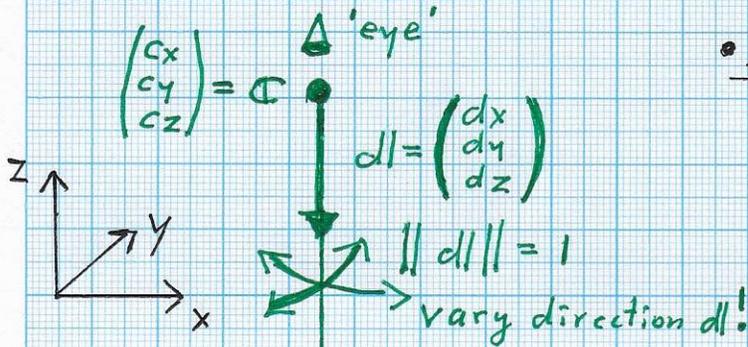


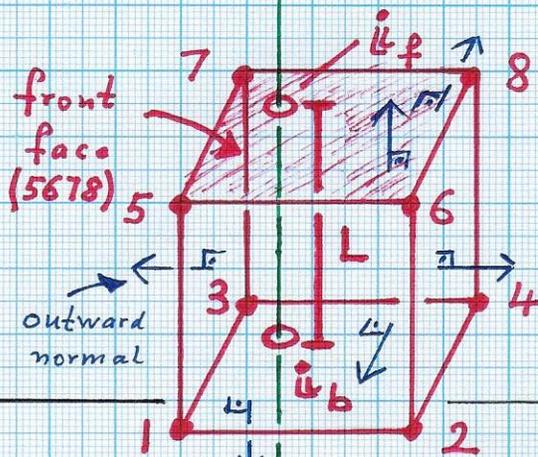
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RECONSTRUCTION = ANALYTICAL PROJECTION - Cont'd.

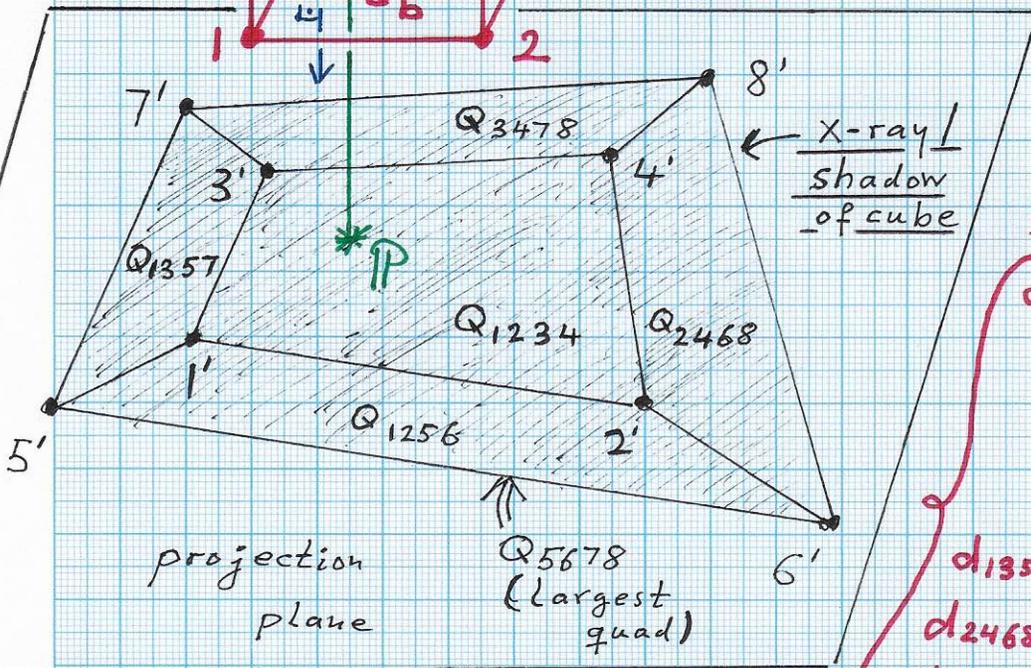
... 2) ii) 3D Case: Cube, Perspective Projection



- Example: only one front face (5678) and five back faces
 (general: one, two or three faces can be front faces...)



