### The computational power of execution bounded chemical reaction networks

David Doty, Ben Heckmann

#### May 2024 Seminar on the Mathematics of Reaction Networks





#### Acknowledgments

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Matthias Köppe Professor UC Davis



For teaching us about "Theorems of the Alternative"

#### Chemical reaction networks

#### Chemical reaction networks reactant(s) $R \rightarrow P_1 + P_2$ product(s)

## $\begin{array}{ll} \mbox{Chemical reaction networks} \\ \mbox{reactant(s)} & R \rightarrow P_1 + P_2 & \mbox{product(s)} \\ \mbox{monomers} & M_1 + M_2 \rightarrow D & \mbox{dimer} \end{array}$

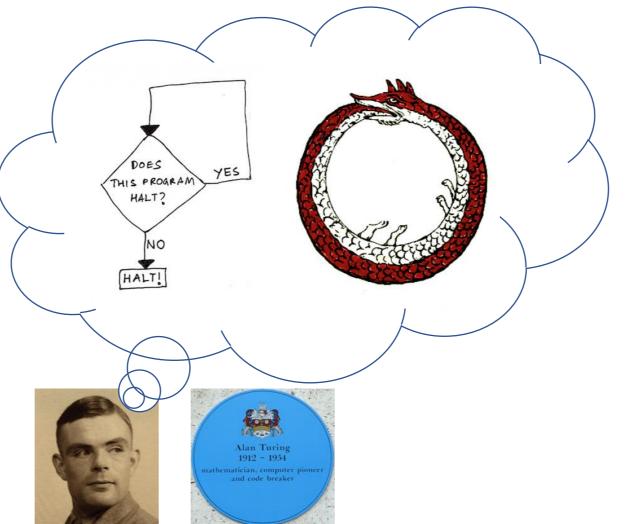
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# Chemical reaction networksreactant(s) $R \rightarrow P_1 + P_2$ product(s)monomers $M_1 + M_2 \rightarrow D$ dimercatalyst $C + X \rightarrow C + Y$

Traditionally a descriptive modeling language... Let's instead use it as a prescriptive programming language

#### Theoretical computer science approach





What computation is possible and what is not?

#### Outline

#### • Formal definition of chemical reaction networks

- Execution bounded chemical reaction networks and linear potential functions
- What is "computation" with chemical reactions?
- Limitations of computation with execution bounded chemical reaction networks

#### Chemical Reaction Network (CRN)

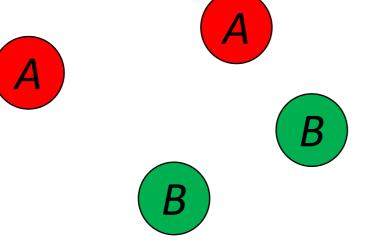
• finite set of d <u>species</u>  $\Lambda = \{A, B, C, D, ...\}$ 

• finite set of <u>reactions</u>: e.g.  $A+B \rightarrow A+C$  $C \rightarrow A+A$  $C+B \rightarrow C$ 



#### What is **possible**: Example execution (reaction sequence) A B C $A+B \rightarrow A+C$ α: $C \rightarrow A + A$

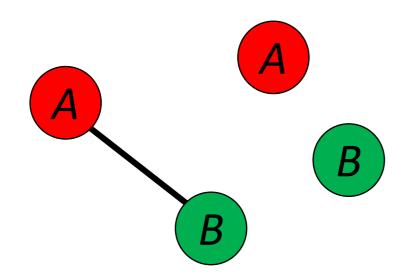
β: A x = (2, 2, 0)



