

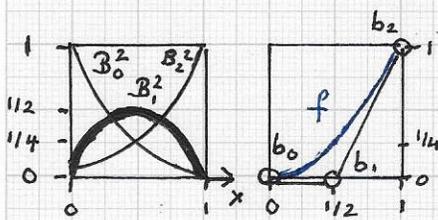
Stratovan

FRACTIONAL CALCULUS AND FEATURES - Cont'd.

Fractional derivatives:

Polynomial of degree 2  
in Bernstein-Bézier form

$$f(x) = \sum_{i=0}^2 b_i B_i^2(x)$$



$$B_i^2(x) = \binom{2}{i} (1-x)^{2-i} x^i, \quad i=0 \dots 2$$

$b_i$  = Bernstein - Bézier coeffs. / control points

$$f'(x) = 2 \cdot \sum_{i=0}^1 \Delta b_i B_i^1(x)$$

$$= 2 \sum_{i=0}^1 \bar{b}_i B_i^1(x)$$

Raise degree

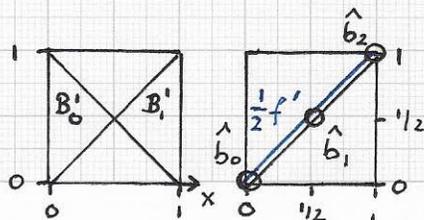
$$= 2 \sum_{i=0}^2 \hat{b}_i B_i^2(x)$$

where  $\hat{b}_0 = (\frac{0}{2} \bar{b}_0 + \frac{1}{2} \bar{b}_1,$

$\hat{b}_1 = \frac{1}{2} \bar{b}_0 + \frac{1}{2} \bar{b}_1,$

$\hat{b}_2 = \frac{2}{2} \bar{b}_1 + (\frac{0}{2} \bar{b}_2),$

and  $\bar{b}_i = \Delta b_i = b_{i+1} - b_i$



When considering only POLYNOMIALS (in monomial or Bernstein-Bézier form), one can view the definition of "simplified fractional derivatives" as blending of the  $(n+1)$  integer-order derivatives  $f^{(0)}(x), \dots, f^{(n)}(x)$  of a degree- $n$  polynomial. Further, since each of these  $(n+1)$  derivatives can be written - via degree-raising - as a degree- $n$  polynomial, non-integer-order derivatives are obtained by interpolating the  $(n+1)$  polynomials  $f^{(0)}(x), \dots, f^{(n)}(x)$  in a second direction -  $\alpha$ -direction - to define a fractional derivative  $f^{(\alpha)}(x)$ ,  $\alpha \in [0, n], \alpha \in \mathbb{R}$ .

The representation of a polynomial in Bernstein-Bézier form has the "advantage" that the "control polygon" defined by the coefficients  $b_i$  closely resembles the shape of the graph of a polynomial  $f(x)$ . We therefore use the Bernstein-Bézier basis polynomials  $B_i^n(x)$  here.

Raising the degrees of all  $(n+1)$  derivatives of a polynomial  $f(x)$

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Fractional derivatives:

Polynomial of degree 2  
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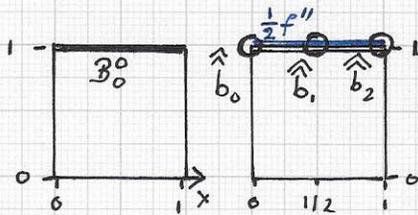
$$\begin{aligned}
 f''(x) &= 2 \cdot 1 \cdot \sum_{i=0}^0 \Delta^2 b_i B_i^0(x) \\
 &= 2 \cdot 1 \cdot \sum_{i=0}^0 \bar{b}_i B_i^0(x) \\
 &= 2 \cdot 1 \cdot \sum_{i=0}^1 \tilde{b}_i B_i^1(x) \\
 &= 2 \cdot 1 \cdot \sum_{i=0}^2 \hat{b}_i B_i^2(x),
 \end{aligned}$$

raise  
degree  
twice

where  $\tilde{b}_0 = \left(\frac{0}{1} \bar{b}_0 + \frac{1}{1} \bar{b}_1\right) \frac{1}{2} \bar{b}_0$ ,  
 $\tilde{b}_1 = \frac{1}{1} \bar{b}_0 + \frac{0}{1} \bar{b}_1$

