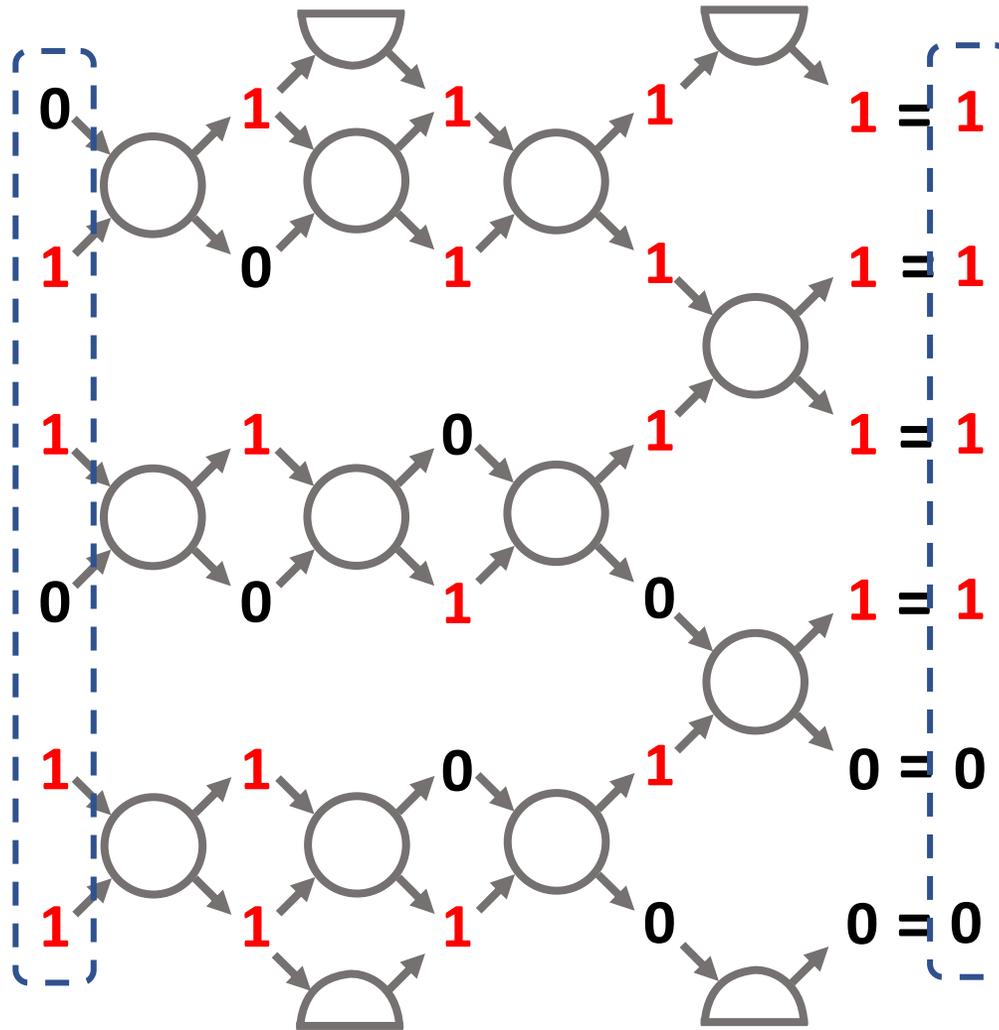


Diverse and robust molecular algorithms using reprogrammable DNA self-assembly.
Damien Woodst, David Doty†, Cameron Myhrvold, Joy Hui, Felix Zhou, Peng Yin, Erik Winfree.
Nature 2019. †*These authors contributed equally.*

Hierarchy of abstractions

➔ Bits:	Boolean circuits compute
Tiles:	Tile growth implements circuits
DNA:	DNA strands implement tiles