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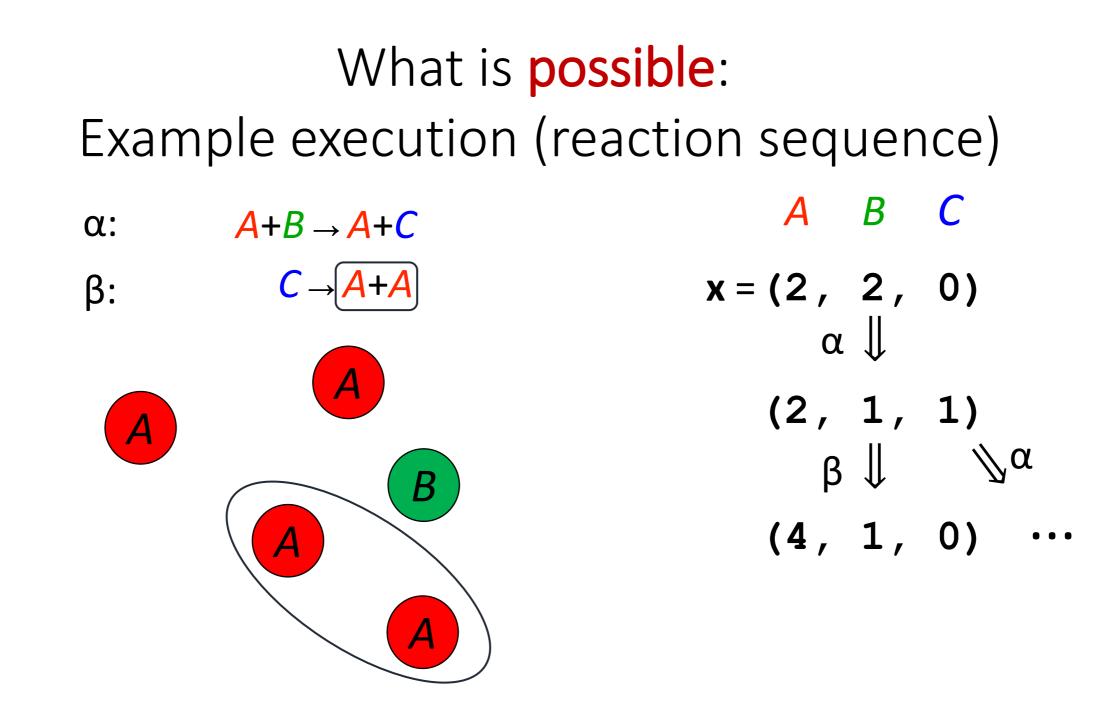
 $\alpha: \qquad \boxed{A+B} \rightarrow A+C$  $\beta: \qquad C \rightarrow A+A$ 

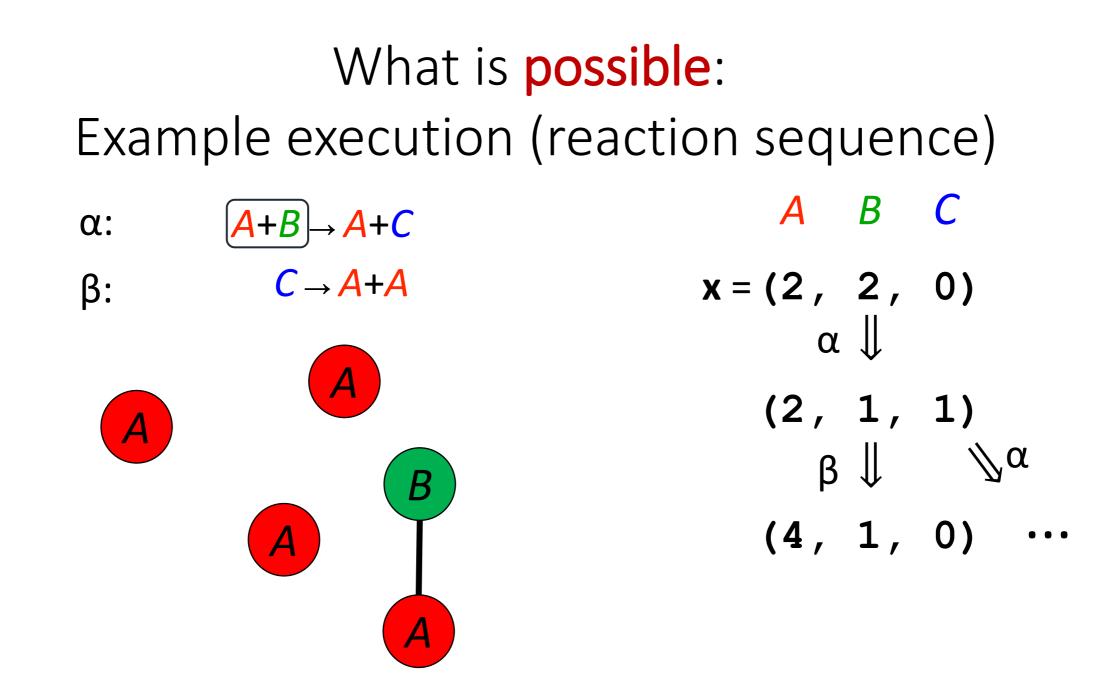
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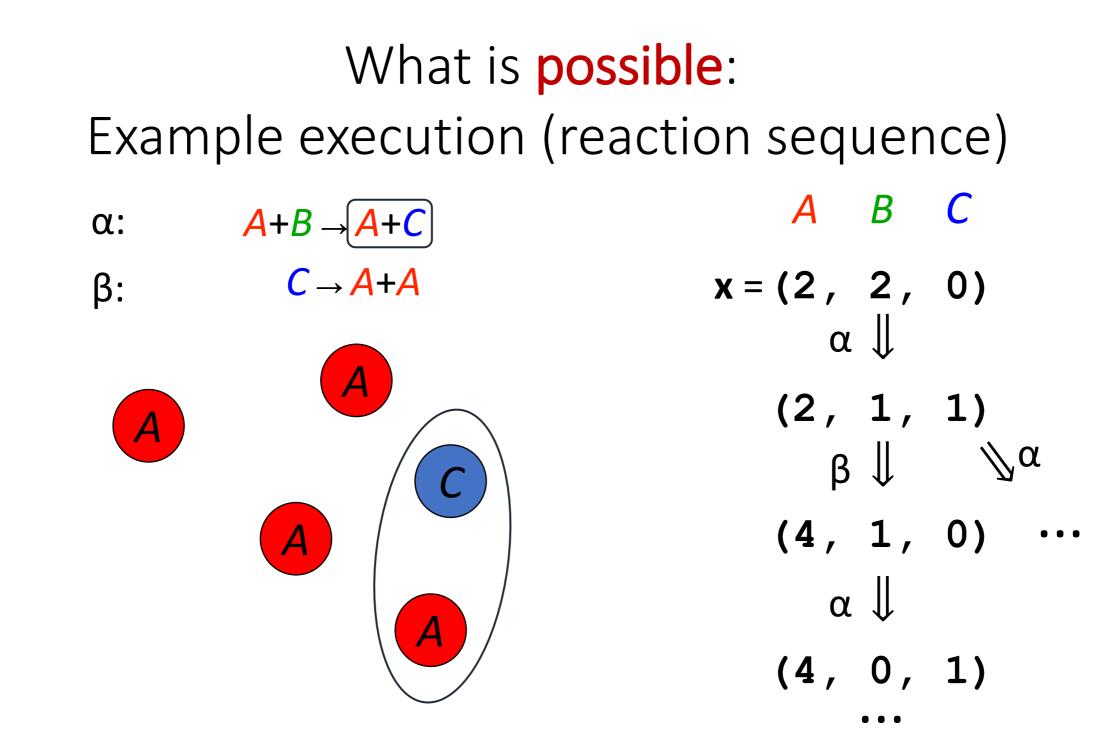