$\hat{b}_0 = \left(\frac{0}{2} \tilde{b}_0 + \frac{1}{2} \tilde{b}_1\right) \frac{2}{2} \tilde{b}_0$ ,  
 $\hat{b}_1 = \frac{1}{2} \tilde{b}_0 + \frac{1}{2} \tilde{b}_1$ ,  
 $\hat{b}_2 = \frac{2}{2} \tilde{b}_1 \left(\frac{1}{2} \tilde{b}_1\right)$

and  $\bar{b}_i = \Delta^2 b_i = b_{i+2} - 2b_{i+1} + b_i$



$\Rightarrow f(x) = x^2 = \sum_{i=0}^2 b_i B_i^2(x)$

$f'(x) = 2x = 2 \cdot \sum_{i=0}^2 \hat{b}_i B_i^2(x)$

$f''(x) = 2 = 2 \cdot 1 \cdot \sum_{i=0}^2 \hat{b}_i B_i^2(x)$

is done elegantly for this polynomial when given in Bernstein-Bézier form.

In the example (left), the polynomial  $f(x) = x^2$  and its first and second derivatives are written as degree-2 Bernstein-Bézier-based polynomials.

Using the algorithm for degree-raising and the forward-difference operator  $\Delta$  for the coefficients, the three derivatives of  $f(x) = x^2$  — i.e.,  $f^{(0)}(x)$ ,  $f^{(1)}(x)$ ,  $f^{(2)}(x) =$

can all be written with three coefficients, always involving all three quadratic Bernstein-Bézier polynomials  $B_0^2(x)$ ,  $B_1^2(x)$  and  $B_2^2(x)$ .

Generally, the  $j^{th}$  derivative of the polynomial  $f(x) = \sum_{i=0}^n b_i B_i^n(x)$  is given as

$$\frac{d^j}{dx^j} f(x) = \frac{n!}{(n-j)!} \sum_{i=0}^{n-j} \Delta^j b_i B_i^{n-j}(x),$$

where  $j$  is an integer and

$$\Delta^j b_i = \Delta^{j-1} b_{i+1} - \Delta^{j-1} b_i,$$

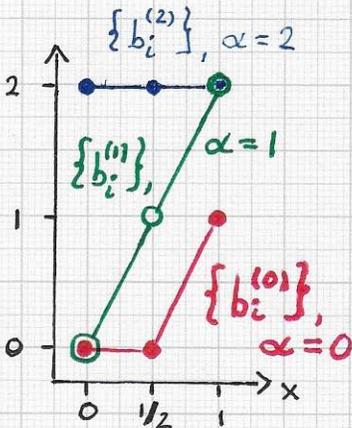
with  $\Delta^0 b_i = b_i$ . The formula used for elevating/raising the degree of  $f(x)$  from  $n$  to  $(n+1)$  is:

$$\begin{aligned}
 \hat{b}_i &= \frac{i}{n+1} b_{i-1} + \frac{n+1-i}{n+1} b_i, \quad i = 0 \dots (n+1), \\
 \Rightarrow f(x) &= \sum_{i=0}^{n+1} \hat{b}_i B_i^{n+1}(x).
 \end{aligned}$$

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■ FRACTIONAL CALCULUS AND FEATURES - Cont'd.