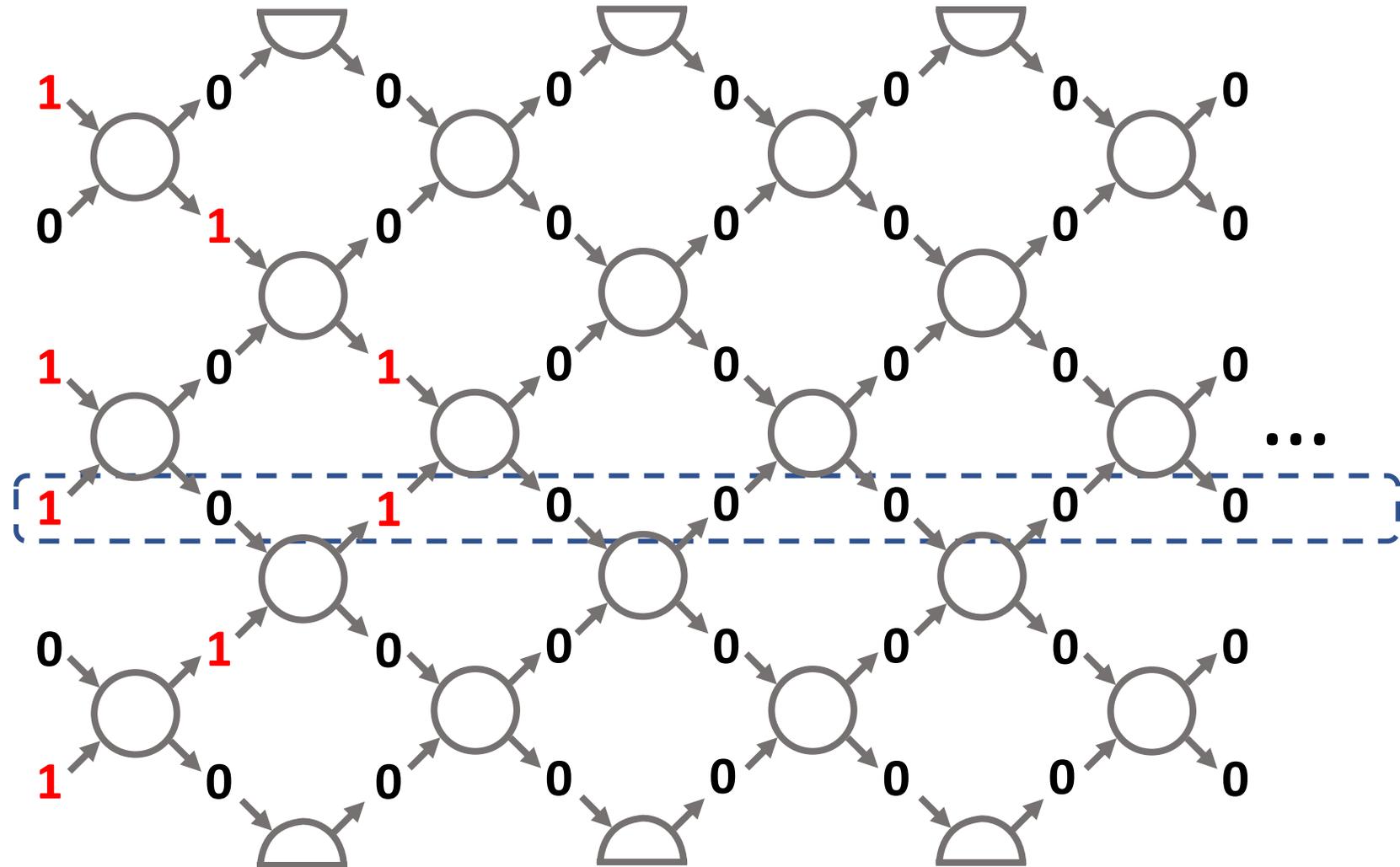
Harmonious arrangement



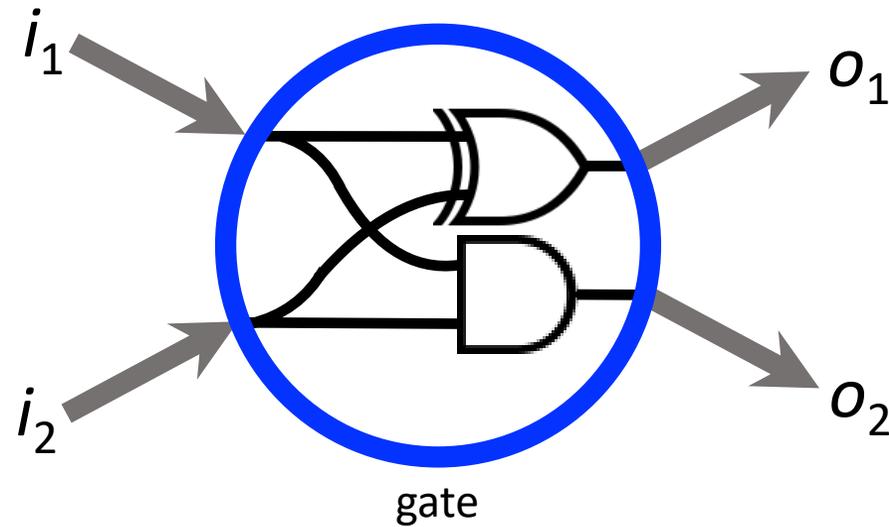
a.k.a. sorting



Parity



Circuit model

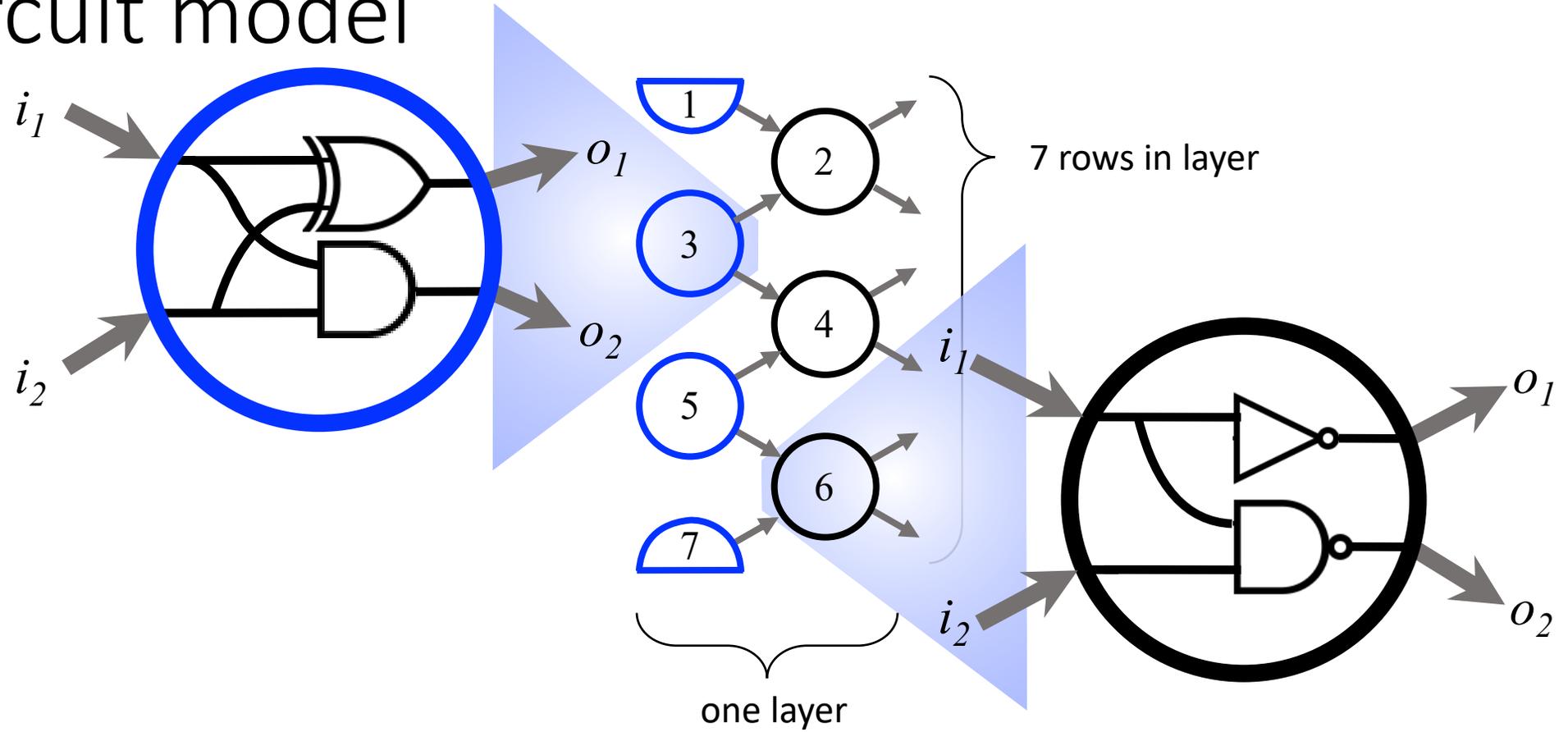


truth table

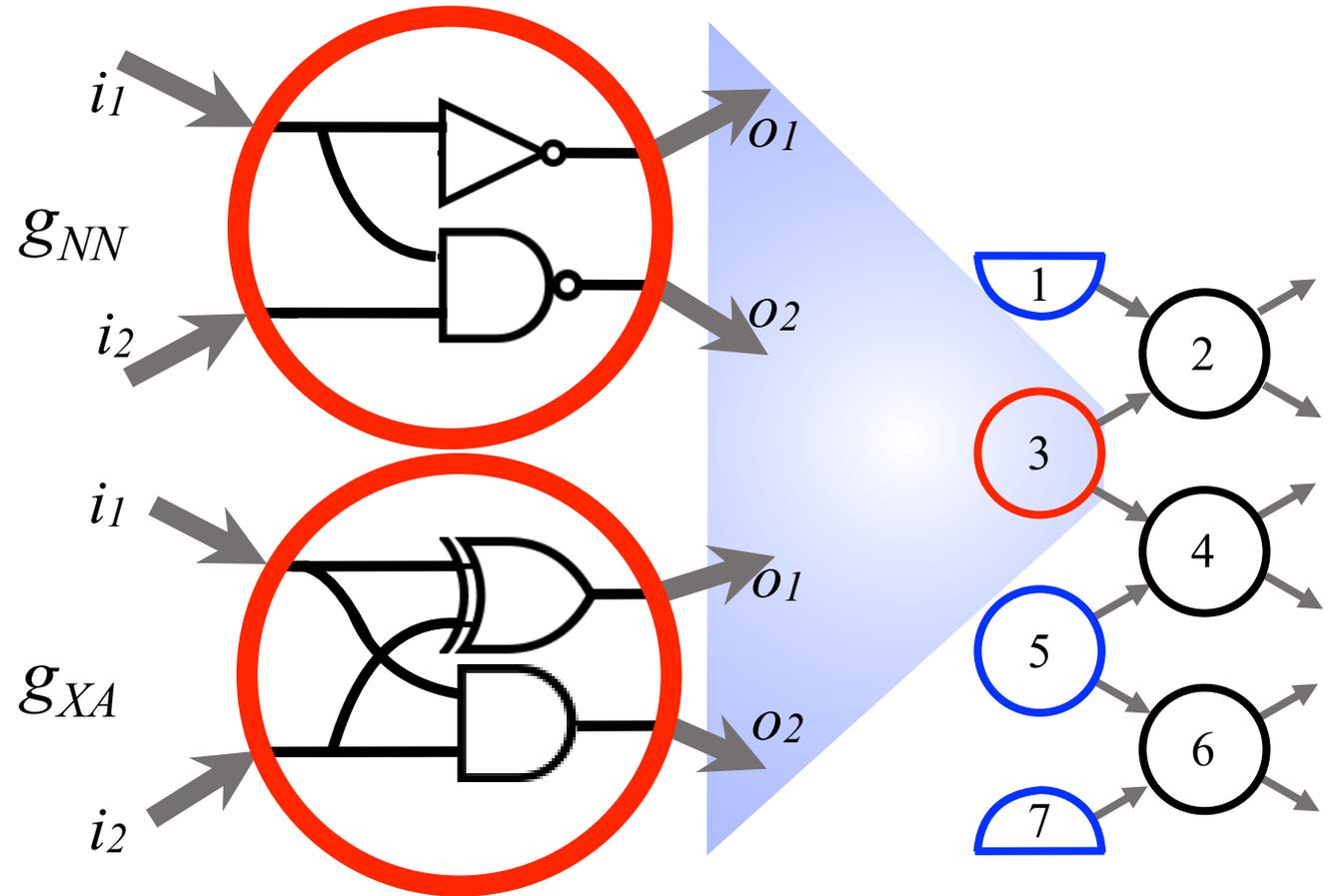
i_1	i_2	o_1	o_2
0	0	0	0
0	1	1	0
1	0	1	0
1	1	0	1

gate: function with two input bits i_1, i_2
and two output bits o_1, o_2

Circuit model



Circuit model

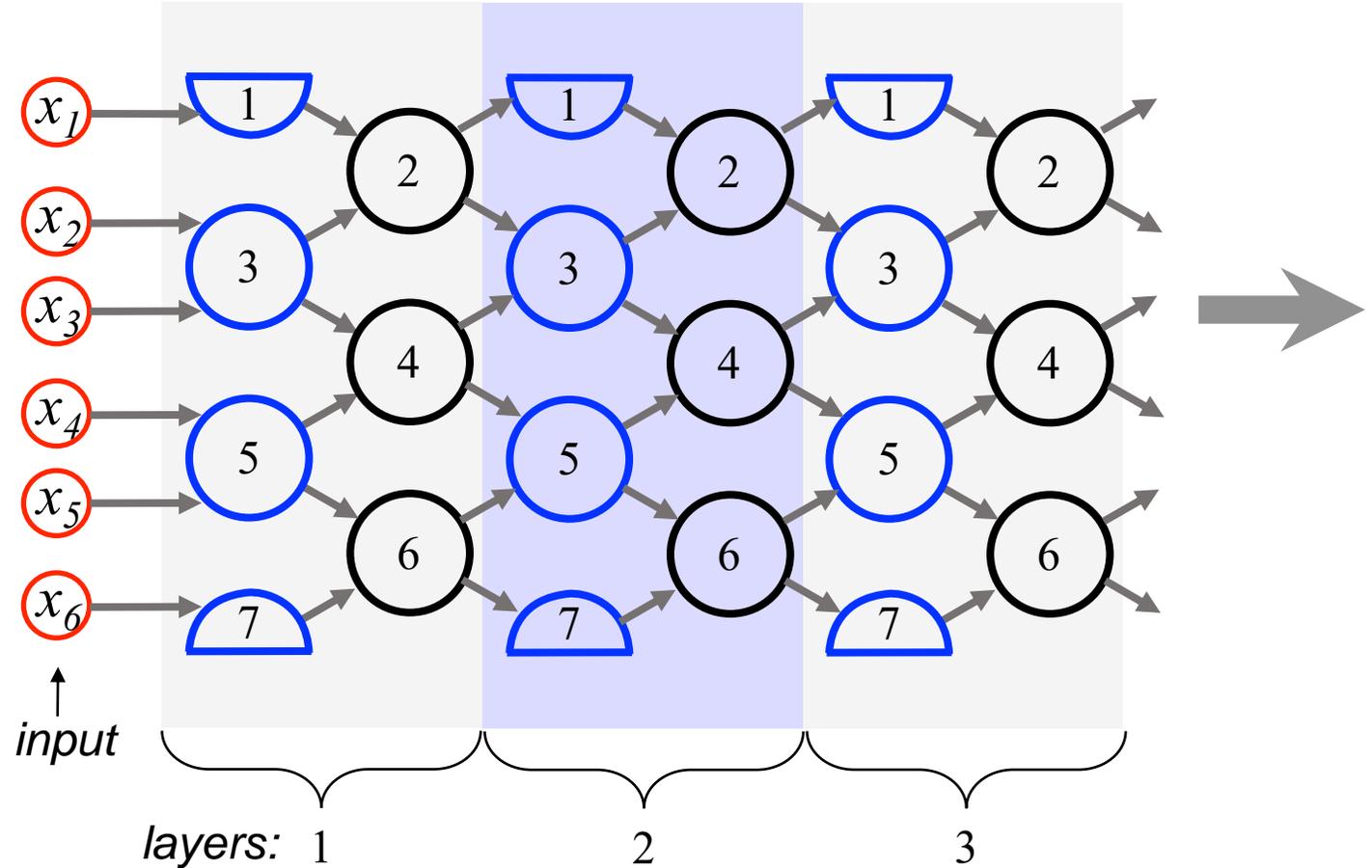


Randomization: Each row may be assigned ≥ 2 gates, with associated probabilities, e.g., $\Pr[g_{NN}] = \Pr[g_{XA}] = \frac{1}{2}$

Circuit model

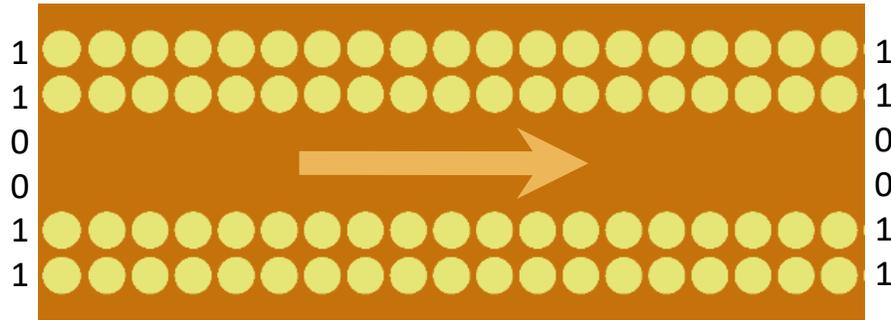
Programmer specifies layer:
gates to go in each row

User gives n input bits

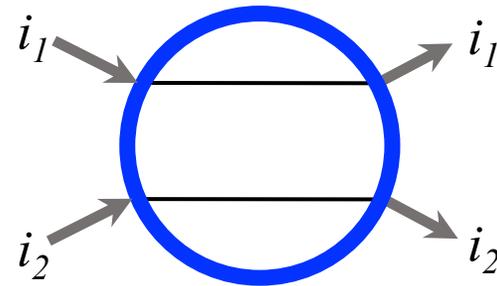


Example circuits with same gate in every row

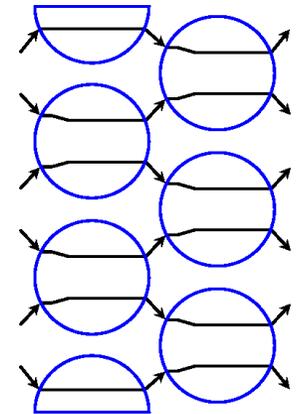
COPY



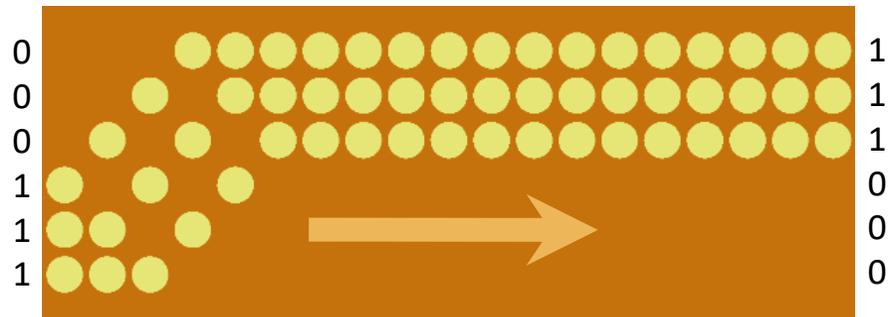
COPY gates



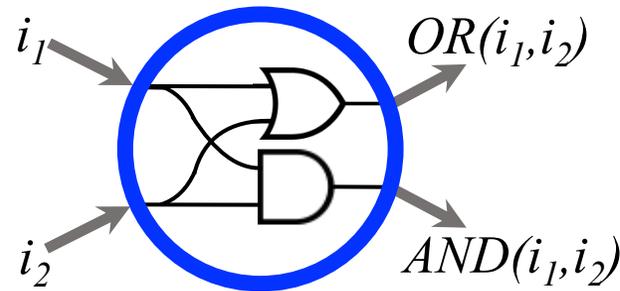
i_1	i_2	o_1	o_2
0	0	0	0
0	1	0	1
1	0	1	0
1	1	1	1



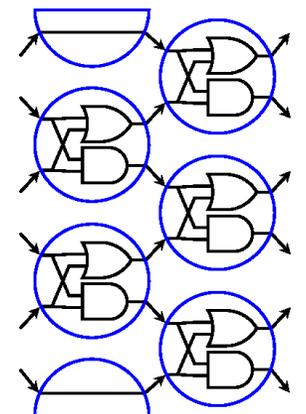
SORTING



SORTING gates

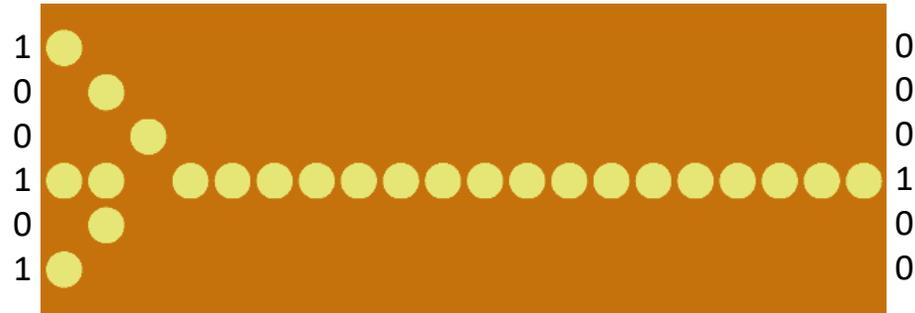
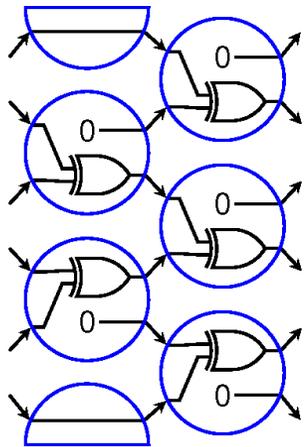