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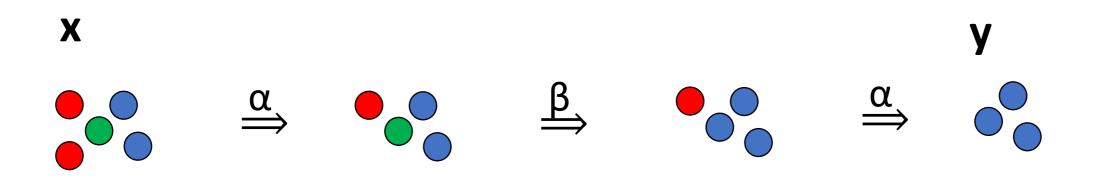


If we can reach from state **x** to **y**, written  $\mathbf{x} \Rightarrow \mathbf{y}$ , then for all  $\mathbf{c} \in \mathbb{N}^d$ ,  $\mathbf{x}+\mathbf{c} \Rightarrow \mathbf{y}+\mathbf{c}$ 

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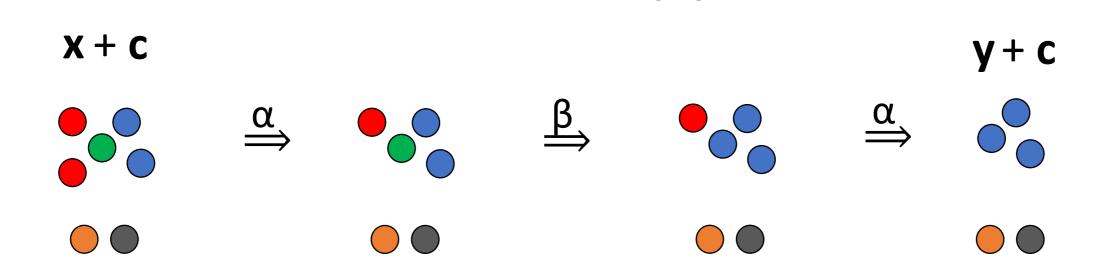


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  - $\mathbf{x} \leq \mathbf{y}$ :  $\mathbf{x}(i) \leq \mathbf{y}(i)$  for  $1 \leq i \leq d$
  - $\mathbf{x} \leq \mathbf{y}$ :  $\mathbf{x} \leq \mathbf{y}$  and  $\mathbf{x} \neq \mathbf{y}$
  - $\mathbf{x} < \mathbf{y}$ :  $\mathbf{x}(i) < \mathbf{y}(i)$  for  $1 \le i \le d$
  - If  $\mathbf{x} \ge \mathbf{0}$ ,  $\mathbf{x}$  is **nonnegative**.
  - If  $x \ge 0$ , x is semipositive.
  - If **x** > **0**, **x** is **positive**.

