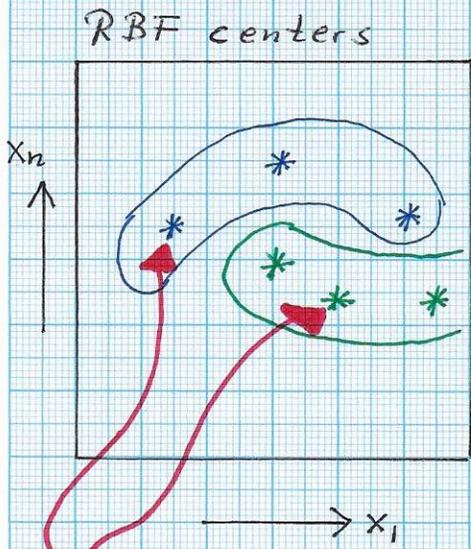
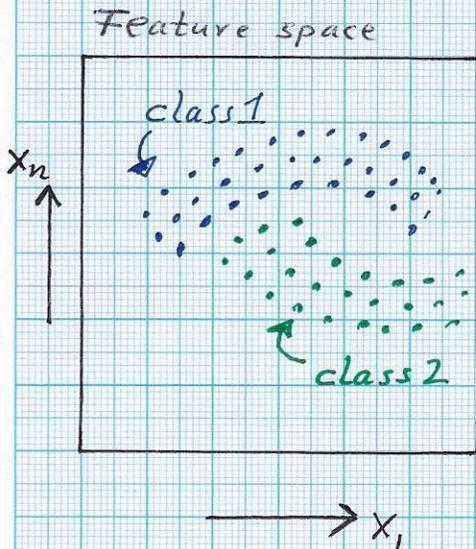


Stratovan

RADIAL BASIS FUNCTIONS (RBFs) AND CLASSIFICATION



"intelligently placed" centers of RBFs $r_l(x)$, $l = 1 \dots L$, with $L \ll K$ (much fewer RBFs than feature points!)

Assumptions:

- n-dimensional feature space with dimensions x_1, \dots, x_n
- m classes of objects/materials, class 1, class 2, ...

→ "example" feature points

$$\bar{p}_k = (x_1^k, \dots, x_n^k, c_k)^T = \begin{pmatrix} x_k \\ c_k \end{pmatrix}, k = 1, \dots, K, c_k \in \{1, 2, \dots, m\}$$

where c_k is the class label of x_k

→ m classifier functions

$$f_1(x), \dots, f_m(x),$$

where $f_j(x) = f_j(x_1, \dots, x_n)$

→ m-dimensional classifier space with dimensions

f_1, \dots, f_m , defining the multi-valued classifier function $\mathbb{F} = (f_1, \dots, f_m)^T$

Stratovan■ RBFs AND CLASSIFICATION - Cont'd.• Assumptions:

→ Each classifier function $f_j(x)$ is an expansion in the RBF basis $\{\tau_L(x)\}$:

$$f_j(x) = \sum_{L=1}^L w_L^j \tau_L(x)$$

(The coefficients w_L^j are computed via a best approximation approach, using the normal equations resulting from a least squares method.)

→ Ideally, $f_j(x)$ ("the neuron returning 1 for values of x representing class j ") returns 1 for all feature points x_k with class label j and 0 for all feature points with class labels different from j

$$f_j(x_k) = \begin{cases} 1, & \text{if } c_k = j \\ 0, & \text{otherwise} \end{cases} = \delta_{j,k} \quad \leftarrow \text{Kronecker symbol}$$

→ The conditions for f_j in "matrix form" are:

$$\begin{aligned} f_j(x_1) &= \sum_{L=1}^L w_L^j \tau_L(x_1) = \delta_{j,1} \\ &\vdots \\ f_j(x_k) &= \sum_{L=1}^L w_L^j \tau_L(x_k) = \delta_{j,k} \end{aligned}$$

Stratovan■ RBFs AND CLASSIFICATION - Cont'd.

... Conditions for classifier function $f_j(x)$:

$$\begin{bmatrix} \tau_1(x_1) & \dots & \tau_L(x_1) \\ \vdots & & \vdots \\ \tau_1(x_K) & \dots & \tau_L(x_K) \end{bmatrix} \cdot \begin{bmatrix} w_1^j \\ \vdots \\ w_L^j \end{bmatrix} = \begin{bmatrix} \delta_{j,1} \\ \vdots \\ \delta_{j,K} \end{bmatrix}$$

$$\Leftrightarrow \underline{\underline{R}} \cdot \underline{\underline{w}}_j = \underline{\underline{\delta}}_j$$