i_1	i_2	o_1	o_2
0	0	0	0
0	1	1	0
1	0	1	0
1	1	1	1

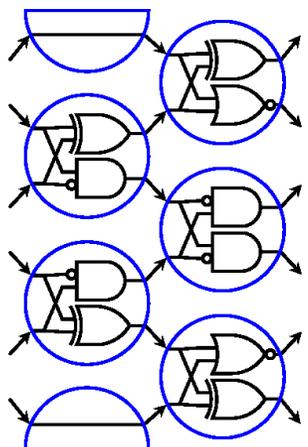


Example circuits with different gates in each row

PARITY



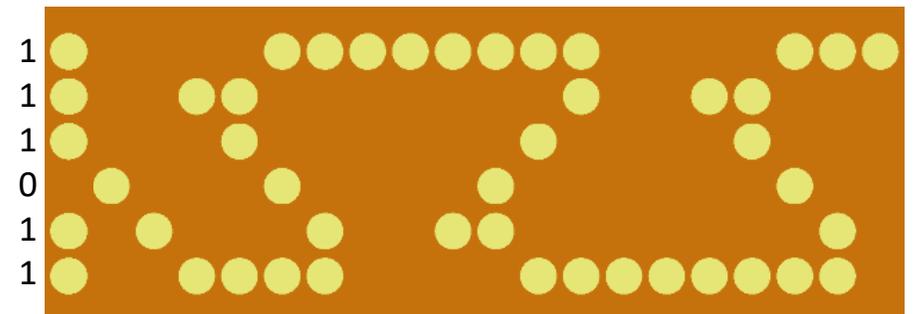
MULTIPLEOF3



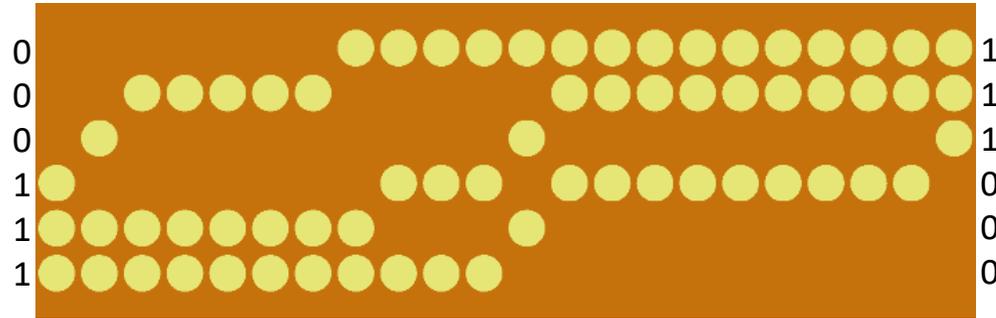
$$011011_2 = 27_{10} = 3 \cdot 9$$



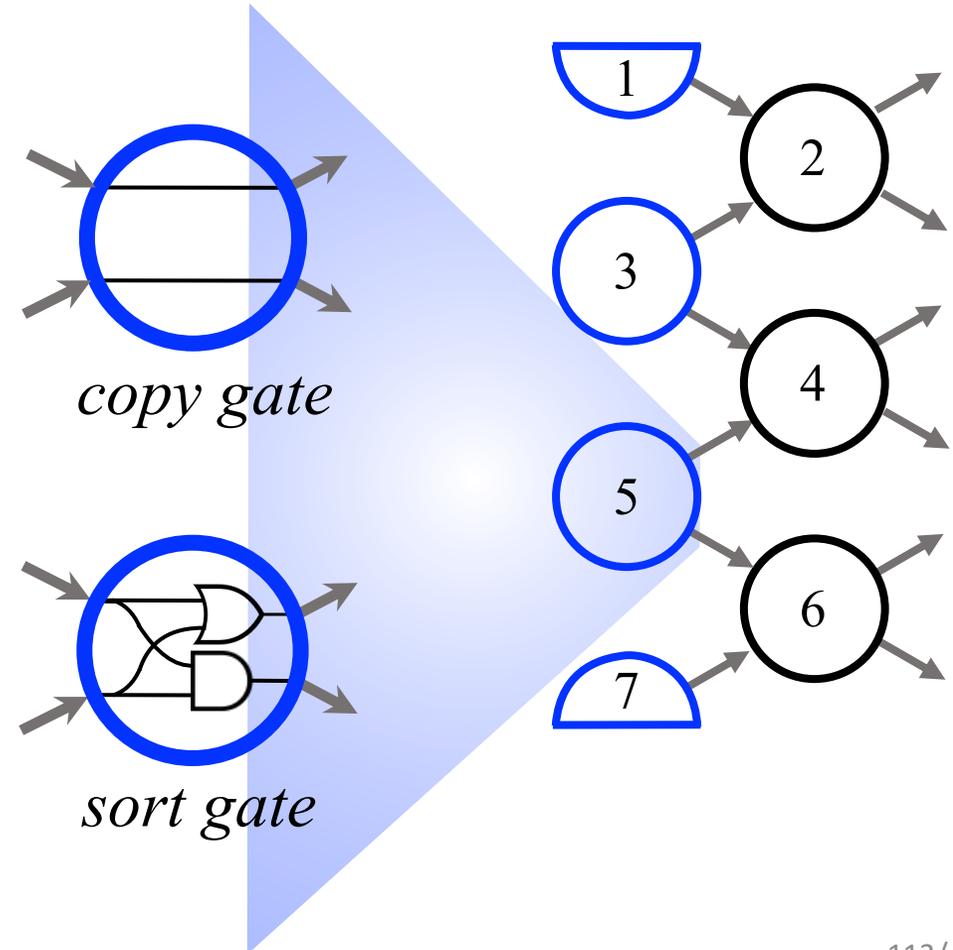
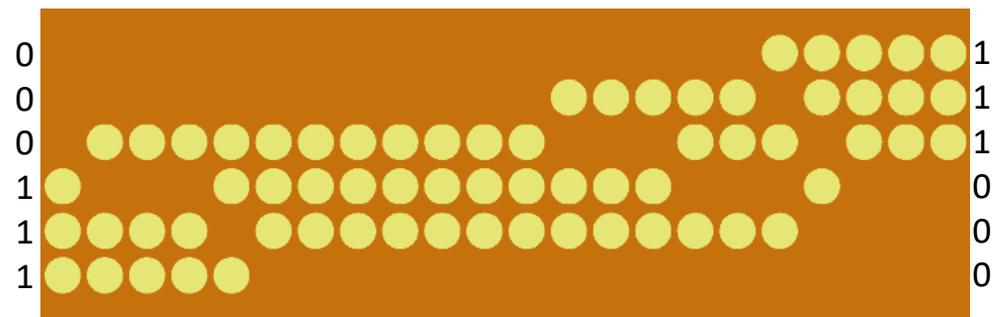
$$111011_2 = 59_{10} = 3 \cdot 19 + 2$$



Randomization: “Lazy” sorting

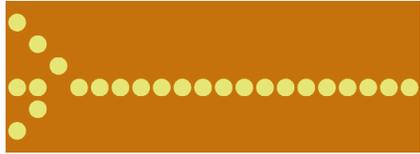


If 1 and 0 out of order, flip a coin to decide whether to swap them.

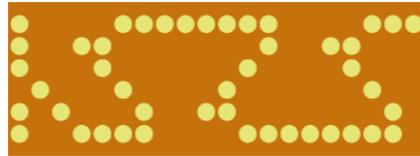
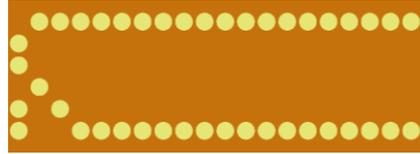


Deterministic circuits

PARITY



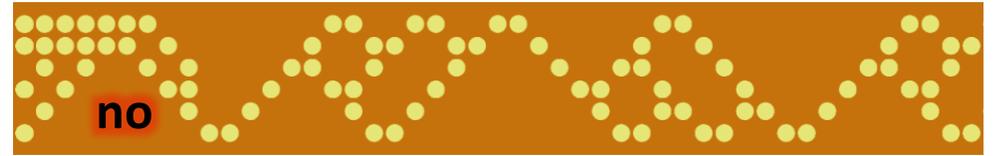
MULTIPLEOF3



PALINDROME

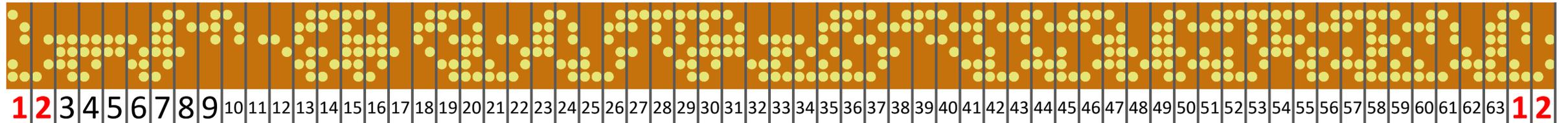


answer yes/no question



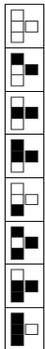
CYCLE63

“count” as high as possible

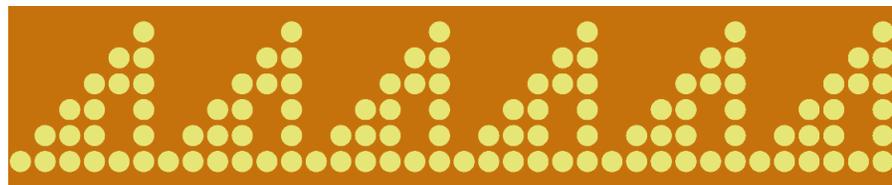


RULE110

simulate cellular automata



time →



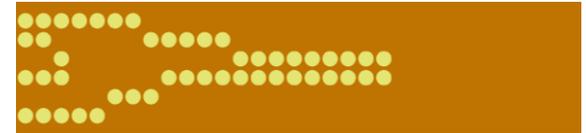
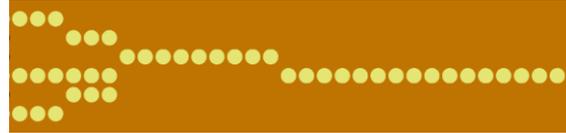
Theorem: Rule 110 can efficiently execute any algorithm.

[Cook, Complex Systems 2004]

[Neary, Woods, ICALP 2006]

Randomized circuits

LAZYPARITY



RANDOMWALKINGBIT



DIAMONDSAREFOREVER



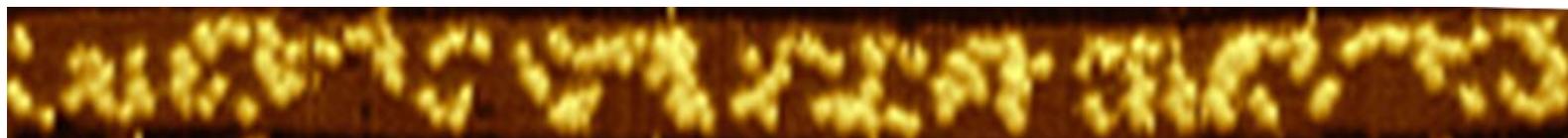
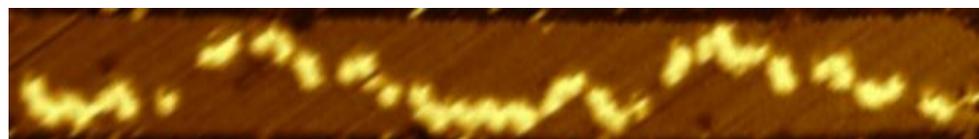
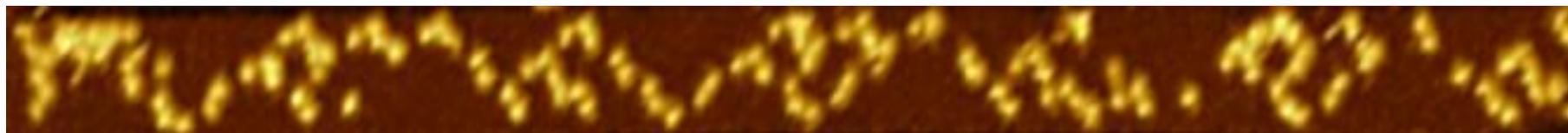
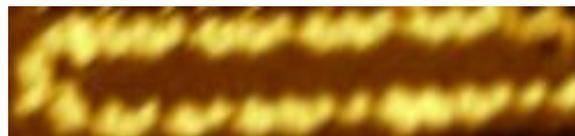
FAIRCOIN

use biased coin to
simulate unbiased coin

$$\Pr \left[\text{Diagram 1} \right] = \Pr \left[\text{Diagram 2} \right] = \frac{1}{2}$$