 $(1,2) \leq (1,2)$  $(1,2) \leq (1,4)$ (1,2) < (3,4)

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#### Execution bounded CRNs

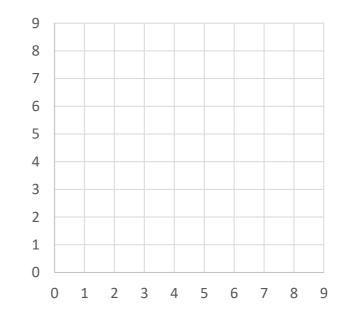
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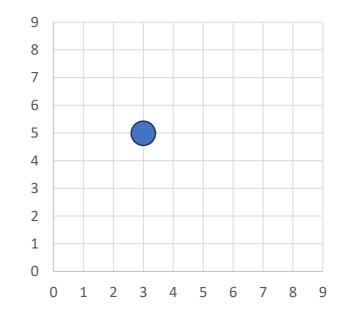
- <u>Definition</u>: A CRN C is execution bounded from state x if all executions starting at x are finite.
- Why prefer execution bounded CRNs?
  - Wet lab implementations of CRNs use up "fuel" to execute reactions; execution bounded CRNs limit the amount of fuel needed
  - Easier to reason about: as long as reactions keep happening, they make "progress" towards reaching a final state.

<u>Easy Lemma</u>: CRN *C* is <u>not</u> execution bounded from  $\mathbf{x}_0$  if and only if there <u>is</u> an execution ( $\mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2, ...$ ) that is **self-covering**:  $\mathbf{x}_i \leq \mathbf{x}_k$  for some i < k.

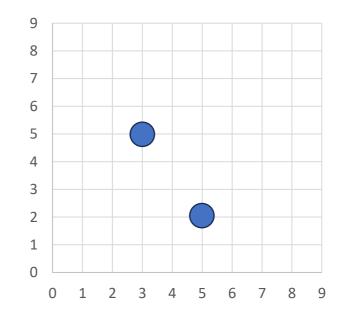
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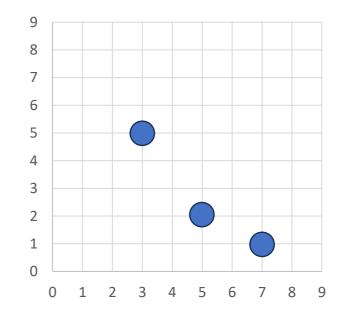
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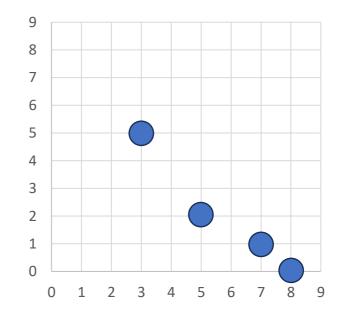
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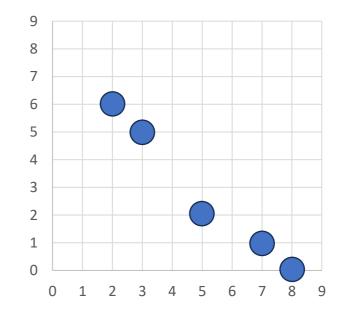
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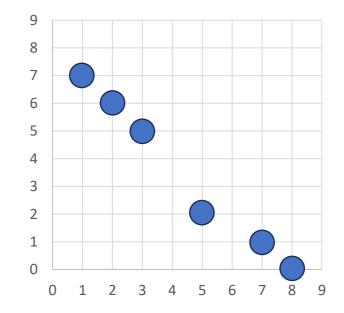
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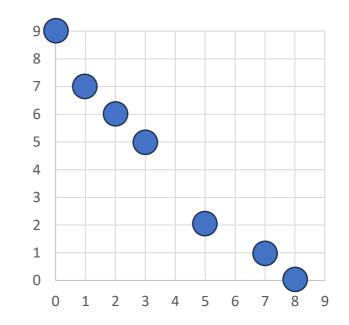
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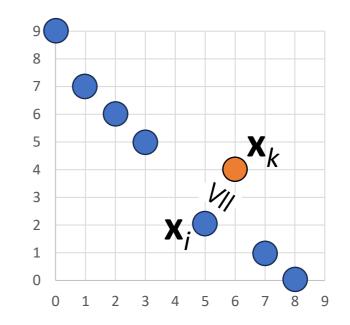
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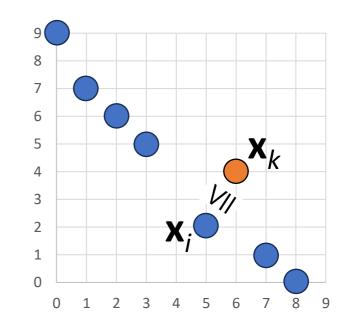