- Pairs of intersection points u_b (on back face) and u_p (on front face) define distances relative to C
- L-function defined for points p in projection plane:



$L(p) =$

- $d_{1234} - d_{5678}$ (in Q_{1234}),
- $d_{1256} - d_{5678}$ (in Q_{1256}),
- $d_{1357} - d_{5678}$ (in Q_{1357}),
- $d_{2468} - d_{5678}$ (in Q_{2468}),
- $d_{3478} - d_{5678}$ (in Q_{3478})

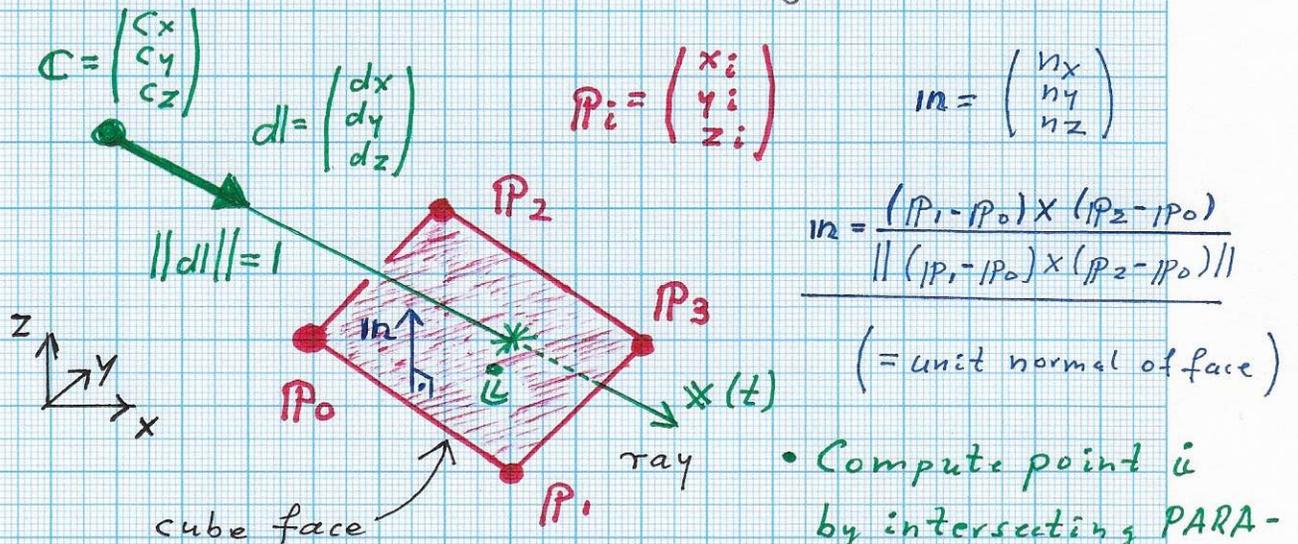
- distance $d_{ijkl} =$ distance between center C and intersection point of ray and cube face $(ijkl)$

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RECONSTRUCTION: ANALYTICAL PROJECTION - Cont'd.

... 2) ii) 3D Case: Cube, Perspective Projection

→ Must compute intersection point between ray and cube face:



- Compute point \hat{u} by intersecting PARAMETRIC ray and IMPLICIT plane (containing the cube face):

(i) RAY: $\mathbb{x}(t) = \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix} = C + t \cdot d$

(ii) PLANE: $n \cdot (\mathbb{x} - p_0) = 0$

(difference vector of point \mathbb{x} and p_0 perpendicular to n)

$\hat{u} = C + t_i \cdot d$

• Insert (i) into (ii): $\begin{pmatrix} n_x \\ n_y \\ n_z \end{pmatrix} \cdot \begin{pmatrix} c_x + t dx - x_0 \\ c_y + t dy - y_0 \\ c_z + t dz - z_0 \end{pmatrix} = 0$

(Note: \hat{u} is inside face

→ $n \cdot C + t \cdot n \cdot d - n \cdot \mathbb{x}_0 = 0$

$P_0 P_1 P_2 P_3 \Leftrightarrow$

→ $t \cdot n \cdot d = n \cdot \mathbb{x}_0 - n \cdot C$

$(\hat{u} - p_0) = u(P_1 - P_0)$

→ $(t_i =) t = \frac{n \cdot (\mathbb{x}_0 - C)}{n \cdot d}$

$+ v(P_2 - P_0)$, where $u, v \in [0, 1]$

Stratoran

RECONSTRUCTION: ANALYTICAL PROJECTION - Cont'd.