for **any** (positive) probabilities for the randomized gate

100 nm



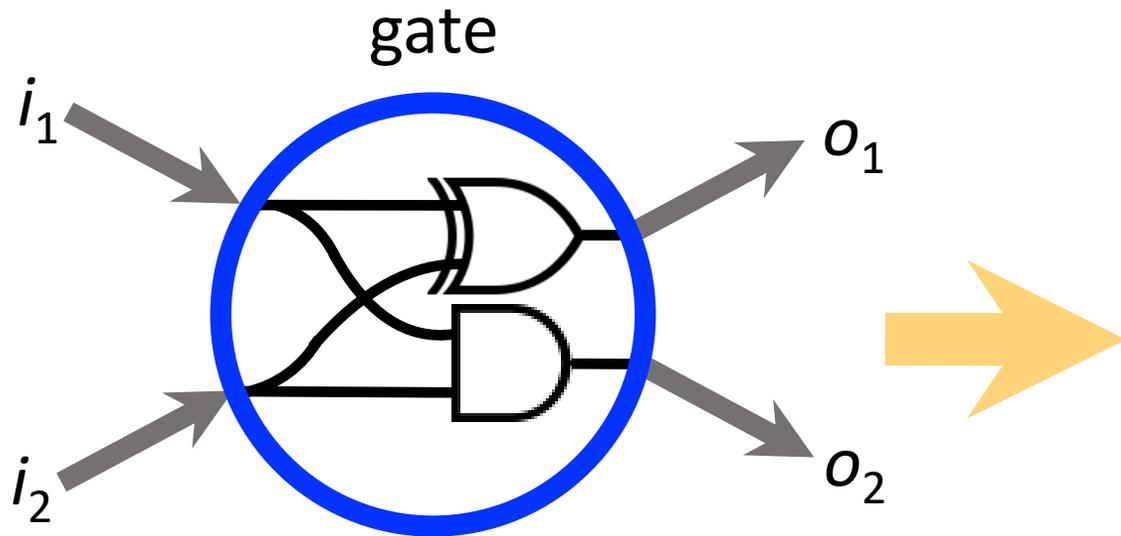
Hierarchy of abstractions

Bits: Boolean circuits compute

→ Tiles: Tile growth implements circuits

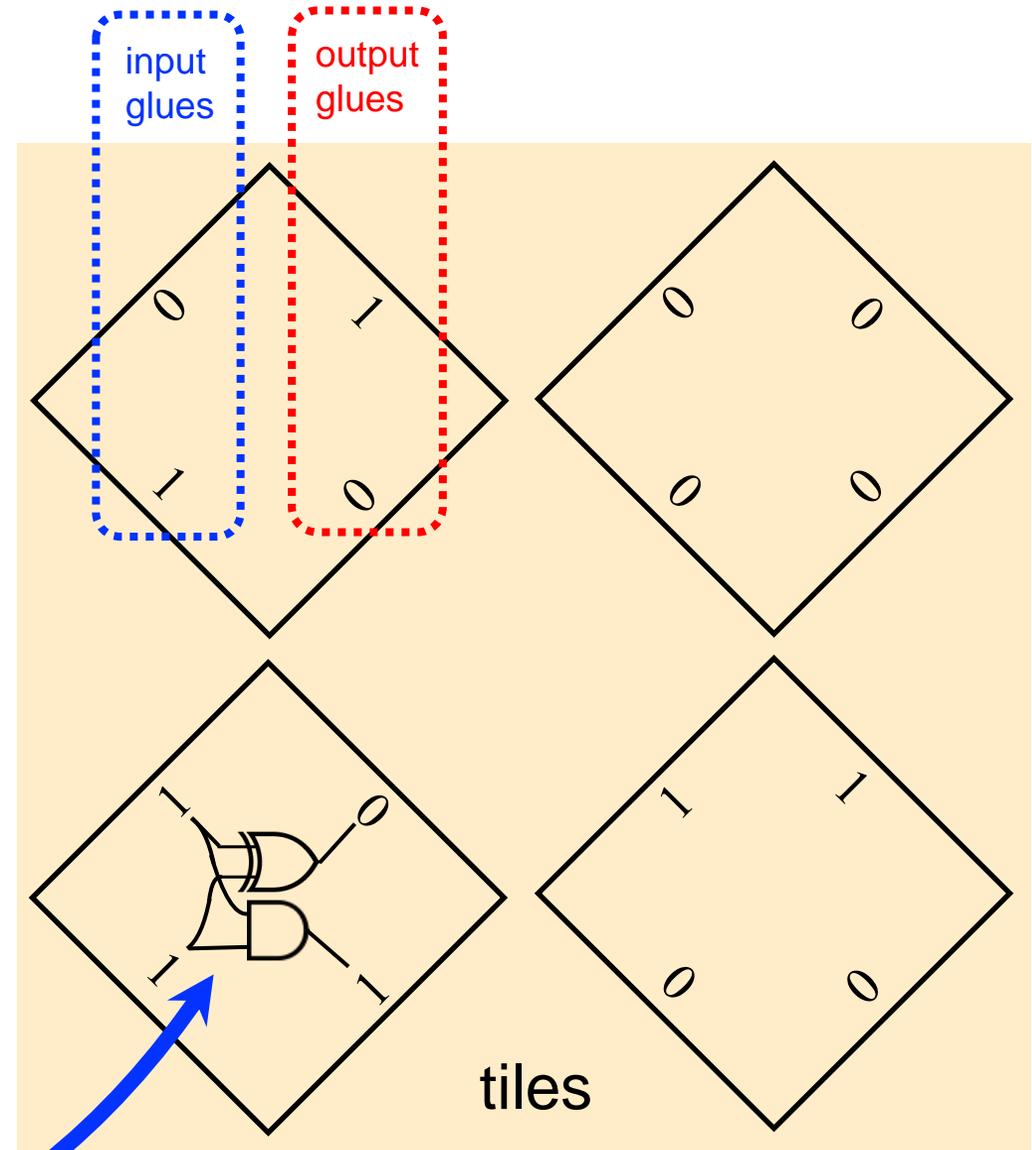
DNA: DNA strands implement tiles

Gates \rightarrow Tiles

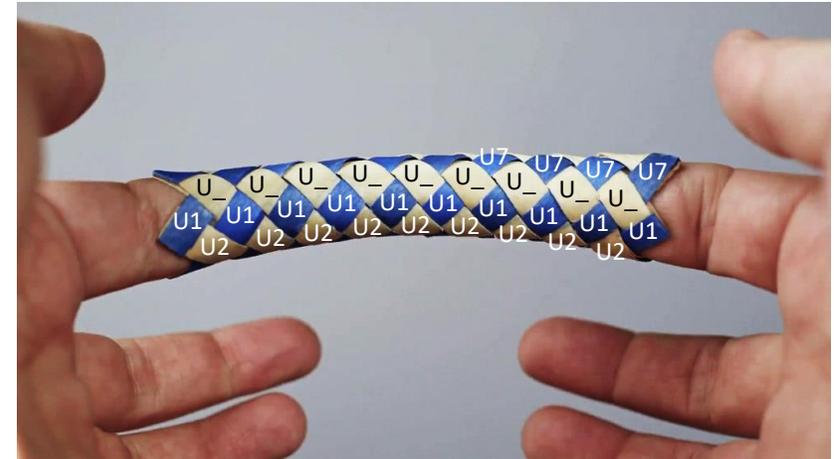
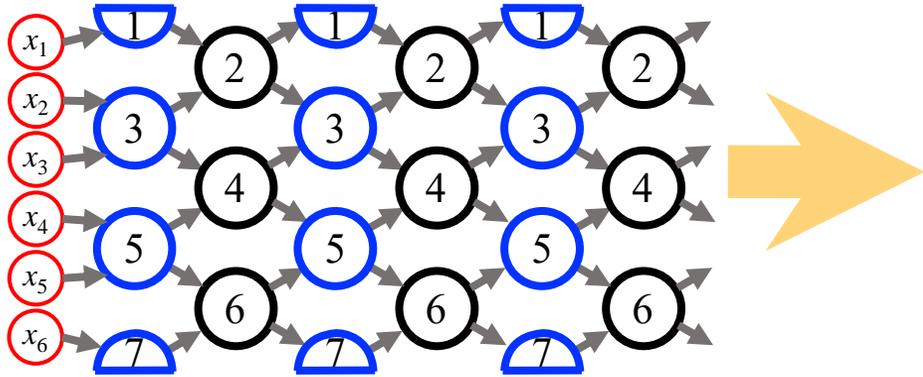


i_1	i_2	o_1	o_2
0	0	0	0
0	1	1	0
1	0	1	0
1	1	0	1

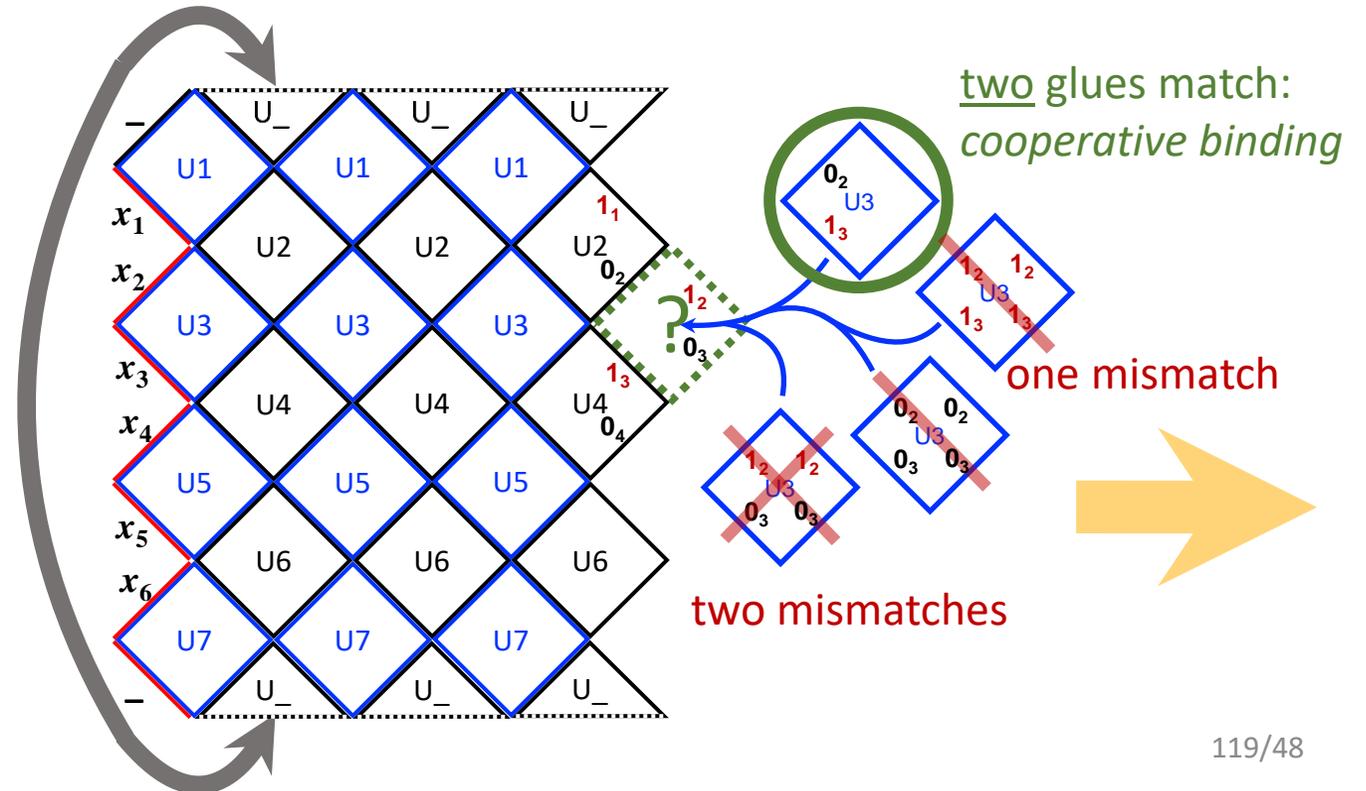
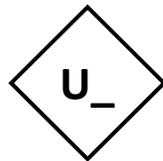
truth table row is encoded by a **tile** with 4 **glues** encoding bits



How tiles compute while growing (algorithmic self-assembly)



“data-free” tile wraps top to bottom to form a tube



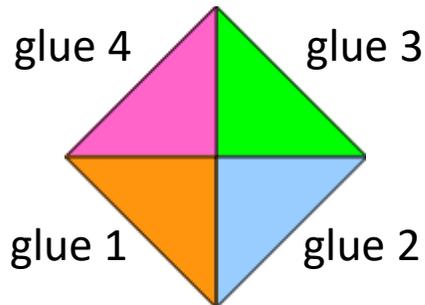
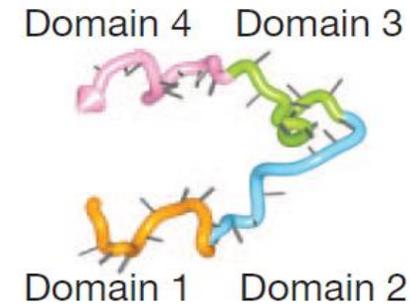
Hierarchy of abstractions

Bits: Boolean circuits compute

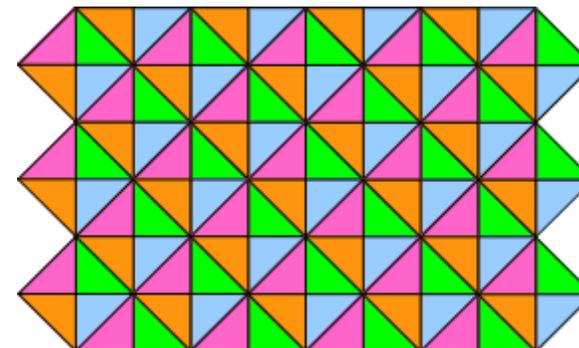
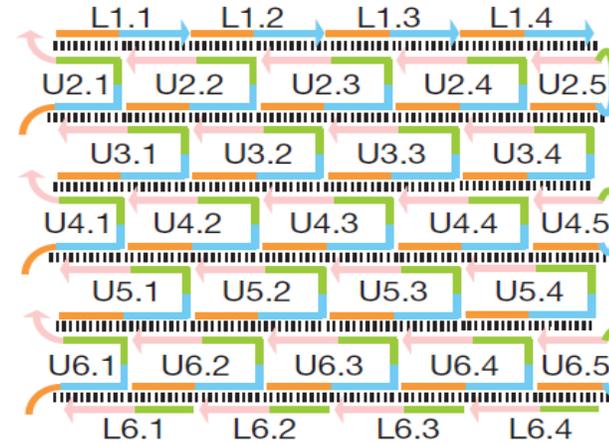
Tiles: Tile growth implements circuits

→ DNA: DNA strands implement tiles

DNA single-stranded tiles

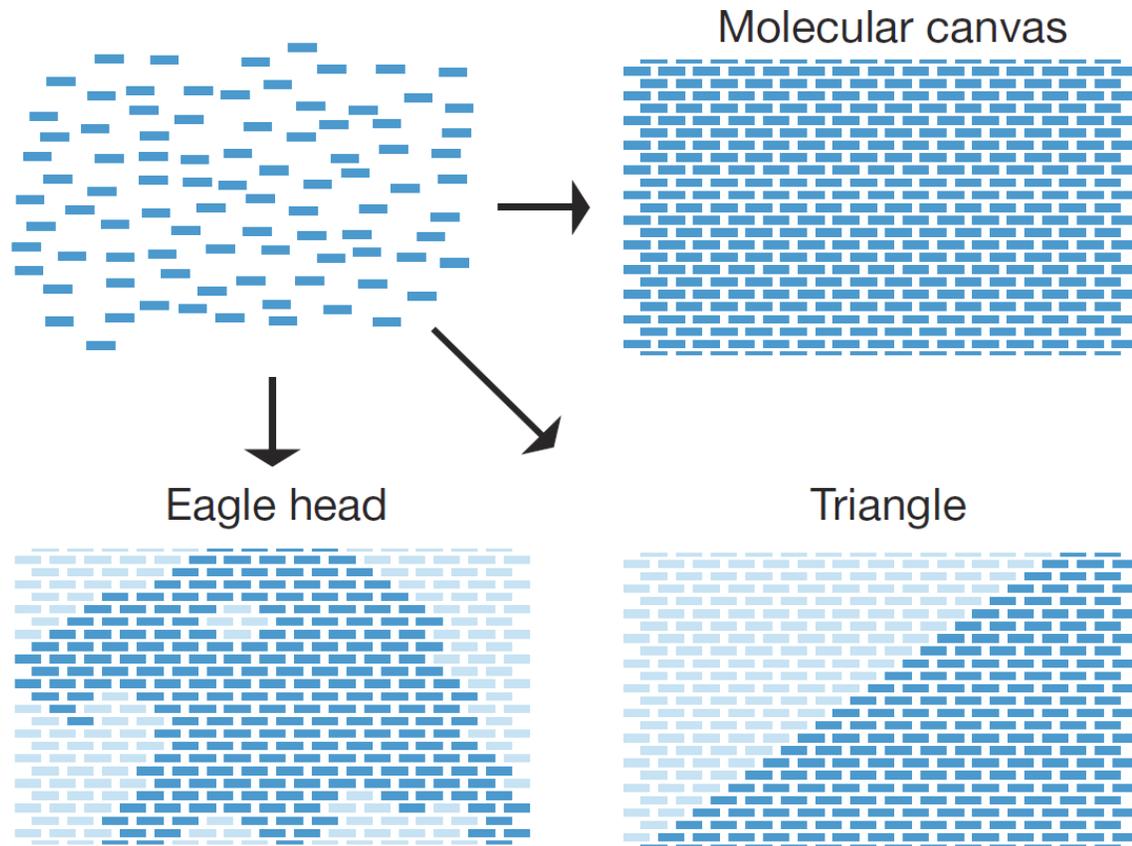


assembly →



Yin, Hariadi, Sahu, Choi, Park, LaBean, and Reif.
Programming DNA tube circumferences.
Science 2008

Single-stranded tiles for making any shape



Bryan Wei, Mingjie Dai, and Peng Yin.
Complex shapes self-assembled from single-stranded DNA tiles.
Nature 2012.