• Fractional derivatives: We use the notation  $b_i^{(j)}$  to denote the  $i^{th}$  "control point" / coefficient for the  $j^{th}$  derivative of a polynomial  $f(x)$ , i.e.,  $f(x) = \sum_{i=0}^n b_i^{(0)} B_i^n(x)$ . Considering the example  $f(x) = x^2$ , its three derivatives in Bernstein-Bézier form are

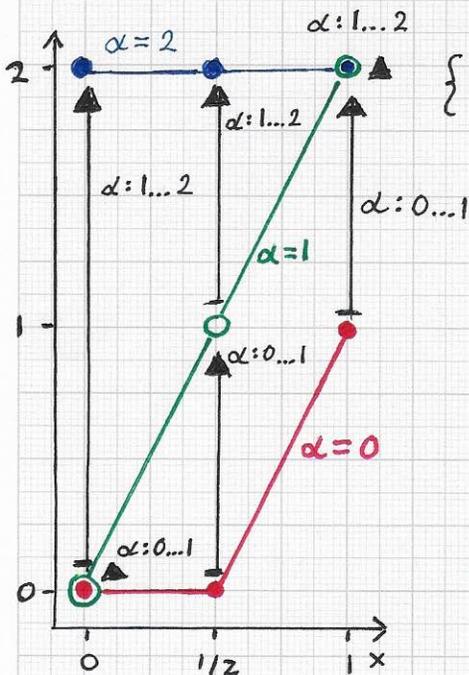


$$f^{(j)}(x) = \sum_{i=0}^2 b_i^{(j)} B_i^2(x), \quad j=0 \dots 2,$$

where  $b_i^{(0)} = b_i$ ,  $b_i^{(1)} = 2 \hat{b}_i$  and  $b_i^{(2)} = 2 \cdot 1 \cdot \hat{\hat{b}}_i$ .

Control polygons of function  $x^2$  for its derivatives  $f^{(0)}(x)$ ,  $f^{(1)}(x)$  and  $f^{(2)}(x)$

Considering the example (left image), it is possible to think about  $f^{(j)}(x)$  in terms of its associated control polygon, i.e., the geometry of  $f^{(j)}(x)$ 's graph.



• Note: The x-coordinates of control points  $(x_i, b_i^{(j)})^T$  are given by  $x_i = i/n$ ,  $i=0 \dots n$ , for a degree- $n$  polynomial defined over the interval  $[0, 1]$ .

The simplest, most straightforward and numerically most "robust" method for blending all derivatives  $f^{(j)}(x)$  to define non-integer-order derivatives  $f^{(\alpha)}(x)$  interpolates two derivatives

Piecewise linear interpolation of control polygons via blending control points  $b_i^{(j)}$  and  $b_i^{(j+1)}$

Linearly:  $f^{(\alpha)}(x) = (\lceil \alpha \rceil - \alpha) f^{(\lceil \alpha \rceil)} + (\alpha - \lfloor \alpha \rfloor) f^{(\lfloor \alpha \rfloor)}$ ,  
 $\alpha \in (0, 1), \alpha \in (1, 2), \dots, \alpha \in (n-1, n)$ ,  
 $\lfloor \alpha \rfloor, \lceil \alpha \rceil = \text{floor, ceiling of } \alpha$ .

Stratovan■ FRACTIONAL CALCULUS AND FEATURES - Cont'd.• Fractional derivatives:

The following questions and aspects arise when defining a simple and "meaningful" (= "information-enriching") method for locally estimating fractional derivatives for pixels or voxels of a 2D/3D image:

• Why use polynomials  $f(x)$ ?

$$\begin{aligned} f(x) &= f^{(0)}(x) = \\ &= \sum_{i=0}^n c_i x^i \\ &= \sum_{i=0}^n b_i B_i^n(x) \end{aligned}$$

(i) Why should one consider polynomials (tensor products of polynomials in the 2D and 3D cases) as class of functions for which to define fractional derivatives?

The use of low-degree polynomials to define local approximations for images is commonly done and accepted practice! Many discrete filter masks/templates and finite difference schemes exist for the class of polynomial functions!

