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## ■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

Laplace eigenfunctions:... The goal is to determine the coefficients  $\alpha_j$  of an expansion of a discrete coefficient histogram of a given, new segment using  $k$  stored discrete coefficient histograms of "samples" of a specific material class - where all histograms initially have the same resolution, the same number  $B$  of bins:

- Characteristics of re-sampling via linear and quadratic B-splines:

- Re-sampling is a LOCAL method using a small no. of original data.
- Re-sampling computes CONVEX COMBINATIONS of data.
- Thus, re-sampling is VARIATION-DIMINISHING, not introducing undesirable oscillations.
- Re-sampling can be viewed as a smoothing operation.
- The re-sampling method presented preserves the INTEGRALS of histograms.

$$lh = \sum_{j=1}^k \alpha_j lh_j .$$

When this linear system is under-determined, i.e., when  $B < k$ , one can use the discussed linear or quadratic B-spline based method for re-sampling all discrete histograms.

The re-sampling method, as described, makes it possible to repeatedly double the number of bins, from  $B$  to  $2B$ , to  $4B$ , to  $8B$  etc. One terminates the re-sampling step when the number of bins is no longer smaller than  $k$ .

The values of coefficients  $\alpha_j$  can then be computed via the normal equations defined by the over-determined system.

WHEN ONE WANTS TO INCREASE THE NUMBER OF BINS FROM  $B$  TO  $2^p B$ ,  $p \in \{1, 2, \dots\}$ , ONE CAN (i) PERFORM BIN-DOUBLING  $p$  TIMES OR (ii) SPLIT EACH ORIGINAL BIN INTO  $2^p$  BINS DIRECTLY...

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Laplacian eigenfunctions:... The alternative method to the (re-

peated) bin-doubling approach is re-sampling performed at bin resolution k. Generally, the solution to the problem of computing the expansion  $h = \sum_{j=1}^k \alpha_j h_j$  would not require one to handle an under- or over-determined system. A simple example is shown in the figure (left).

The given bin resolution of B=2 is increased to resolution 3. Using the quadratic B-spline with control points (ordinates)  $h_0, h_1, h_2$  and  $h_3$  and a "uniform knot partition with spacing  $\Delta_1$ ", one obtains the 3 histogram values  $H_1, H_2$  and  $H_3$  by evaluating the B-spline at the equidistantly spaced c-values  $c_1, c_2$  and  $c_3$ . The computations can be done via the de Boor algorithm (repeated

linear interpolation:

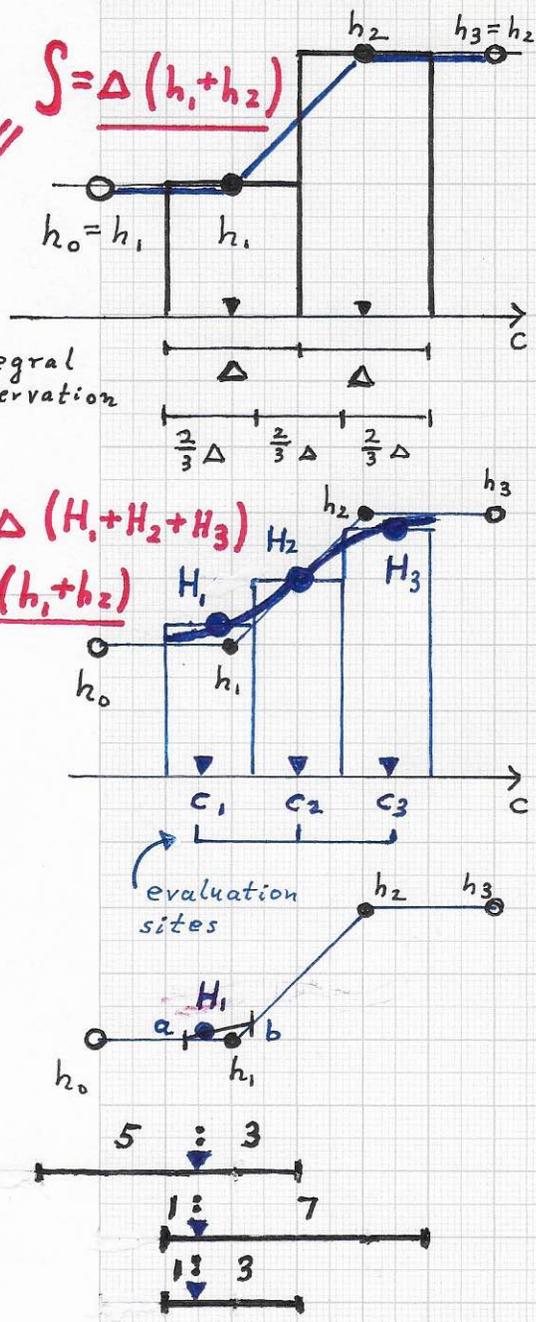
$$\begin{aligned}
 H_1 &= \frac{3}{4} a + \frac{1}{4} b \\
 &= \frac{3}{4} \left( \frac{3}{8} h_0 + \frac{5}{8} h_1 \right) + \frac{1}{4} \left( \frac{7}{8} h_1 + \frac{1}{8} h_2 \right) \\
 &= \frac{9}{32} h_0 + \frac{22}{32} h_1 + \frac{1}{32} h_2 = \frac{31}{32} h_1 + \frac{1}{32} h_2, \\
 H_2 &= \frac{1}{2} (h_1 + h_2), \\
 H_3 &= \frac{1}{32} h_1 + \frac{31}{32} h_2.
 \end{aligned}$$

$\Rightarrow H_1 + H_2 + H_3 = \frac{3}{2} (h_1 + h_2)$

$S = \Delta (h_1 + h_2)$

$S = \frac{2}{3} \Delta (H_1 + H_2 + H_3)$   
 $= \Delta (h_1 + h_2)$

integral preservation

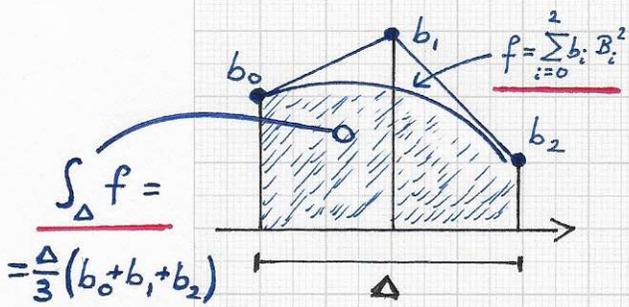


Re-sampling via quadratic B-spline. Top: original histogram with 2 bins, defining B-spline control points  $h_0, \dots, h_3$ ; middle: new histogram with 3 bins and values  $H_1, H_2$  and  $H_3$ ; bottom: computation of  $H_1$  via de Boor algorithm.

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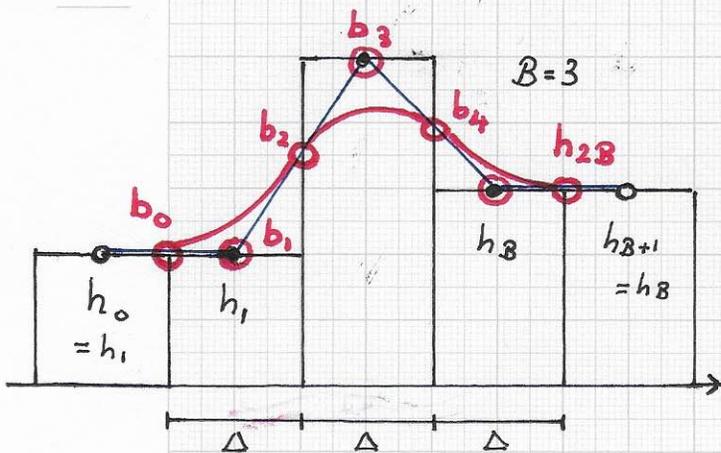
Laplacian eigenfunctions: ... One can show that such a re-sampling



approach based on B-splines preserves the integral value of the given histogram for every bin resolution used. In the limit, the new resolution used for re-sampling is ∞, and one can also show

