

Stratoran

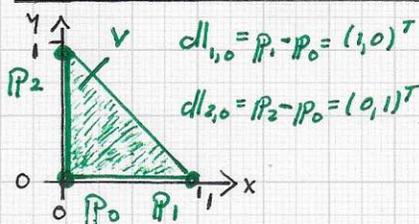
■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions: ... **HOW IS A SIMPLEX AND HOW ARE BARYCENTRIC COORDINATES RELATED TO THE CLASSIFICATION PROBLEM?** We assume that a class is represented by k samples.

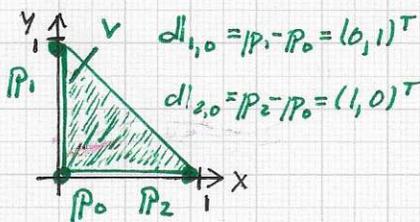
Computation of (hyper-) volumes of simplices in arbitrary dimension



$$v = \frac{1}{1!} \det(x_1 - x_0) = \begin{cases} x_1 - x_0 \geq 0 & \text{if } x_1 \geq x_0 \\ x_1 - x_0 < 0 & \text{if } x_1 < x_0 \end{cases}$$

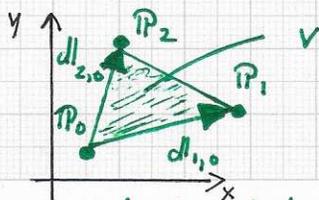


$$v = \frac{1}{2!} \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = \frac{1}{2}$$



$$v = \frac{1}{2!} \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} = -\frac{1}{2}$$

Indexing/orientation defining sign of volume v of a simplex.



$$v = \frac{1}{2!} \begin{vmatrix} | & | & | \\ dl_{1,0} & dl_{2,0} & | \\ | & | & | \end{vmatrix}$$

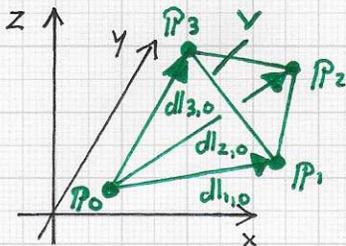
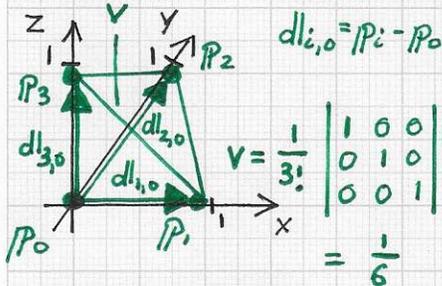
RELATED TO THE CLASSIFICATION PROBLEM? We assume that a class is represented by k samples. Each sample is characterized statistically via a histogram, or multiple histograms, to describe a feature value's distribution. (In the case of an eigenfunction-based multi-scale/frequency description of a sample, there are multiple, scale-specific coefficient value histograms - one histogram per scale.) Each histogram has B = k bins. (As discussed, one can construct a B-bin histogram such that B = k from an original histogram that has B ≠ k bins.) After normalization, k histograms define k points on a unit hyper-sphere that is embedded in k-dimensional space. The "complete graph" of the k points defines a (k-1)-dimensional simplex - the "reference simplex." ...

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■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

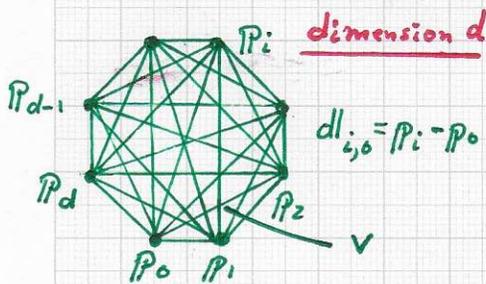
• Laplacian eigenfunctions:... WHEN A NEW UNCLASSIFIED

Simplex volumes:



$$V = \frac{1}{3!} \begin{vmatrix} | & | & | \\ d_{1,0} & d_{2,0} & d_{3,0} \\ | & | & | \end{vmatrix}$$

• General case:



$$V = \frac{1}{d!} \begin{vmatrix} | & | & | & | \\ d_{1,0} & \dots & d_{d,0} \\ | & | & | & | \end{vmatrix}$$

Volumes of k-dimensional simplices in k-dimensional embedding space and (k+1) vertices.