Uniquely addressed self-assembly versus algorithmic

Unique addressing: each DNA “monomer” appears **exactly once** in final structure.

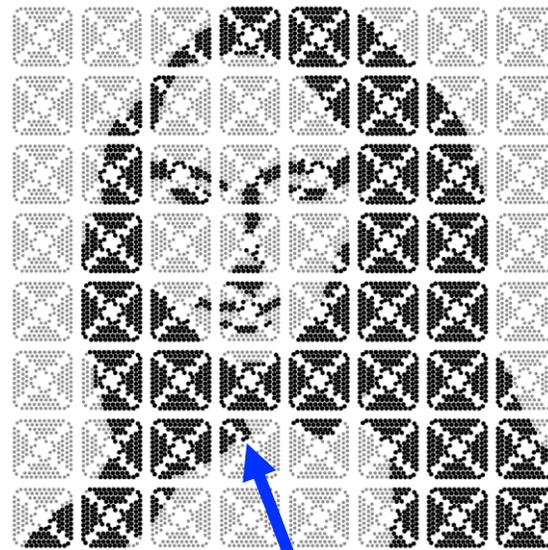
Algorithmic: DNA tiles are **reused** throughout the structure.

single DNA origami



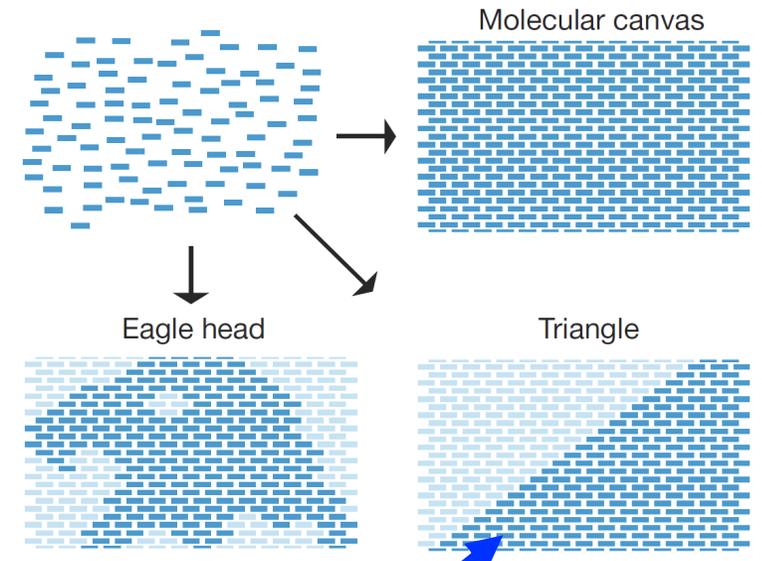
staple strand for position (4,2)

array of many DNA origamis



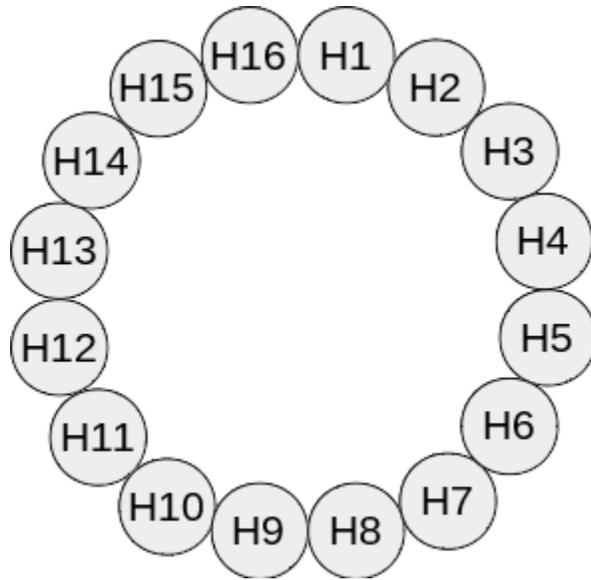
origami for position (4,2)

uniquely-addressed tiles

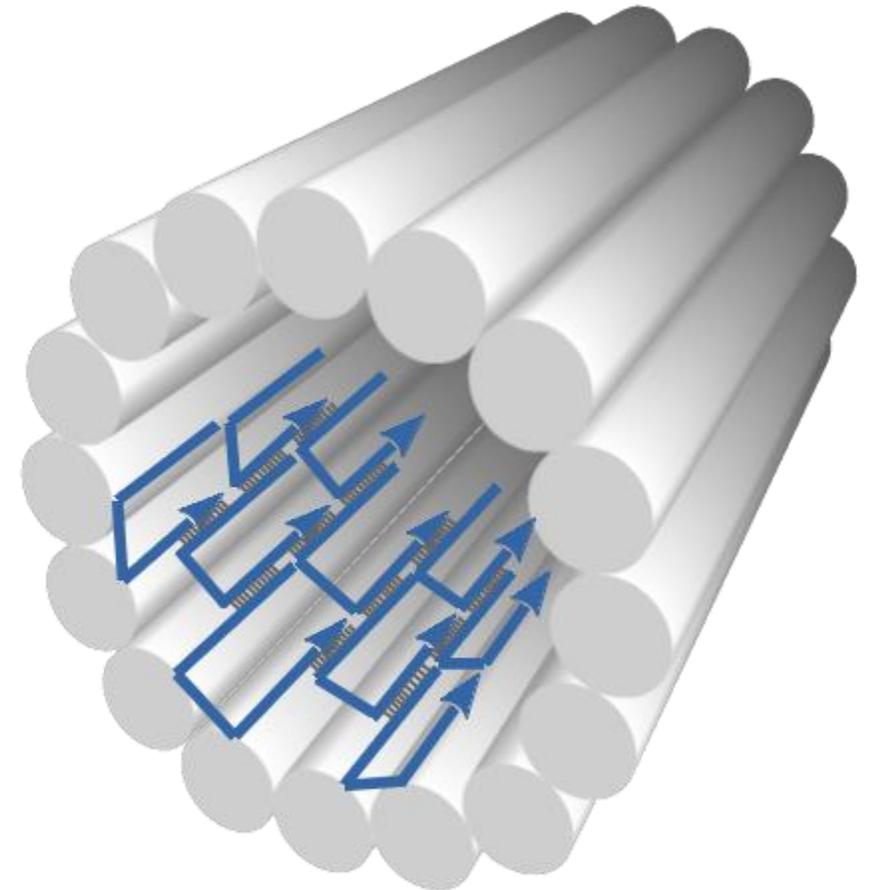


tile for position (4,2)

Single-stranded tile tubes



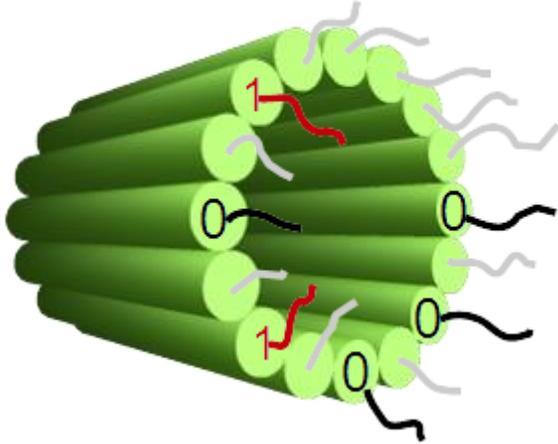
DNA-level diagram of 20-helix tube



Seeded growth

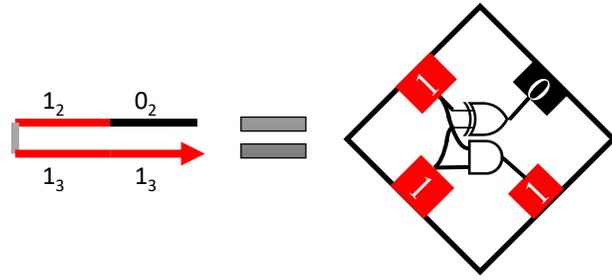
DNA origami seed

single-stranded "input-adapter"
extensions encoding 6 input bits

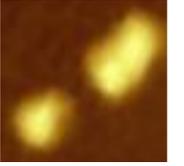


need barrier to nucleation
(tile growth without seed);
[tile]=100 nM;
temperature=50.9° C

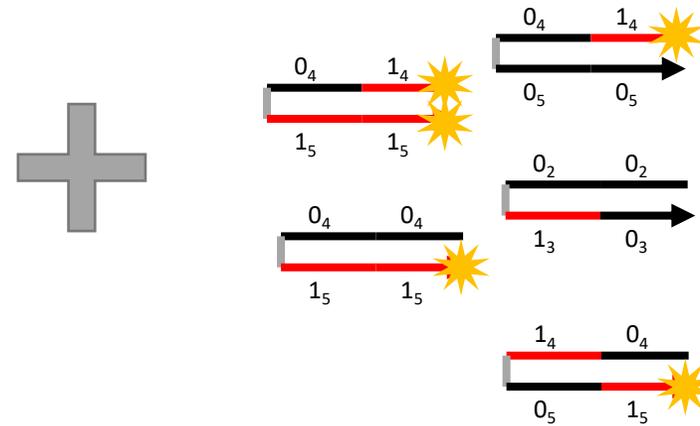
hold 8-48 hours
→



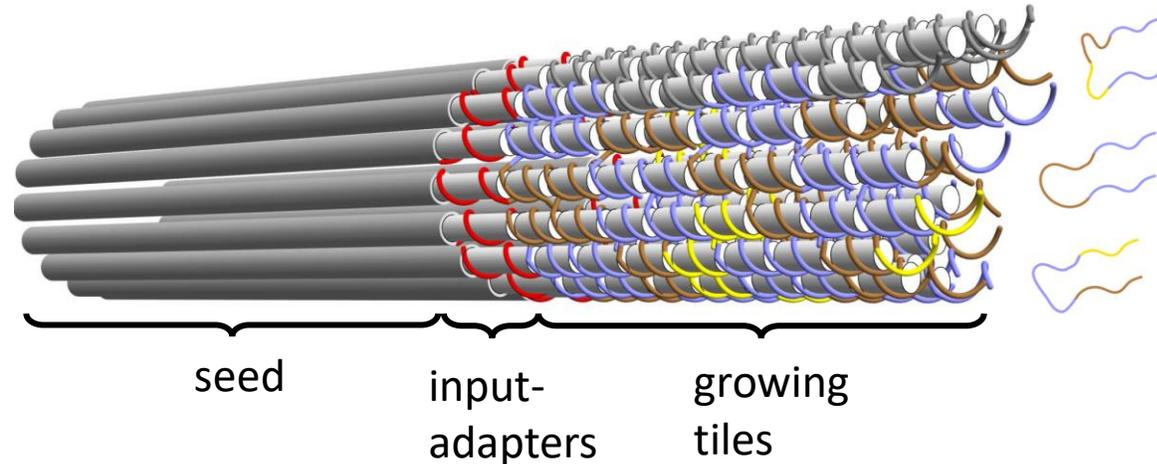
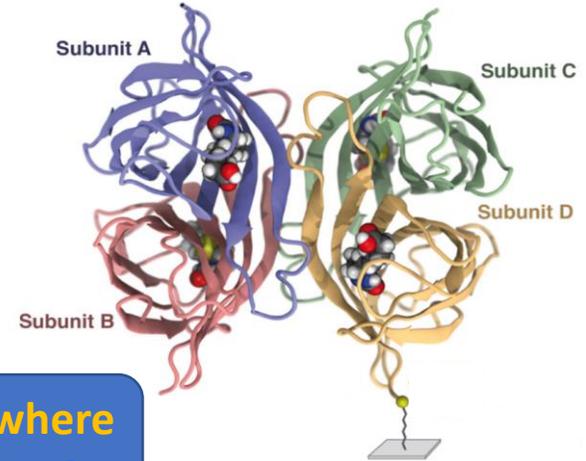
can later add streptavidin (5 nm wide protein) to bind biotins and visualize where the 1's are



