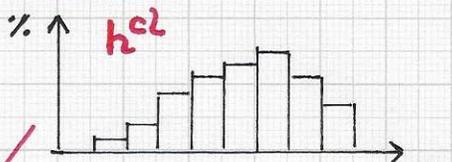


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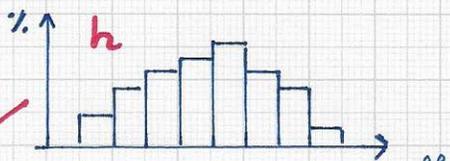
■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...

Computation of p_i
when scale i of a specific class is represented by only ONE class sample in the "database":



Sketch of a coeff. value histogram h^{cl} of ONE sample s_i for scale i

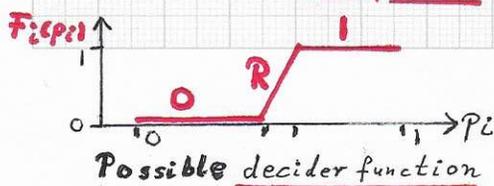


Sketch of a coeff. value histogram h of unclassified segment S , for scale i

By embedding h^{cl} and h in a vector space of finite or infinite dimension, one can compute a difference measure

$\|h^{cl} - h\|$,

normalized to the interval $[0, 1]$ that serves as the value for p_i , where minimal difference 0 is mapped to maximal similarity $p_i = 1$.



The discussion of individual univariate decider functions $F_i(p_i)$ did not address the necessary computation of the value of p_i in the desirable detailed manner. The discussion simply referred to p_i as a measure of similarity (at scale i) of an unclassified segment S and a second, classified segment s serving as THE ONE sample image segment representing a specific material class — stored with all other sample segments in a "database." When the "database" indeed only stores EXACTLY ONE SAMPLE PER CLASS, the discussion concerning the computation of a p_i -value is straightforward: At scale i , and for each class, one only needs to compute the coefficient value histogram difference for A PAIR of histograms — the one associated with S and the one associated with s , where s is the single, only representation of a specific class.

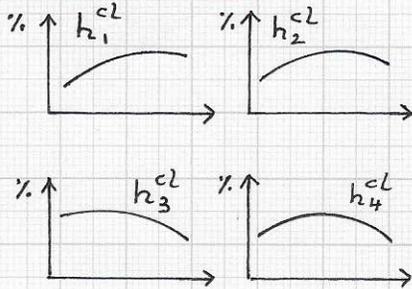
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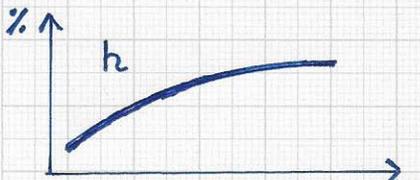
OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

- Laplacian eigenfunctions and neural networks:...

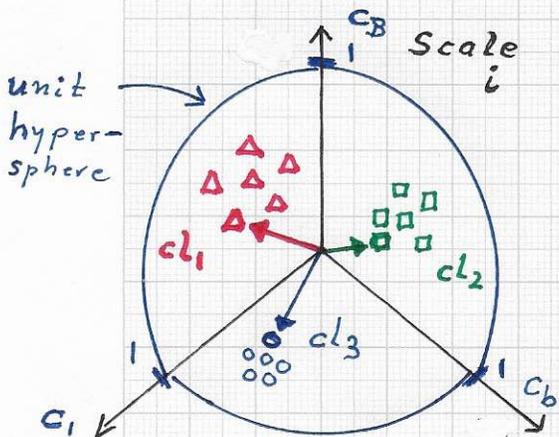
Computation of p_i when the "database" stores MORE THAN ONE class sample:



Sketch of 4 coefficient value histograms $h_1^{cl}, \dots, h_4^{cl}$ of 4 samples S_1, \dots, S_4 , for scale i .



Sketch of a coeff. value histogram h of unclassified segment S_i , for scale i .



Binned, discrete histograms (normalized) of coefficient values of 6 samples of 3 classes can be viewed as points on a sphere.