IS GIVEN, IT IS ALSO CHARACTERIZED BY A NORMALIZED HISTOGRAM (S) DEFINING AN ADDITIONAL POINT (S) ON THE UNIT HYPER-SPHERE IN k-DIMENSIONAL SPACE. ONE CAN COMPUTE THE BARYCENTRIC COORDINATES OF THE NEW POINT (S) RELATIVE TO THE "REFERENCE SIMPLEX." THE RESULTING BARYCENTRIC COORDINATE VALUES FOR THE NEW POINT (S) ARE USED TO DETERMINE A PROBABILITY FOR THE NEW UNCLASSIFIED SAMPLE INDICATING WHETHER IT IS LIKELY FOR IT TO BELONG TO THE CLASS - EXEMPLIFIED BY THE k SAMPLES - OR NOT.

The computation of signed hyper-volumes of simplices is necessary for the direct calculation of a point's barycentric coordinates. The previous, this and the following pages describe simplex volume computation.

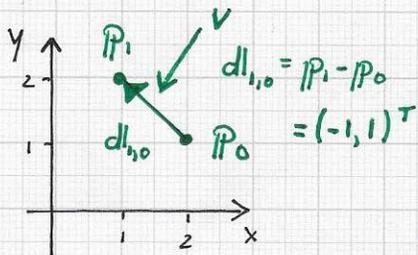
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OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

Laplacian eigenfunctions: ... Considering the classification

Simplex volumes of (k-1)-dimensional simplices with k vertices, in k-dimensional embedding space:

k=2



* The square root is taken of the absolute value of the determinant; THE SIGN OF THE DETERMINANT IS

$$v = \frac{1}{1!} \left| \begin{matrix} -dl_{1,0} \\ dl_{1,0} \end{matrix} \right|^{1/2}$$

$$= \left| \begin{matrix} (-1, 1) \\ (-1, 1) \end{matrix} \right|^{1/2}$$

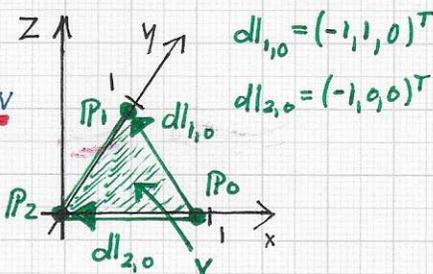
$$= \sqrt{2}$$

problem, the k "classified sample points" P_1, \dots, P_k are points with normalized positional vectors, i.e., they lie on a unit hyper-sphere of (manifold) dimension (k-1), in a k-dimensional embedding space. Thus, one must compute volumes of (k-1)-dimensional simplices with vertices

P_1, \dots, P_k in k-dimensional embedding space. The figures (left) show two examples, a 1- and 2-dimensional simplex (line segment and triangle), for which length and area are computed via square roots of determinants. This volume computation can also be done via the calculation of the "cross product" of vectors, i.e., via the calculation

k=3

THE SIGN OF THE VOLUME.

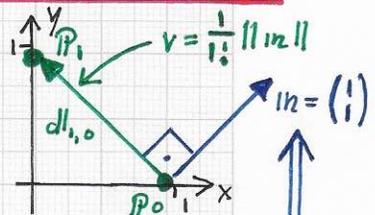


$$v = \frac{1}{2!} \left| \begin{matrix} \langle dl_{1,0}, dl_{1,0} \rangle & \langle dl_{1,0}, dl_{2,0} \rangle \\ \langle dl_{2,0}, dl_{1,0} \rangle & \langle dl_{2,0}, dl_{2,0} \rangle \end{matrix} \right|^{1/2}$$

$$= \frac{1}{2} \left| \begin{matrix} 2 & 1 \\ 1 & 1 \end{matrix} \right|^{1/2} = \frac{1}{2}$$

of normal vectors and their lengths. The

example (right figure) shows the computation of a line segment's absolute length value in 2-dimensional "embedding space".