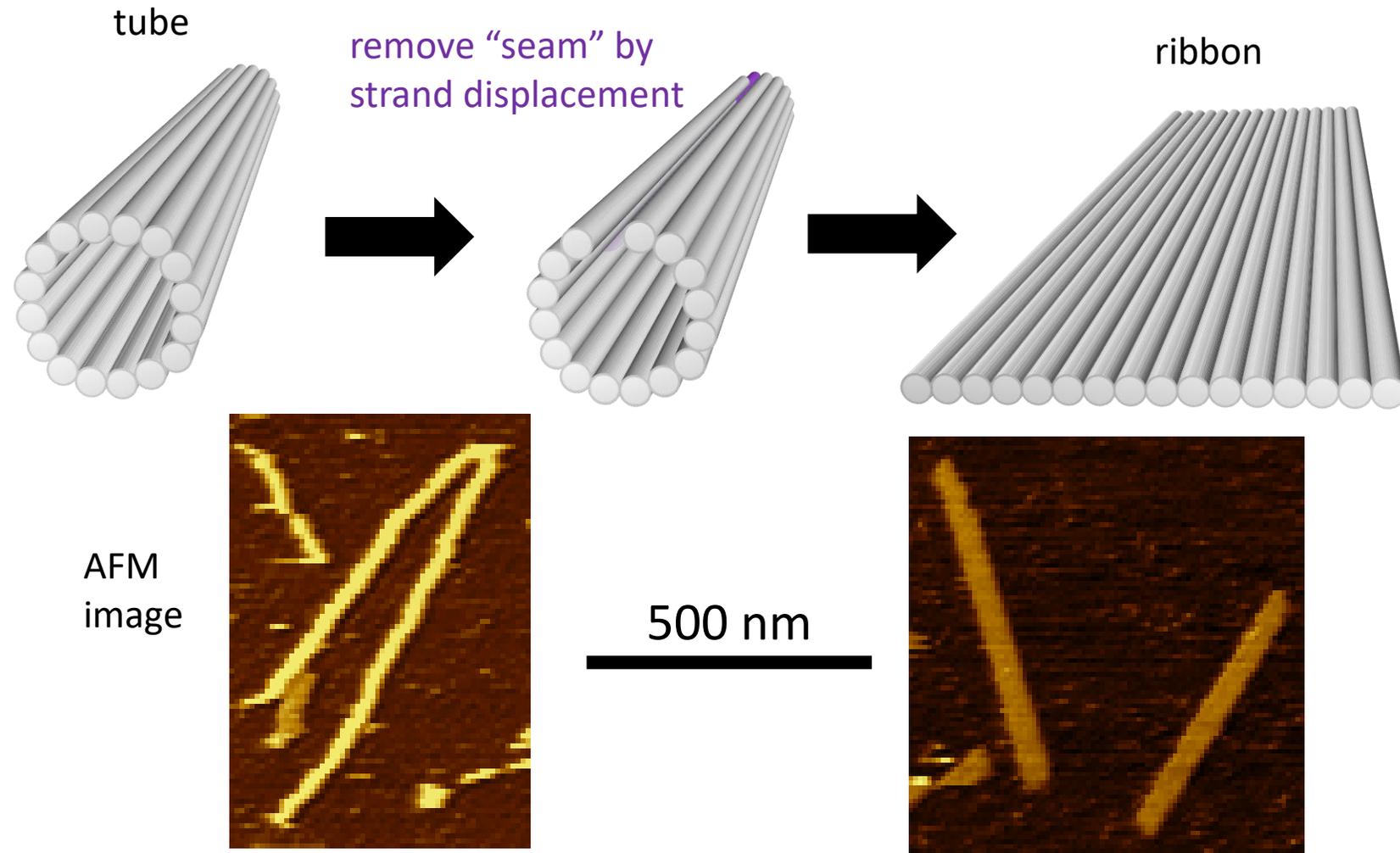
single-stranded tiles
implementing circuit gates



biotins where
output = 1



Tubes to ribbons

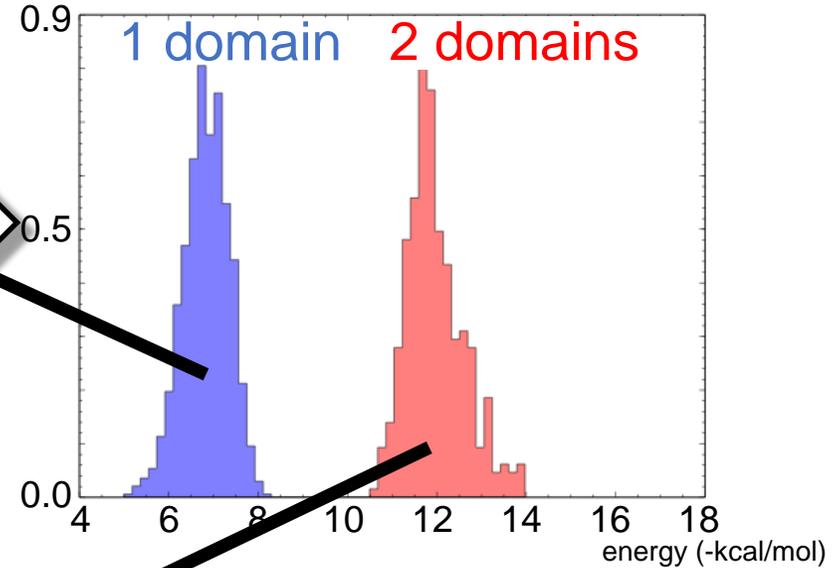
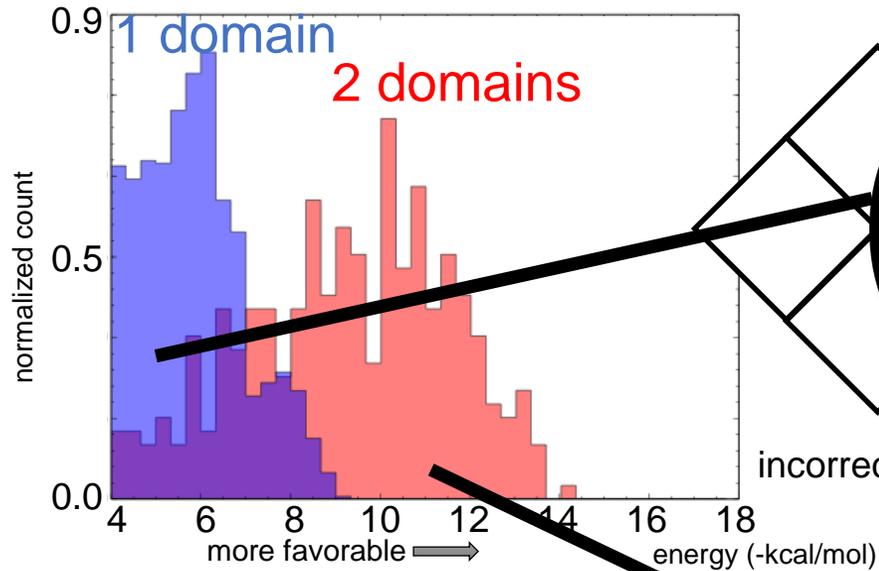


DNA sequence design

Random sequences

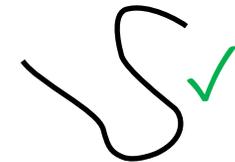
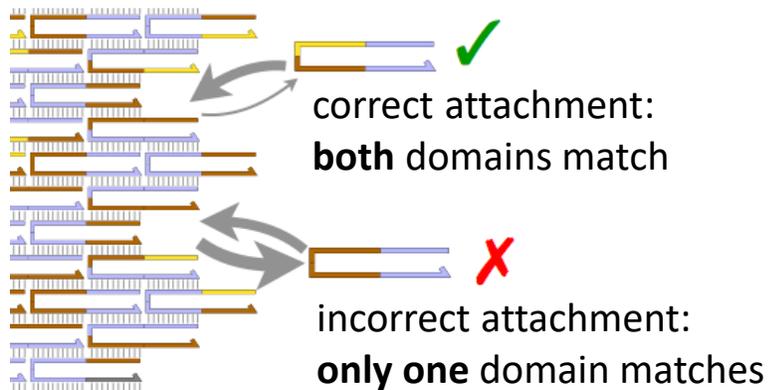
vs

designed sequences



incorrect binding

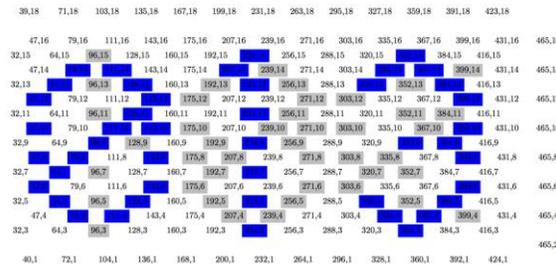
correct binding



Other goals:

- low strand secondary structure
- low interaction between strands

Bar-coding origami seed for imaging multiple samples at once



some staples of origami seed have version with a biotin

Generate plate map



```

*****
* pos3su, coding staples, no biotin (14 staples)
16H barrel stap 2
1 2 3 4 5 6 7 8 9 10 11 12
A
B
C
D
E
F
G
H
*****
pos3su, coding staples, biotin (16 staples)
16H 2bit biotin staples | unzippers2 + biotin_staples_2_3
1 2 3 4 5 6 7 8 9 10 11 12 | 1 2 3 4 5 6 7 8 9 10 11 12
A
B
C
D
E
F
G
H
*****
    
```

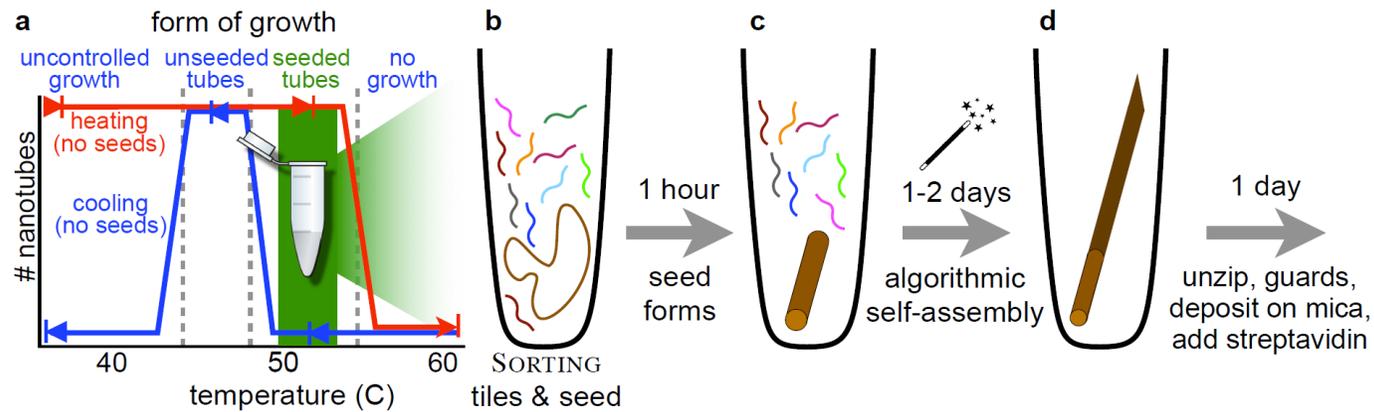
represents some combination of circuit and input, e.g.,
013 = "parity circuit, input=011010"



label with streptavidin



Experimental protocol

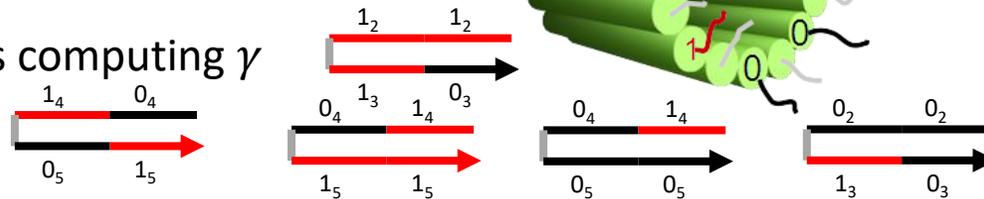


To execute circuit γ on input $x \in \{0,1\}^*$:

- Mix
 - origami seed (bar-coded to identify γ and x)

- “adapter” strands encoding x

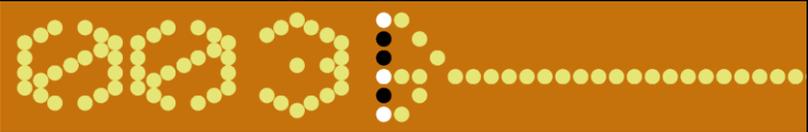
- tiles computing γ



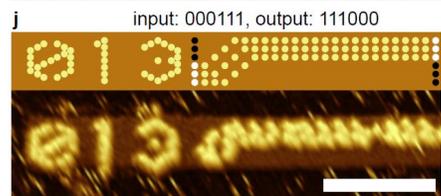
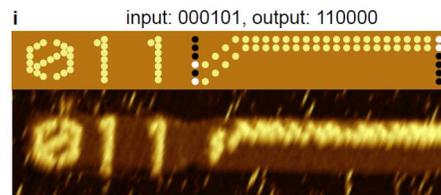
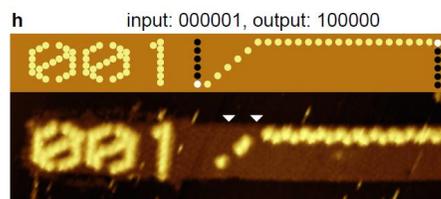
- Anneal 90°C to 50.9°C in 1 hour (*origami seeds form*)
- Hold at 50.9°C for 1-2 days (*tiles grow tubes from seed*)
- Add “unzipper” strands (remove seam to convert tube to ribbon)
- Add “guard” strands (complements of output sticky ends, to deactivate tiles)
- Deposit on mica, buffer wash, add streptavidin, AFM



Results

```
def test_parity():  
    actual = parity('100101')  
    expected =   
    assertEquals(expected, actual)
```

SORTING



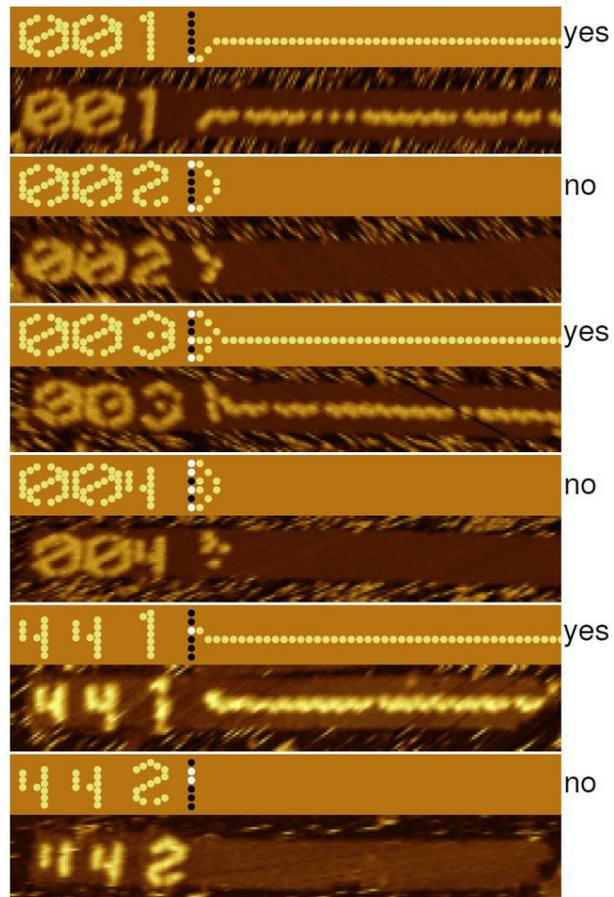
100 nm

COPY



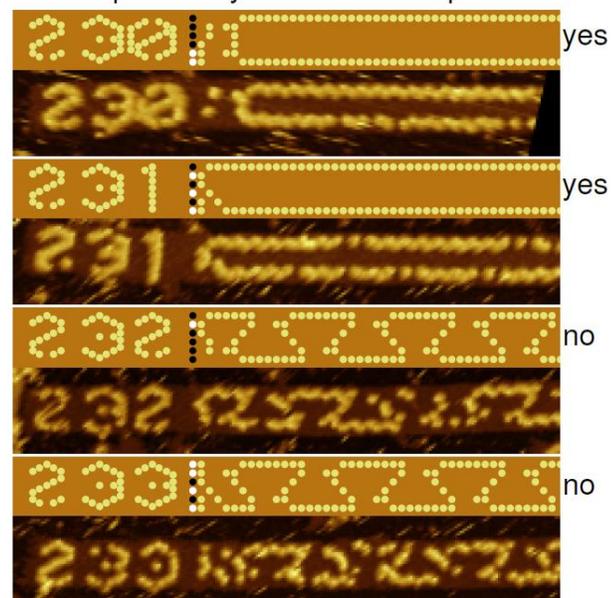
PARITY

Is the number of 1's odd?