• How to interpolate  $f^{(0)}(x), \dots, f^{(n)}(x)$  to obtain "good" non-integer-order derivatives  $f^{(\alpha)}(x)$ ,  $0 < \alpha < n$ ?

(ii) Given a polynomial  $f^{(0)}(x)$  of degree  $n$  and its  $(n+1)$  integer-order derivatives,  $f^{(0)}(x), \dots, f^{(n)}(x)$ , is there a "best way" to interpolate these  $(n+1)$  polynomials in  $\alpha$ -direction ( $0 < \alpha < n$ ) such that, for a specific value  $\bar{x}$ , the value of  $f^{(\alpha)}(\bar{x}) = \text{"Interpolate } (\alpha, f^{(0)}(\bar{x}), \dots, f^{(n)}(\bar{x})) \text{"}$  represents an interpolated value that is "ideal" (i.e., most beneficial for feature-based image data classification)?

FRACTIONAL CALCULUS AND FEATURES - Cont'd.

Fractional derivatives: (ii) ... Three methods are obvious candi-

dates to consider for computing an interpolated value for  $f^{(\alpha)}(\bar{x})$ :

• **Piecewise**

**Linear interpolation**

a) linearly interpolate  $f^{(\lfloor \alpha \rfloor)}(\bar{x})$

and  $f^{(\lceil \alpha \rceil)}$  for  $\lfloor \alpha \rfloor < \alpha < \lceil \alpha \rceil$ ,  $0 < \alpha < n$ ;

• **Natural cubic**

**spline interpolation**

b) compute the natural cubic spline

interpolating the values  $f^{(0)}(\bar{x})$ ,

$f^{(1)}(\bar{x})$ , ...,  $f^{(n)}(\bar{x})$  and evaluate

this spline (depending on  $\alpha$ ) for  $\alpha$ ;

• **Polynomial**

**interpolation**

c) compute the degree- $n$  polynomial

(depending on  $\alpha$ ) interpolating the

values  $f^{(0)}(\bar{x})$ , ...,  $f^{(n)}(\bar{x})$  and evaluate

it for  $\alpha$ .

(iii) Given a specific method used for

computing fractional derivatives

$f^{(\alpha)}(x)$ , does this method lead to

a corresponding discrete filter

mask that supports efficient and

numerically stable fractional deri-

vative computations?

Concerning the type of interpolation

performed in  $\alpha$ -direction, piecewise

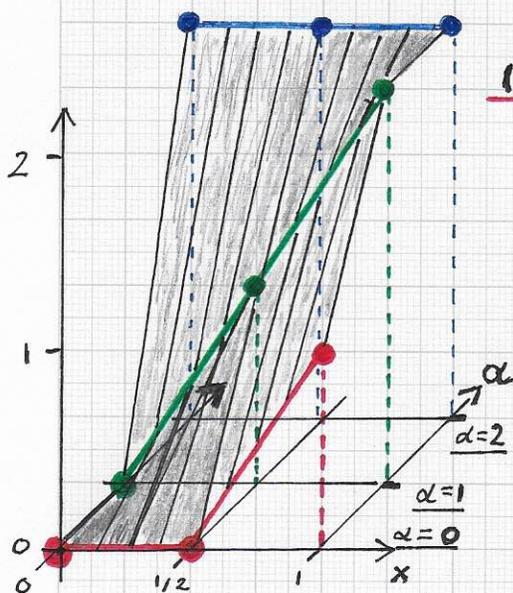
Linear interpolation is simple, efficient,

numerically stable, and it computes only

CONVEX COMBINATIONS of  $f^{(2)}(x)$  values;

thus, UNDER- and OVERSHOOTS are IMPOSSIBLE.

~ BH



Bernstein-Bézier control polygons for  $f^{(0)} = x^2$  (•),

$f^{(1)} = 2x$  (•),  $f^{(2)} = 2$  (•);

piecewise linear interpolation in  $\alpha$ -direction