$$n = \begin{vmatrix} x & -1 \\ y & 1 \end{vmatrix} = 1x + 1y$$

$$\Rightarrow v = \|n\| = \sqrt{2}$$

General case: k

$$v = \frac{1}{(k-1)!} \left| \begin{matrix} \langle dl_{1,0}, dl_{1,0} \rangle & \dots & \langle dl_{1,0}, dl_{k-1,0} \rangle \\ \vdots & & \vdots \\ \langle dl_{k-1,0}, dl_{1,0} \rangle & \dots & \langle dl_{k-1,0}, dl_{k-1,0} \rangle \end{matrix} \right|^{1/2}$$

* The "cross product" is defined only for some dimensions!

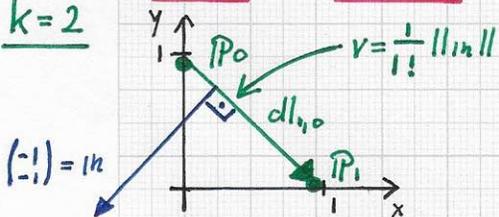
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OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

Laplacian eigenfunctions:... The normal's orientation defines the POSITIVE HALF-SPACE relative to the simplex: +1n points in the positive half-space, and -1n points in the negative half-space. The normal +1n is also called "outward normal." The indexing of the points P_0, \dots, P_{k-1} defines the normal's orientation. As a consequence, a point's barycentric coordinates - AND THEIR SIGNS - depend on orientation. We provide a simple example of barycentric coordinate calculation (right figure). The "reference triangle" has vertices P_0, P_1, P_2 ; its OUTWARD normal is defined by $\begin{vmatrix} x & -2 & -2 \\ y & 2 & 0 \\ z & 0 & 0 \end{vmatrix} = 4 \cdot z \Rightarrow \underline{1n = (0, 0, 4)^T}$. Thus, the volume of the triangle is $\underline{v = \frac{1}{2} \cdot 4 = 2}$. The point P defines the 3 sub-triangles PP_0P_1, PP_1P_2 and PP_2P_0 with their 3 normal vectors defined by

(Hyper-) Volumes of Simplices - Determinants and normals:

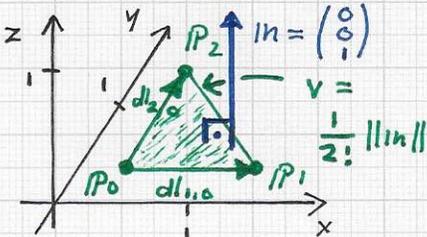
k=2



$$1n: \begin{vmatrix} x & 1 \\ y & -1 \end{vmatrix} = -1x - 1y$$

$$\Rightarrow v = \|1n\| = \sqrt{2}$$

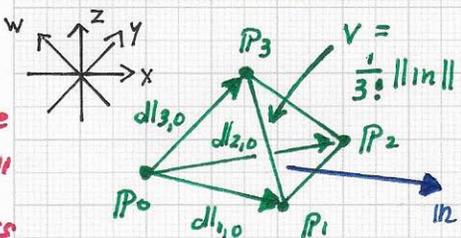
k=3



$$1n: \begin{vmatrix} x & 1 & 0 \\ y & 0 & 1 \\ z & 0 & 0 \end{vmatrix} = \begin{matrix} 0x \\ +0y \\ +1z \end{matrix}$$

$$\Rightarrow v = \frac{1}{2} \|1n\| = \frac{1}{2}$$

k=4

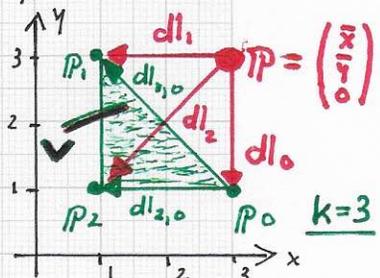


$$1n: \begin{vmatrix} x & 1 & 1 & 1 \\ y & dl_{1,0} & dl_{2,0} & dl_{3,0} \\ z & 1 & 1 & 1 \\ w & 1 & 1 & 1 \end{vmatrix} = \begin{matrix} Ax \\ +By \\ +Cz \\ +Dw \end{matrix}$$

$$\Rightarrow v = \frac{1}{6} \|(A, B, C, D)^T\|$$

Note: The "standard" vector cross product cannot be applied to arbitrary dimension!