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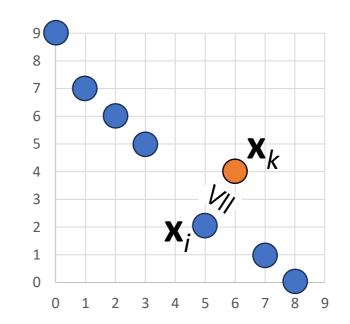
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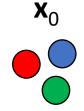
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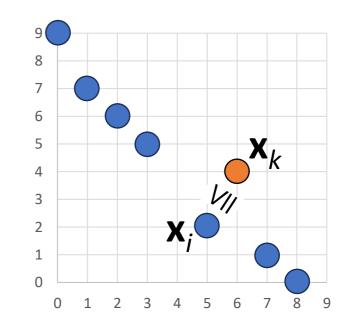
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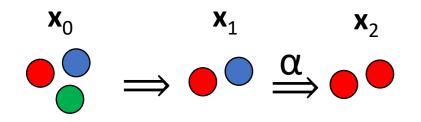
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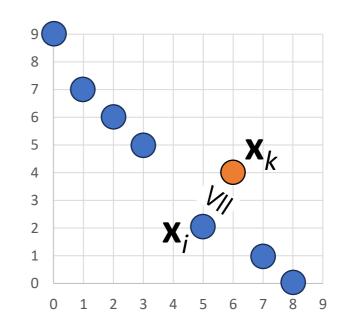
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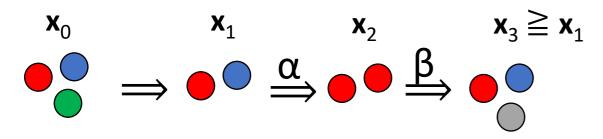
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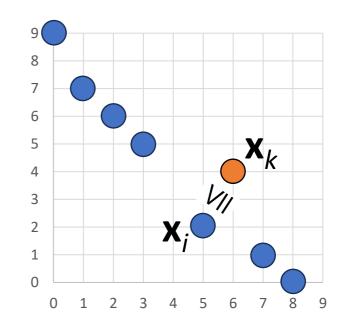




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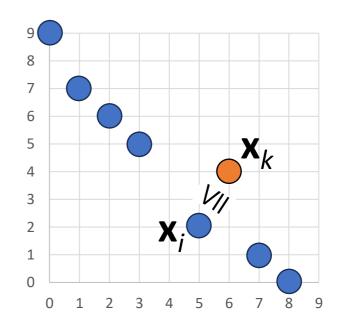
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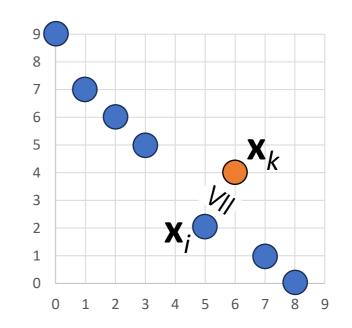
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- By clearing denominators, we can assume each v<sub>s</sub> is an integer, so each reaction decreases Φ by at least 1.

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Forward direction is easy: Since each reaction reduces  $\Phi$  by at least 1, at most  $\Phi(\mathbf{x})$  reactions are possible from any state  $\mathbf{x}$ .

<u>Theorem:</u> (Gale 1960) *"Theorem of the Alternative"* (similar to Farkas' Lemma): Let **M** be a matrix. Then exactly one of the following statements is true:

- 1. There is a vector  $\mathbf{u} \ge \mathbf{0}$  such that  $\mathbf{Mu} \ge \mathbf{0}$ .
- 2. There is a vector  $\mathbf{v} \ge \mathbf{0}$  such that  $\mathbf{vM} < \mathbf{0}$ .