... 2) ii) 3D Case: Cube, Perspective Projection

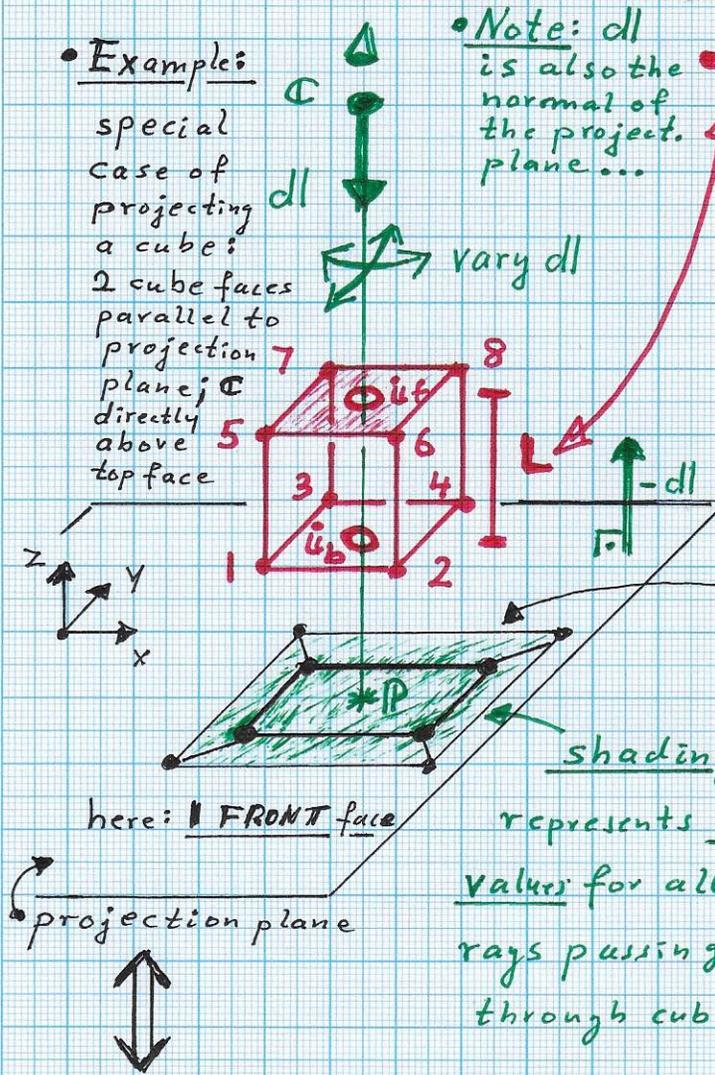
Example:

special case of projecting a cube: 2 cube faces parallel to projection plane; \mathbb{C} directly above top face

Note: dl is also the normal of the project. plane...

L-function generations

Shooting bundles of rays, emanating from \mathbb{C} , through cube; distance between "entry" and "exit" points defines L-value for point P in projection plane



boundary of X-ray/shadow of cube defined by boundary of convex hull of eight projected cube corners

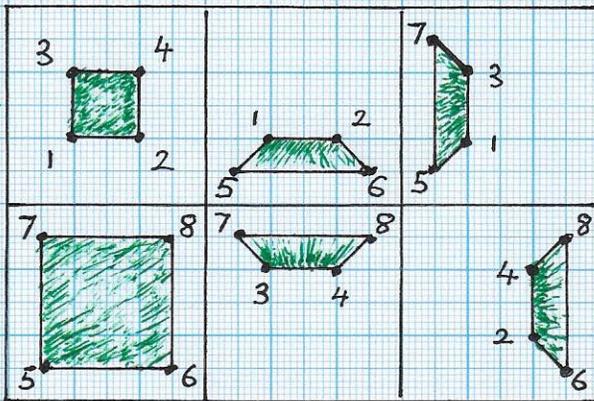
shading represents L values for all rays passing through cube

L-function parametrization:

can use $L = L(2D \text{ projection plane})$ or $L = L(\text{long-lat, spherical coords.})$

(dl can be parametrized using spherical coords.)

distance functions for each of the 6 cube faces $ijkl$: $d_{i,j,k,l}$?



projections of six faces - top-down view onto projection plane

shading represents distances between \mathbb{C} and faces $ijkl$;

$L = \|\vec{u}_b - \vec{u}_f\| = \text{distance of BACK and FRONT FACE points}$