The integral of a function  $f$ , a polynomial, expressed via Bernstein polynomials  $B_i^n$  over a domain interval  $\Delta$  has the integral value  $\Delta \cdot (b_0 + b_1 + \dots + b_n) / (n+1) = \int_{\Delta} f$ .

that the original histogram's integral value equals the integral value of the continuous B-spline over the same domain interval on the  $c$ -axis.



The figure (left) shows that B bins of width Δ each with histogram values  $h_1, \dots, h_B$  define the (B+2) control points/ordinates of a quadratic B-spline, i.e.,  $h_0 = h_1, h_1, h_2, \dots, h_B, h_{B+1} = h_B$ . The quadratic B-spline has B segments; each segment can be represented in the basis of Bernstein polynomials of degree 2 via 3 Bernstein-Bézier control points/coefficients:

Original histogram with B bins of width Δ and values  $h_0 = h_1, h_1, \dots, h_B, h_{B+1} = h_B$ ; quadratic B-spline control polygon defined by polygon connecting  $b_0, b_1, \dots, b_{B+1}$ ; each quadratic spline segment converted to Bernstein-Bézier representation defined by a triple of control points/coefficients  $b_0, b_1, b_2; b_2, b_3, b_4; \dots; b_{2B-2}, b_{2B-1}, b_{2B}$ .

$b_0, b_1, b_2; b_2, b_3, b_4; \dots; b_{2B-2}, b_{2B-1}, b_{2B}$ . Their values are:

$$b_{2i} = (h_i + h_{i+1}) / 2, i = 0 \dots B,$$

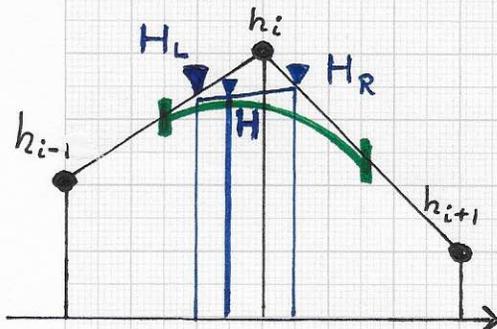
$$b_{2i+1} = h_{i+1}, i = 0 \dots (B-1)$$

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Laplacian eigenfunctions:... The integral value of the "piecewise constant histogram function" is  $\Delta \sum_{i=1}^B h_i$ .

• de Boor algorithm for B-spline evaluation via repeated linear interpolation:



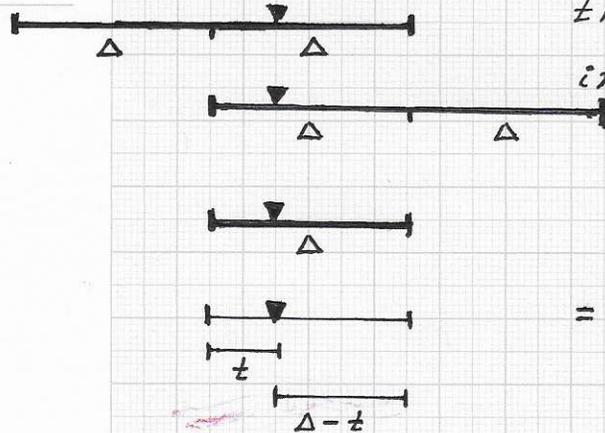
The integral value of the quadratic B-spline defined over the same domain with B spline segments is given by

$$\frac{\Delta}{3} ((b_0 + b_1 + b_2) + \dots + (b_{2B-2} + b_{2B-1} + b_{2B}))$$

This formula uses the Bernstein-Bézier representation for the B quadratic segments.