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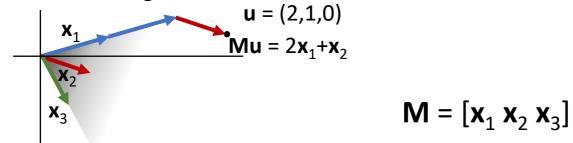


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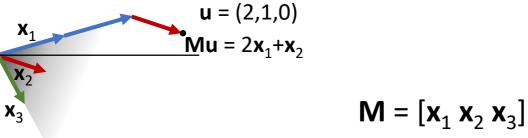


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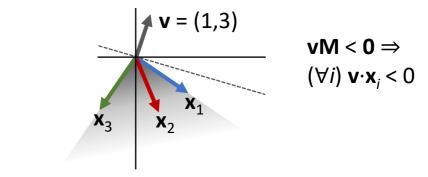
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1. Either the cone of **M**'s column vectors intersects the nonnegative orthant:



2. Or it doesn't, and then some hyperplane (dashed line) separates that cone from the nonnegative orthant:



Let **M** be the stoichiometric matrix, e.g.  $\alpha \quad \beta$   $\alpha: A \rightarrow B + 2C$   $\beta: 3B + C \rightarrow A + B + C$   $M = \begin{pmatrix} -1 & 1 \\ 1 & -2 \\ 2 & 0 \end{pmatrix} \begin{pmatrix} A \\ B \\ C \end{pmatrix}$ 

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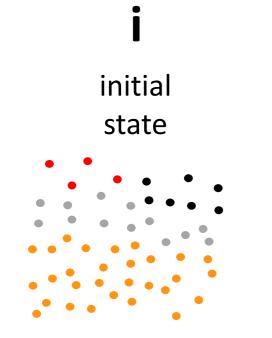
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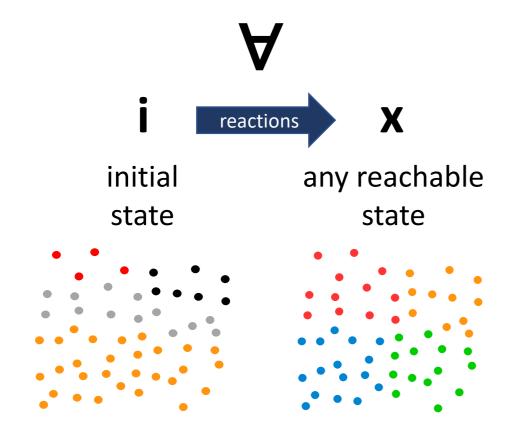
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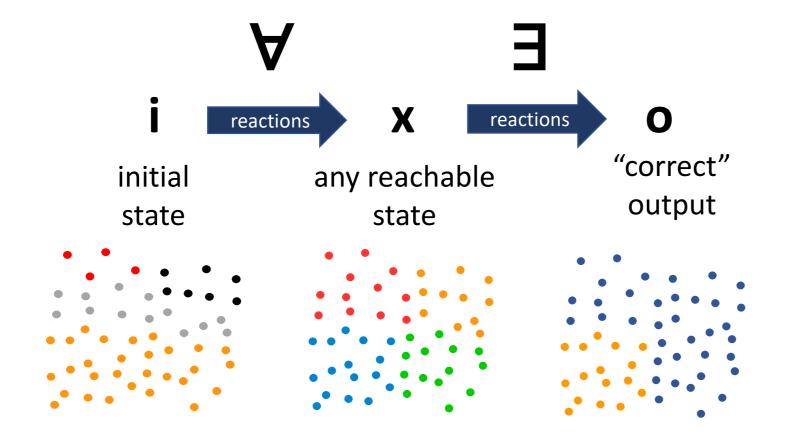
Then there <u>is</u> a vector  $\mathbf{v} \ge \mathbf{0}$  such that  $\mathbf{vM} < \mathbf{0}$ . Let  $\mathbf{v}$  be the coefficients of a linear function  $\Phi(\mathbf{x}) = \mathbf{v} \cdot \mathbf{x}$ . Then  $\mathbf{vM} < \mathbf{0}$  means each reaction decreases  $\Phi$ : it is a linear potential function. QED