Thus, the normals of the sub-triangles are $1n_2 = (0, 0, -4)^T$, $1n_0 = (0, 0, 4)^T$ and $1n_1 = (0, 0, 4)^T$...



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■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions:... The volumes of the 3 sub-triangles are:

$$v_2 = \frac{1}{2} \cdot 4 = 2; v_0 = \frac{1}{2} \cdot 4 = 2; v_1 = \frac{1}{2} \cdot 4 = 2.$$

BUT: The signs of these volumes must be determined! For this purpose one considers the angles (inner product values) between ln and ln_2 , ln and ln_0 , and ln and ln_1 :

- 1) If $\langle ln, ln_i \rangle > 0$, then $sign \|ln_i\| = '+'$.
- 2) If $\langle ln, ln_i \rangle < 0$, then $sign \|ln_i\| = '-'$.
- 3) If $\langle ln, ln_i \rangle = 0$, then 'special case'.

Concerning the example, the $\langle \cdot, \cdot \rangle$ test yields:

$$\langle ln, ln_2 \rangle = -16 \Rightarrow v_2 = -2$$

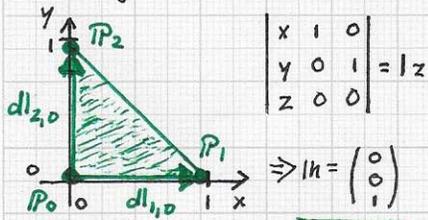
$$\langle ln, ln_0 \rangle = 16 \Rightarrow v_0 = 2$$

$$\langle ln, ln_1 \rangle = 16 \Rightarrow v_1 = 2$$

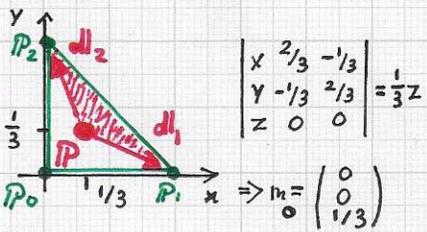
The resulting barycentric coordinates for P are: $u_0 = v_0/v = 1; u_1 = v_1/v = 1; u_2 = v_2/v = -1$.

k=3

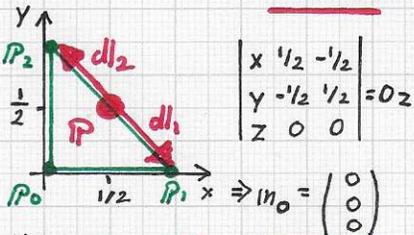
Indexing of P_0, \dots, P_{k-1} and location of P defining sign of volumes:



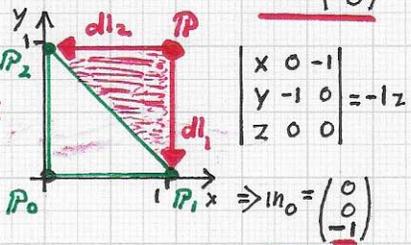
INSIDE



ON BOUNDARY



OUTSIDE



The normal of the "reference triangle" defines the +OUTWARD direction; the outward normal is (0,0,1).

Three scenarios are shown for normal ln_0 of the sub-triangle PP_1P_2 . The sign of P 's barycentric coordinate $u_0 = v_0/v$ is given by the sign of $\langle ln, ln_0 \rangle$. The shown three scenarios yield the inner product values $\frac{1}{3}, 0$ and -1 .

In summary, the absolute values and signs of a point's barycentric coordinates can be computed via determinants and a "simple" inner product sign test. We must apply these computations to our setting - where P and P_0, \dots, P_{k-1} are all points on a unit hyper-sphere. ...