→ Conditions "summarized" for all functions
 $f_1(x), \dots, f_m(x)$:

$$\begin{bmatrix} R \end{bmatrix} \cdot \begin{bmatrix} \underline{\underline{w}}_1 \\ \dots \\ \underline{\underline{w}}_m \end{bmatrix} = \begin{bmatrix} \underline{\underline{\delta}}_1 \\ \dots \\ \underline{\underline{\delta}}_m \end{bmatrix}$$

$$\Leftrightarrow \underline{\underline{R}} \cdot \underline{\underline{W}} = \underline{\underline{\Delta}}$$

→ BEST approximation of $\underline{\underline{F}} = (f_1, \dots, f_m)^T$
obtained via least squares / normal equations:

$$\underline{\underline{W}} = \underline{\underline{(R^T \cdot R)^{-1} \cdot R^T \cdot \Delta}}$$

→ "IDEAL": Classification vector $\underline{\underline{F}}$ has component $f_j(x)$ return 1 if x represents class j (and all other components return 0).

Stratovan■ RBFs AND CLASSIFICATION - Cont'd→ **ALTERNATIVE VIEW AND APPROACH:**

Instead of computing a classification vector, a multi-valued function $\mathbb{F} = (f_1(x), \dots, f_m(x))^T$,

compute a single scalar-valued function $f(x)$ that - ideally - returns a specific value representing the class associated with x .

In other words, construct a function

$$f(x) = \begin{cases} v_1, & \text{if } x \text{ represents class 1} \\ v_2, & \text{" } x \text{ " " } 2 \\ \dots & \\ v_m, & \text{" } x \text{ " " } m \\ \vdots \\ 0, & \text{otherwise ; "class 0"} \\ = v_0 \end{cases}$$

For example, use "class values" $0 < v_1 < v_2 < \dots < v_m$.

→ In this case, the conditions for $f(x)$ are:

$$f(x_k) = \sum_{L=1}^L w_L \tau_L(x_k) = \sum_{j=1(0)}^m v_j \cdot \delta_{c_k, j} \quad \text{class label}$$

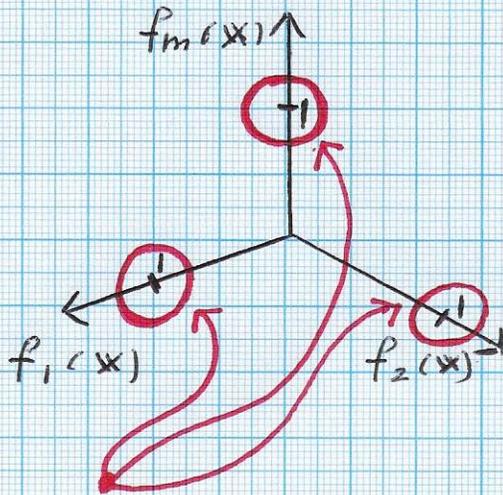
$$k = 1 \dots K, c_k \in \{1, \dots, m, 0\}$$

(Note: $\sum_{j=1(0)}^m v_j \cdot \delta_{c_k, j}$ returns value v_j when x_k has class label j .)

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RBFs AND CLASSIFICATION - Cont'd

→ Use of multi-valued classification function $\mathbb{F} = (f_1, \dots, f_m)$ vs. single- / scalar-valued classification function f :



ϵ -neighborhoods of class types \mathbb{F}_j

• Ideal: $\mathbb{F} = (1, 0, 0, \dots, 0)^T$

\Rightarrow class 1

...

$\mathbb{F} = (0, \dots, 0, 0, 1)^T$

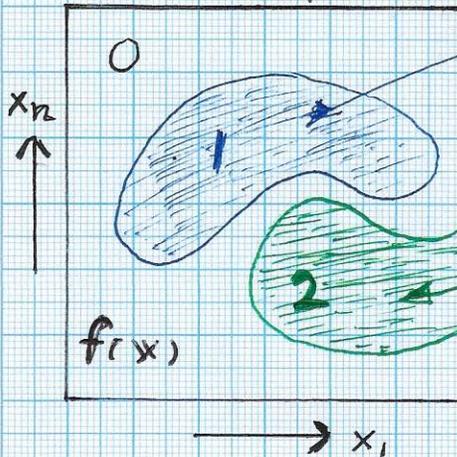
\Rightarrow class m

$\mathbb{F}_j = (0, \dots, 0, 1, 0, \dots, 0)^T \Rightarrow$ class j

$\Rightarrow \|\mathbb{F}(x) - \mathbb{F}_j(x)\|$ identifies

$\begin{cases} j, & \text{if} \\ \epsilon & \text{for } j \in \{1, \dots, m\} \text{ "class j"} \\ 0, & \text{otherwise} \end{cases}$

Feature space



class-1 region

$\Rightarrow |f(x) - v_1| < \epsilon$

class-2 region

$\Rightarrow |f(x) - v_2| < \epsilon$

(class) j identified

if $|f(x) - v_j| < \epsilon$