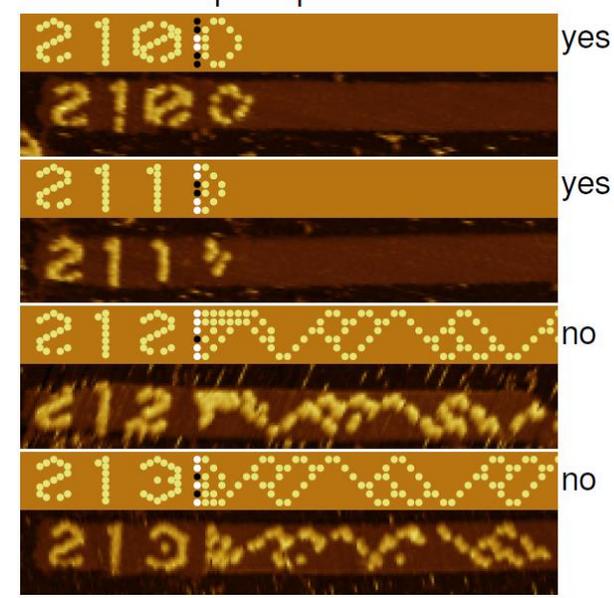
MULTIPLEOF3

Is the input binary number a multiple of 3?



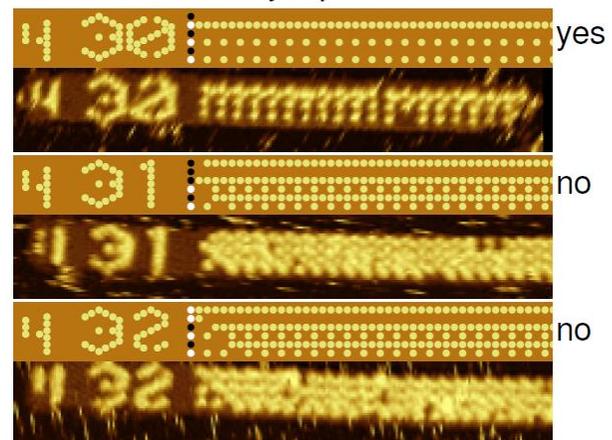
PALINDROME

Is the input a palindrome?



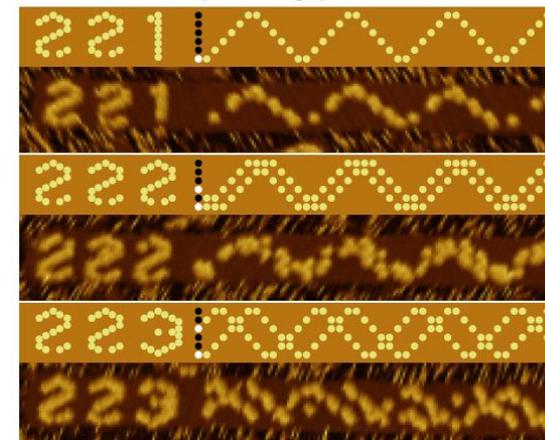
RECOGNISE21

Is the binary input = 21?

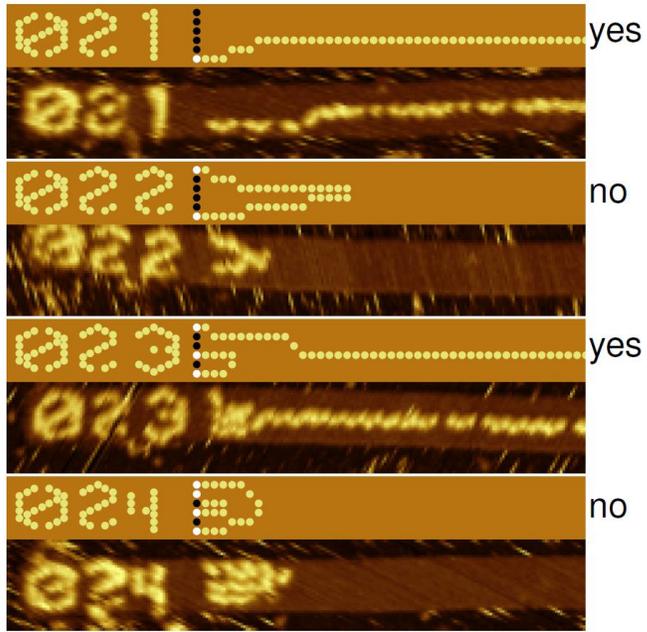


ZIG-ZAG

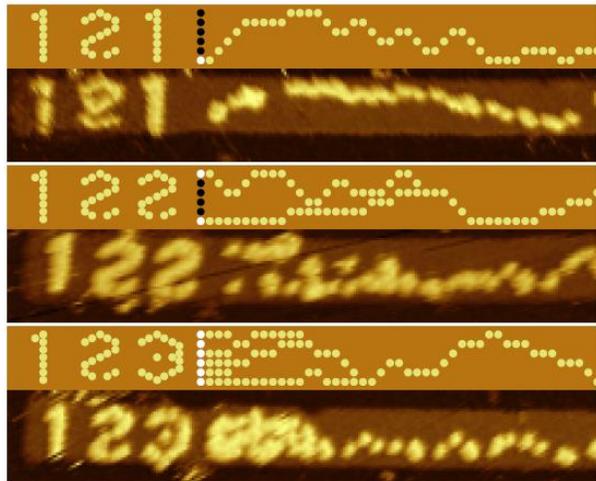
Repeating pattern



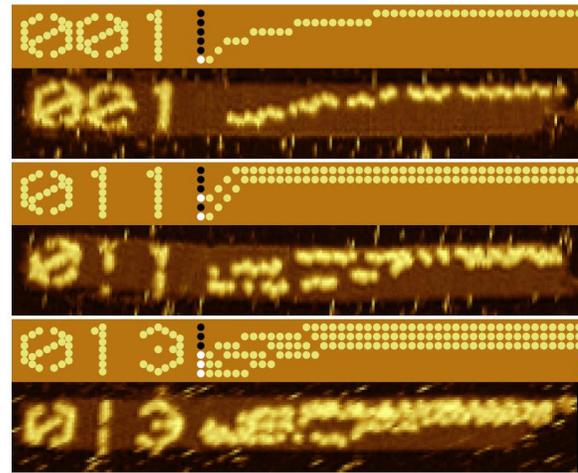
LAZYPARITY



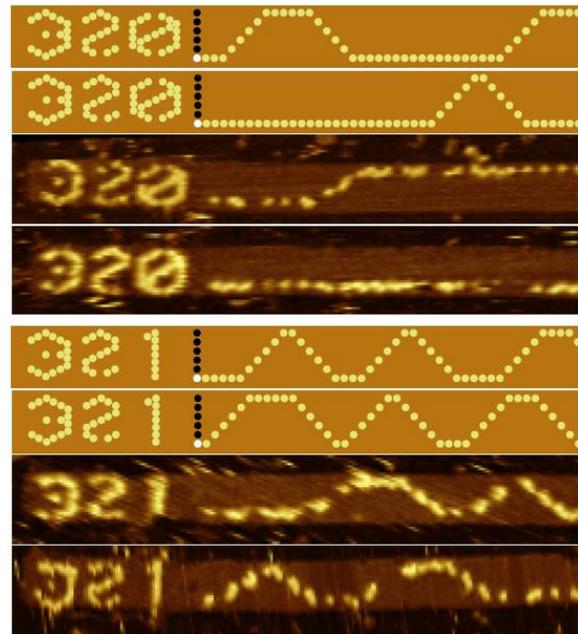
LEADERELECTION



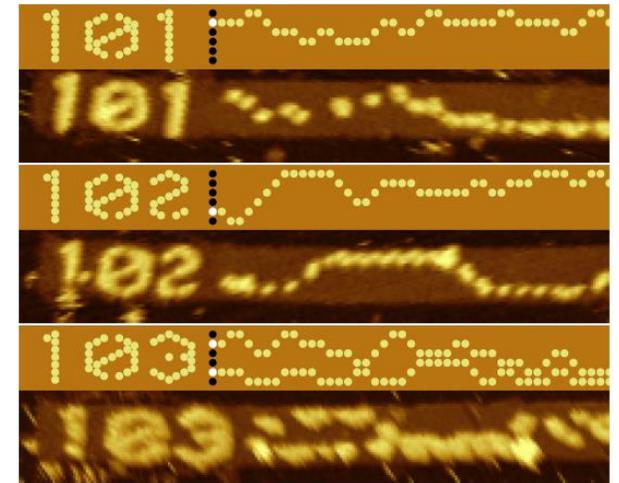
LAZYSORTING



WAVES

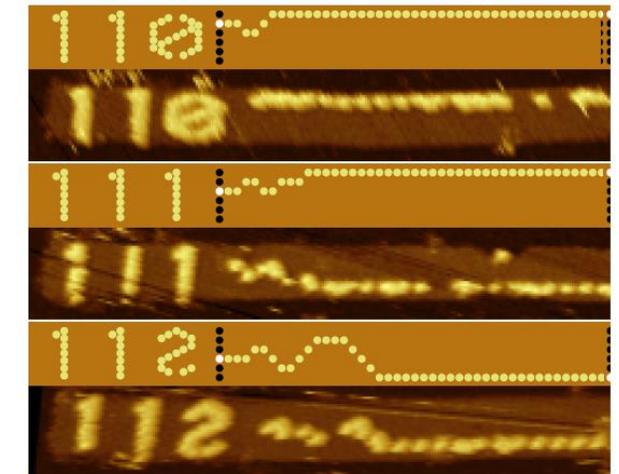


RANDOMWALKINGBIT



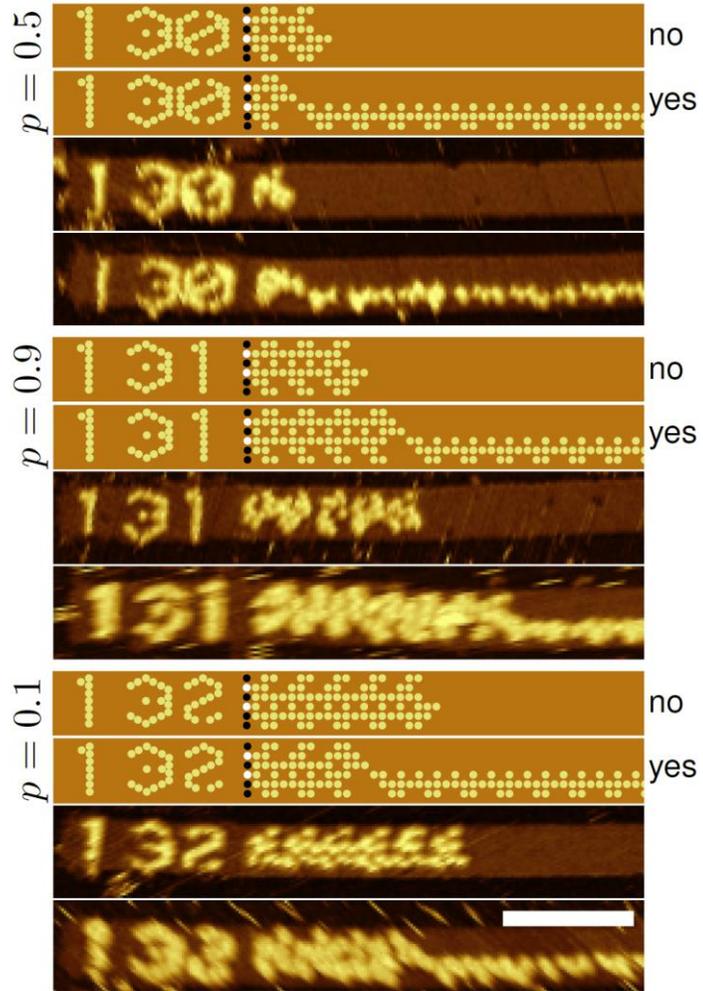
ABSORBINGRANDOMWALKINGBIT

Random walker absorbs to top/bottom



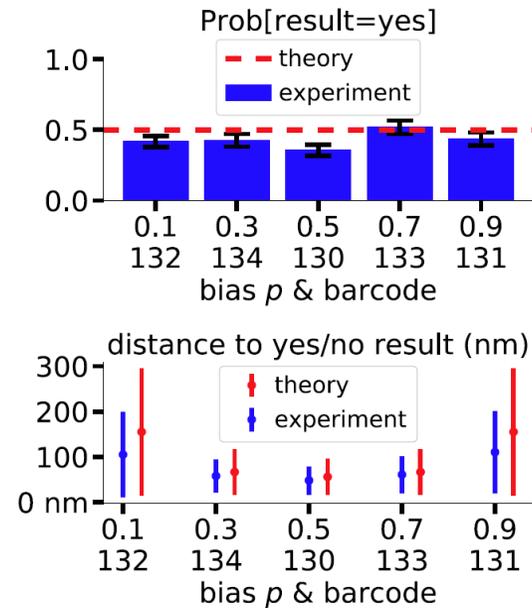
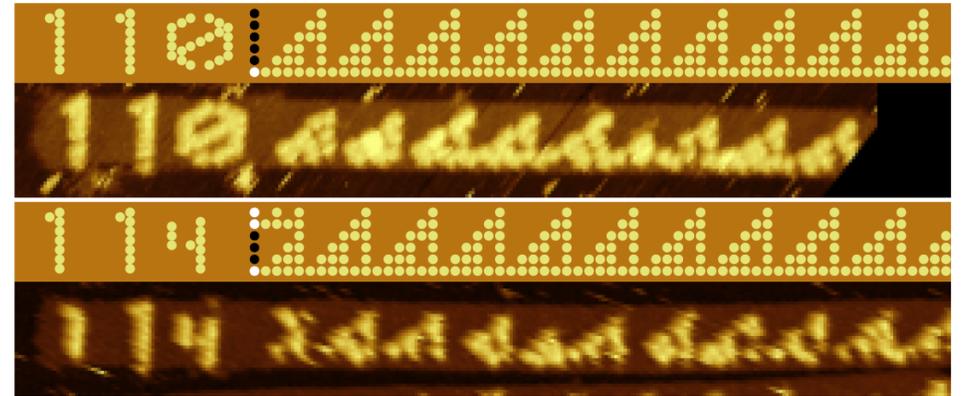
FAIRCOIN

Unbiasing a biased coin



RULE110

Simulation of a cellular automaton



Counting to 63

Circuit with 63 distinct strings



Is there a 64-counter?