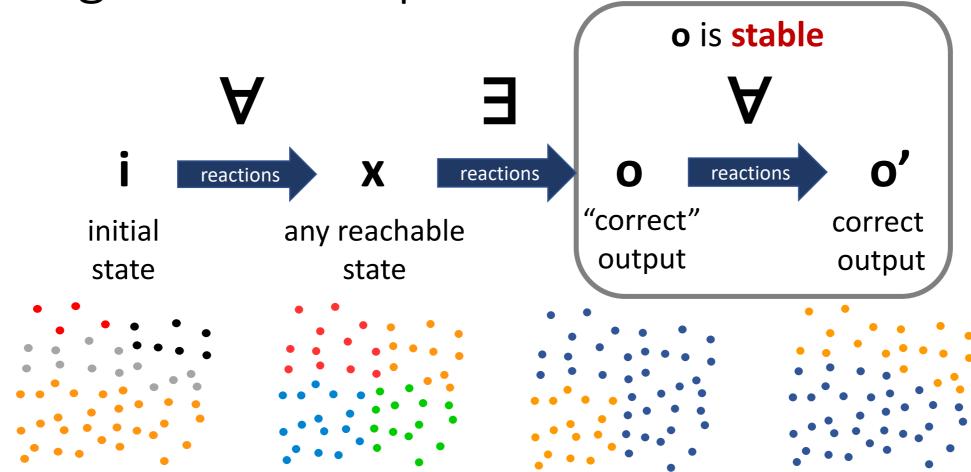
### Outline

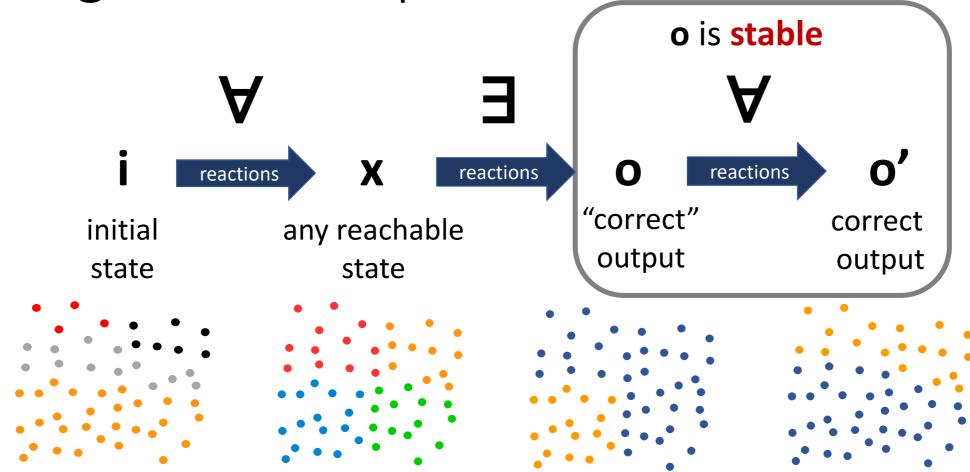
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(assuming finite set of reachable states) equivalent to: The system <u>will</u> reach the correct output with probability 1.

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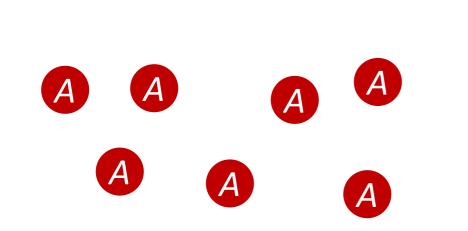
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- **o** is stable if  $\psi(\mathbf{o}) = \psi(\mathbf{o'})$  for all **o'** reachable from **o**

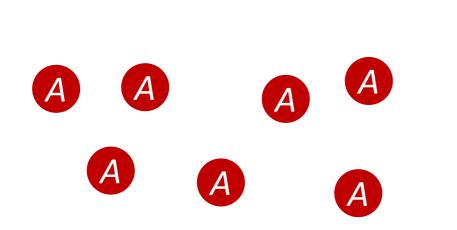
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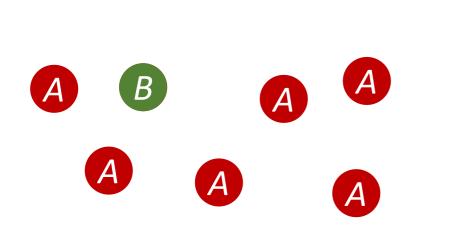
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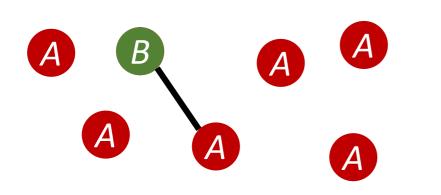
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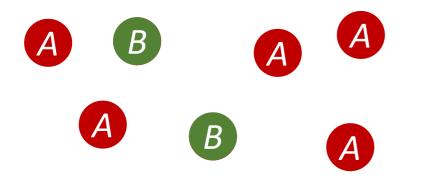
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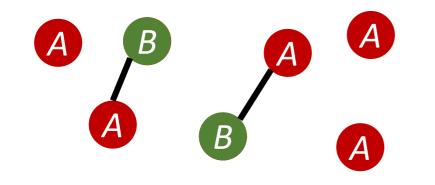
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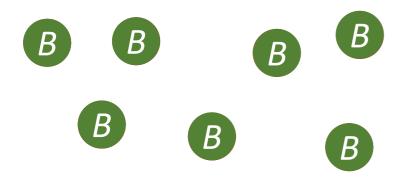
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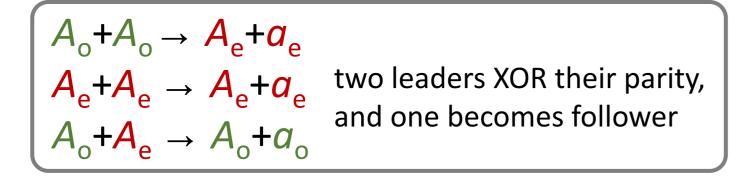
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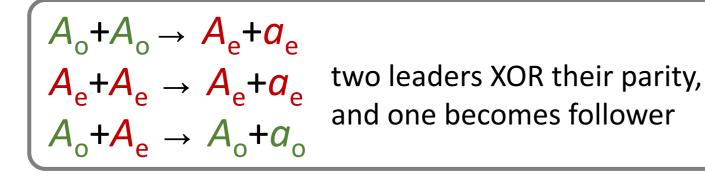
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#### Not execution bounded!