Using the formulas for  $b_0, b_1, \dots, b_{2B}$  from the previous page, one obtains the integral value as

$$\begin{aligned} & \frac{\Delta}{3} ( b_0 + 2b_2 + 2b_4 + \dots + 2b_{2B-2} + b_{2B} \\ & \quad + b_1 + b_3 + b_5 + \dots + b_{2B-1} ) \\ & = \frac{\Delta}{3} ( (h_0 + h_1)/2 + (h_1 + h_2) + \dots + (h_{B-1} + h_B) + (h_B + h_{B+1})/2 \\ & \quad + h_1 + h_2 + \dots + h_B ) \end{aligned}$$



$$H_L = \frac{\Delta-t}{2\Delta} h_{i-1} + \frac{\Delta+t}{2\Delta} h_i$$

$$H_R = \frac{2\Delta-t}{2\Delta} h_i + \frac{t}{2\Delta} h_{i+1}$$

$$H = \frac{\Delta-t}{\Delta} H_L + \frac{t}{\Delta} H_R$$

$$\begin{aligned} & = \frac{\Delta}{3} ( h_1 + (h_1 + h_2) + \dots + (h_{B-1} + h_B) + h_B \\ & \quad + h_1 + h_2 + \dots + h_B ) \\ & = \frac{\Delta}{3} ( 3h_1 + 3h_2 + \dots + 3h_B ) = \Delta \sum_{i=1}^B h_i \end{aligned}$$

Using repeated linear interpolation to compute a value H of a quadratic B-spline segment via given histogram values  $h_{i-1}, h_i$  and  $h_{i+1}$ .

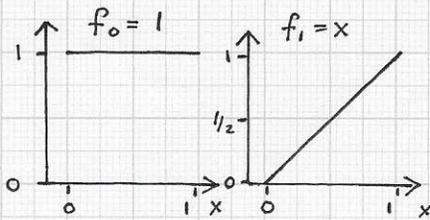
The implication of this result is that the continuous, analytically defined quadratic B-spline has the integral of the "piecewise constant histogram function." ...

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■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions:... In summary, one can employ, for example, the discussed linear or quadratic B-spline based re-sampling approaches to generate new histogram representations with exactly k bins from original histogram data with only B bins (B < k). One can use the de Boor algorithm for the calculation of the needed k B-spline values, defined by equidistantly spaced evaluation sites in the histogram's domain and their associated B-spline values. The de Boor algorithm is illustrated on the previous page for the computation of a new value H on a segment of a quadratic B-spline.

- Analytical approach to function approximation via least-squares:



i) best approximation of  $f_1$  in basis  $\{f_0\}$ :

$$f_1 = c f_0$$

$$\langle f_0, f_0 \rangle c = \langle f_0, f_1 \rangle$$

$$1 c = \frac{1}{2}$$

$$c = \frac{1}{2}$$

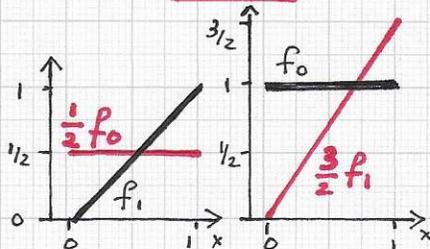
ii) best approximation of  $f_0$  in basis  $\{f_1\}$ :

$$f_0 = c f_1$$

$$\langle f_1, f_1 \rangle c = \langle f_1, f_0 \rangle$$

$$\frac{1}{3} c = \frac{1}{2}$$

$$c = \frac{3}{2}$$



Best approximations. Using  $f_0$  to optimally approximate  $f_1$ ; using  $f_1$  to optimally approximate  $f_0$  (via normal equations).

The de Boor algorithm is illustrated on the previous page for the computation of a new value H on a segment of a quadratic B-spline. Alternatively, one could even devise an approach using a continuous, analytical B-spline representation for histograms when having to represent a new given histogram as an expansion of stored (material sample) histograms. Using such a completely B-spline, analytical function based approach is discussed next. The shown example (left) provides background, ...

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