No!

Proof by Tristan Stérin, Maynooth University

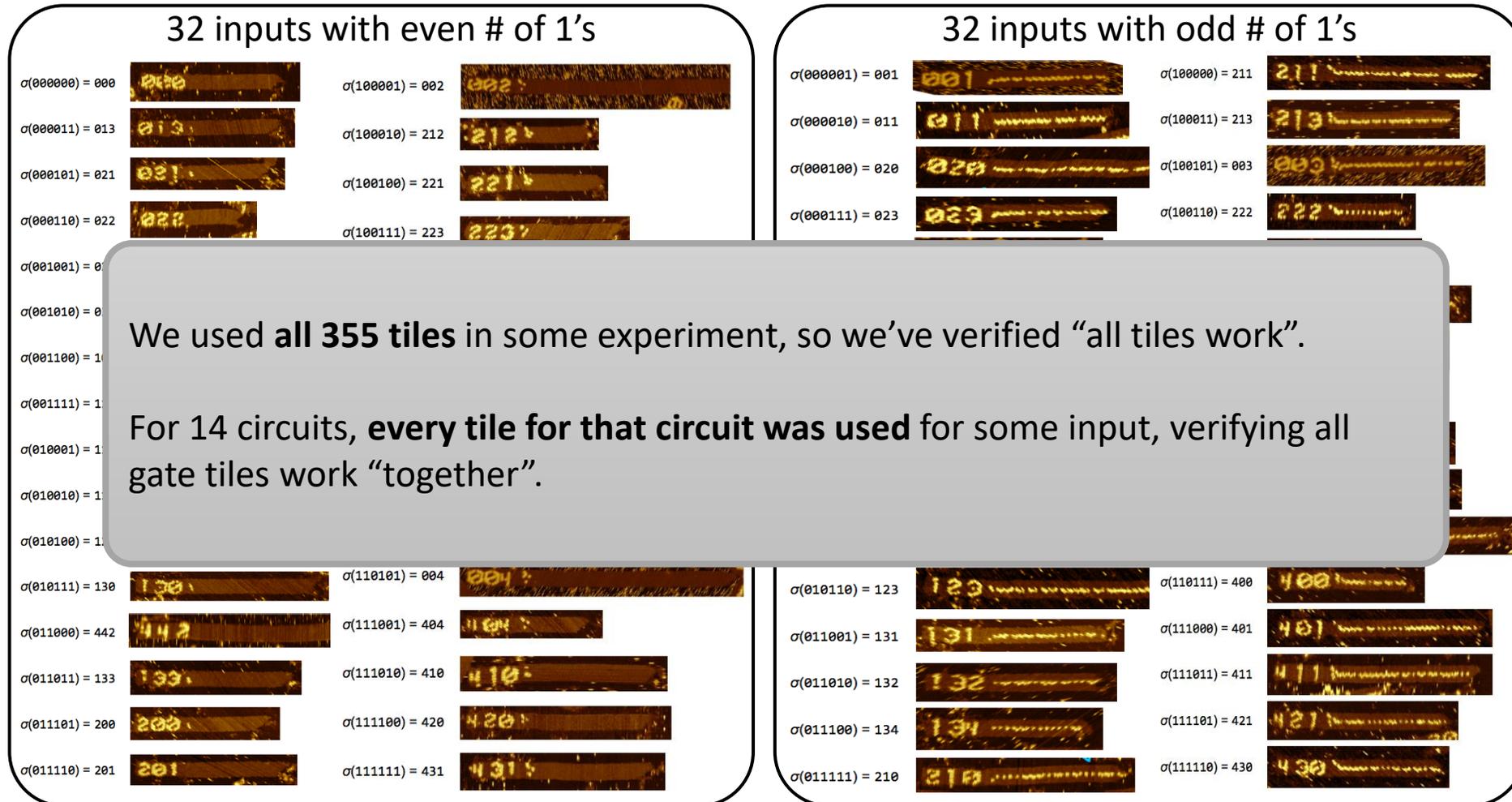
Consequence of following theorem:

No Boolean function computes an odd permutation if some output bit does not depend on all input bits.



Parity tested on all inputs

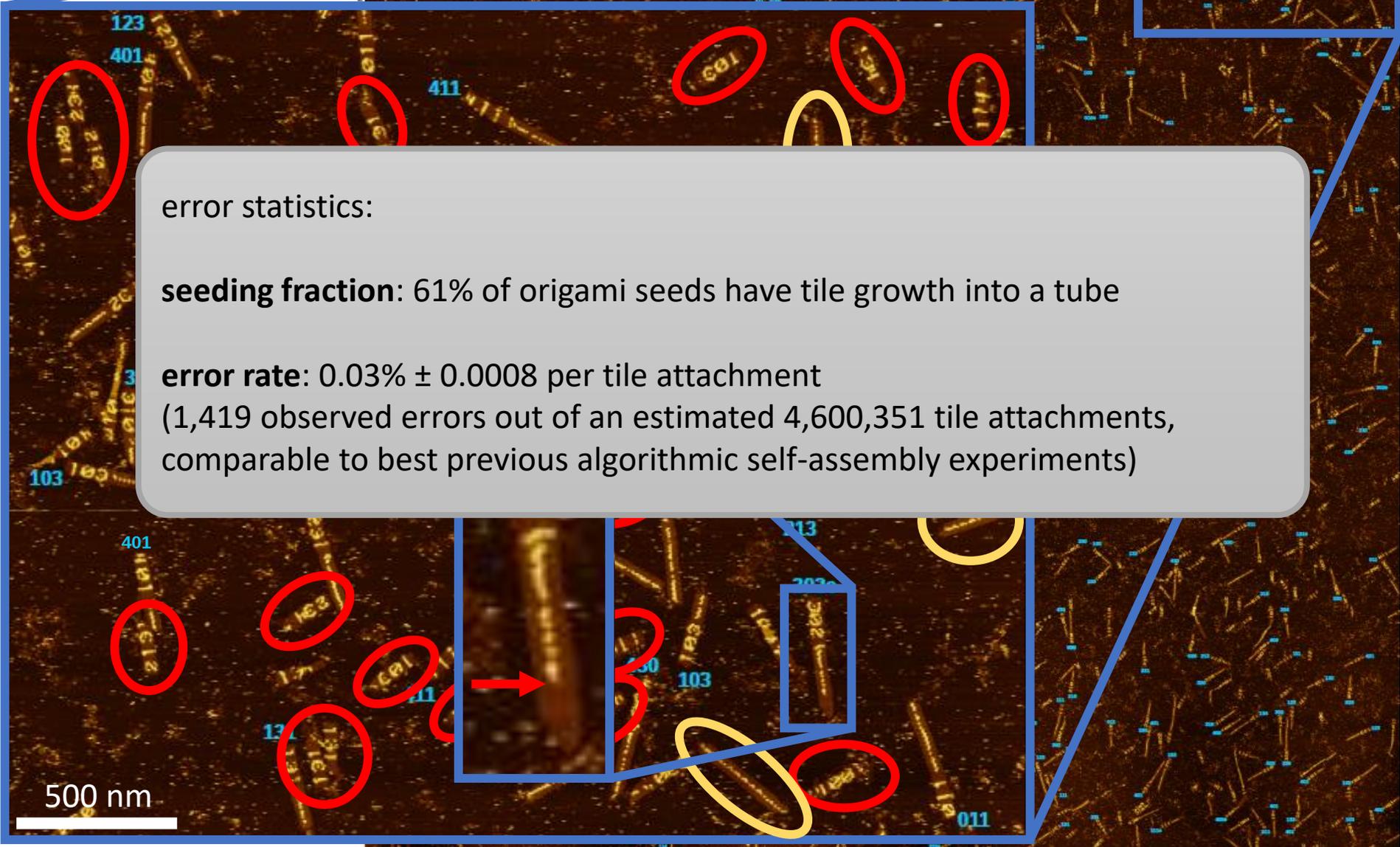
$2^6 = 64$ inputs with 6 bits



$\sigma(6\text{-bit input}) = 3\text{-digit barcode representing that input}$

150 nm

12 μm AFM image of parity ribbons for several inputs whose output is 1

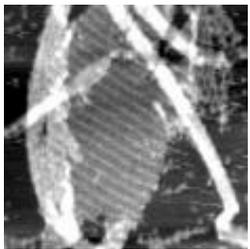


What did we learn?

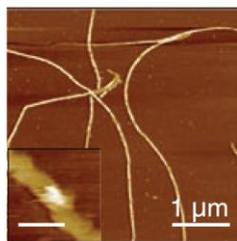
A small(ish) library of molecules can be reprogrammed to self-assemble reliably into many complex patterns, by processing information as they grow.

Contrasting with other self-assembly work:

more algorithmic control
than **periodic** self-assembly

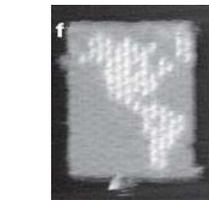


2D tile lattices
(Winfree et al.,
Nature 1998)



1D tile tubes
(Yin et al.,
Science 2008)

fewer types of DNA strands
required than **uniquely-**
addressed self-assembly



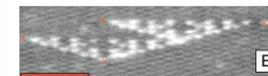
DNA origami
(Rothemund,
Nature 2006)



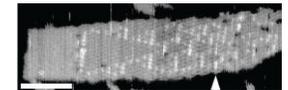
hard-coded tile
lattice (Wei et al.,
Nature 2012)

order of magnitude more tile
types available than previous
algorithmic self-assembly

double-crossover tile lattices



(Rothemund et al.,
PLoS Bio 2004)



(Fujibayashi et al.,
Nano Letters 2008)



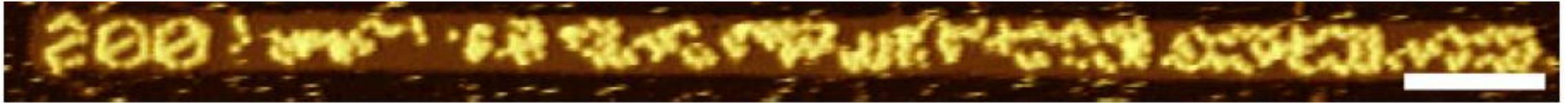
(Barish et al., *PNAS*
2009)



(Evans, *Ph.D. thesis*
2014)

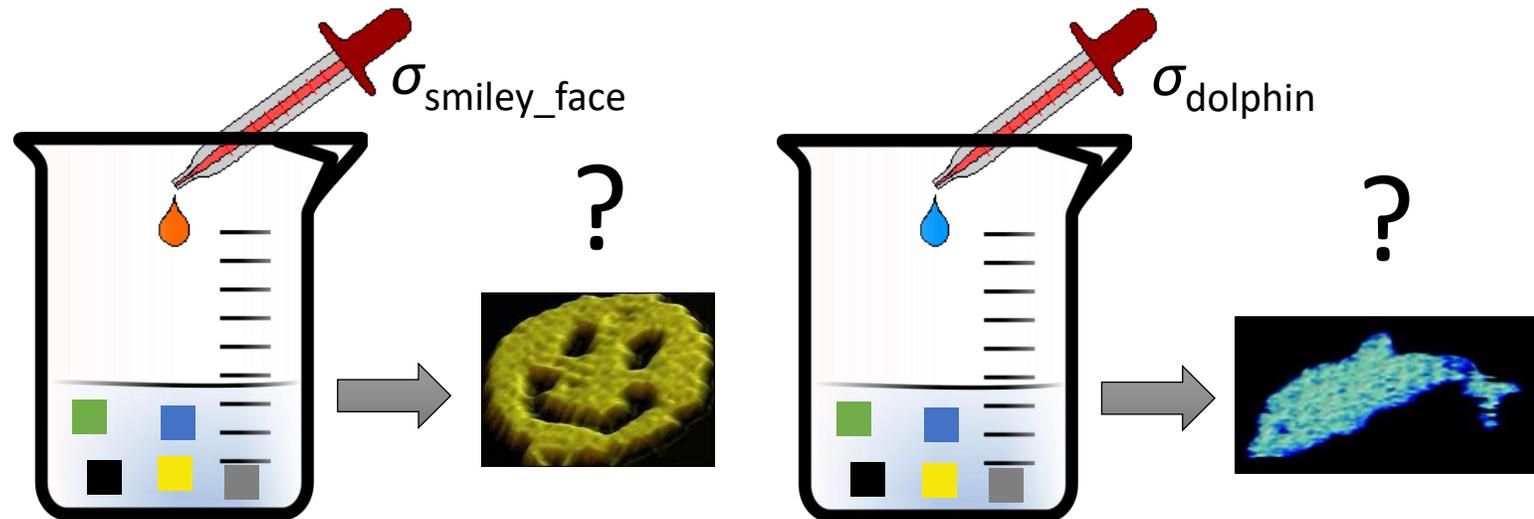
Next big challenge: Algorithmically control shape

We “drew” interesting patterns on a boring shape (infinite rectangle)



Can we run algorithms to **grow interesting shapes**?

Theorem: There is a single set T of tile types, so that, for any finite shape S , from an appropriately chosen seed σ_S “encoding” S , T self-assembles S .



These tiles are **universally programmable** for building any shape.