#### Limits of stable computation

<u>Theorem</u>:  $\varphi$ :  $\mathbb{N}^k \rightarrow \{Y, N\}$  is stably computable by a CRN if and only if  $\varphi$  is *semilinear*. semilinear = Boolean combination of <u>threshold</u> and <u>mod</u> predicates:

```
take weighted sum s = w_1 \cdot a_1 + \dots + w_k \cdot a_k of inputs and ask if
```

- *s* > constant *c*?
- $s \equiv c \mod m$  for constants c,m?

a>b?	) a	=b?	<i>a</i> is odd?	a>1?	<i>a</i> >1 and <i>b</i> is	odd?
	NOT	$a=b^2$ ?	a is a po	wer of 2?	a is prime?	

[Angluin, Aspnes, Diamadi, Fischer, Peralta, Computation in networks of passively mobile finite-state sensors, *PODC* 2004] [Angluin, Aspnes, Eisenstat, Stably computable predicates are semilinear, *PODC* 2006]

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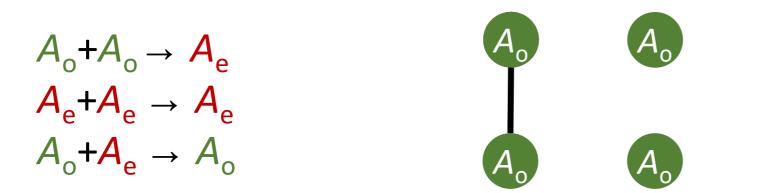
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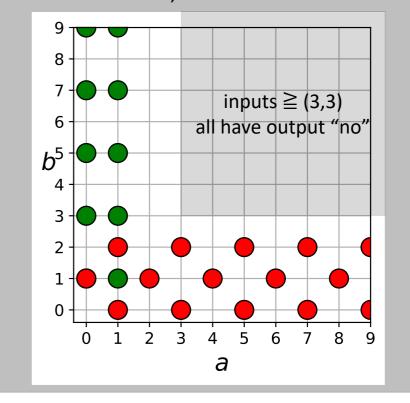
#### Eventually constant predicates

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Non-eventually constant predicates: majority (a≥b?) parity (a is odd?) equality (a=b?) and most anything interesting. Example of eventually constant predicate: a < 2 and b is odd, or b < 3 and a+b is odd



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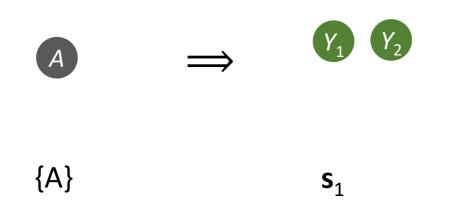


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- Since  $\Phi$  is nonnegative, at some point we cannot continue. QED

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- Those CRNs take expected time O(n log n) to converge, whereas non-execution bounded (and leader-driven) CRNs can stably compute all semilinear predicates in expected time O(polylog(n)).

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  - Not all species are required to vote, and
  - We can start with an "initial leader", e.g., to compute majority (a≥b?), start in initial state {1 L, a A, b B}... these are execution bounded from such states, but not from states with multiple leaders.
  - Or if all species are required to vote, but the CRN can be collapsing.
- Those CRNs take expected time O(n log n) to converge, whereas non-execution bounded (and leader-driven) CRNs can stably compute all semilinear predicates in expected time O(polylog(n)).
- <u>Conjecture</u>: Any execution bounded CRN takes at least Ω(n) expected time to stably compute any non-eventually-constant predicate.

## Thank you!

**Questions?**