Generally, MULTIPLE sample image segments, represented via their coefficient value histograms for H scales, are stored in the "database" for each class. Using the notation from the previous discussion, we have C classes (cl_1, \dots, cl_C) with k_1 sample segments for class cl_1, \dots and k_C sample segments for class cl_C . IN A SETTING WHERE ONE HAS MORE THAN ONE SAMPLE SEGMENT FOR A CLASS, HOW DOES ONE / CAN ONE COMPUTE p_i -VALUES?

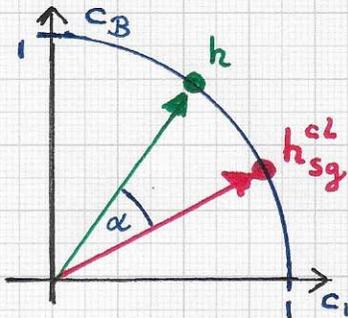
The figures (Left) sketch the case where a class cl is represented in the sample "database" via the histogram data for four class samples. Thus, one can compute the histogram distance measures $\|h_{sg}^{cl} - h\|, sg=1..4$, for the unclassified segment S_i , for each scale $i, i=1..H$. The problem to be addressed is the proper definition of a p_i -value from multiple $\|h_{sg}^{cl} - h\|$ -values.

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■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

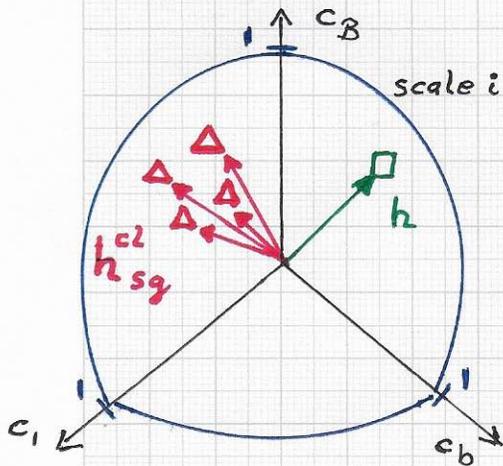
• Laplacian eigenfunctions and neural networks:...



Using the COS angle measure to define the similarity of two histograms h and h_{sg}^{cl} :

$$\cos \alpha = \langle h, h_{sg}^{cl} \rangle.$$

This measure, as desired, yields the value 1 when the two histograms are identical and 0 when the two histograms are orthogonal to each other.



To determine the similarity between a histogram h and 4 same-class histograms $h_{sg}^{cl}, sg=1...4$, one must consider all 4 cos values.

We can assume that all coefficient value histograms are binned, discrete histograms, using B bins - bin_1, \dots, bin_B .

Thus, all NORMALIZED histograms can be interpreted as points on a UNIT HYPER-SPHERE, having positional vectors with only non-negative coordinate values.

The figure (bottom) on the previous page illustrates this interpretation;

for a particular scale i , it shows the points representing the histograms of 6 sample segments for 3 material classes.

Based on this geometrical viewpoint, one can use a simple "angle measure" to define the difference / distance of two normalized, binned histograms in B -dimensional space.

The top figure (left) shows how one can employ the inner product of two normalized vectors - histograms - to define their similarity.

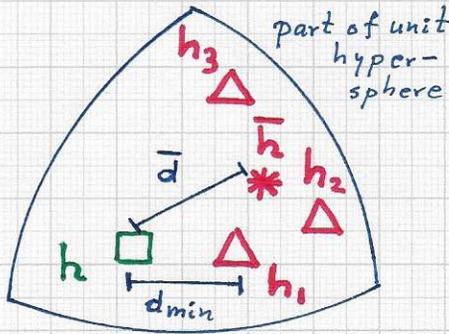
The bottom figure (left) illustrates our situation:

We must calculate ONE similarity value for a given histogram h and a set of histograms $h_{sg}^{cl}, sg=1...4$, of the same class.

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■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...



Two viable possibilities for computing a similarity value for h and {h1, h2, h3}: use the "minimal angle distance" d_{min} (with maximal cos value) or use the angle distance to h_{bar}, i.e., the normalized vector of the averaged vectors h1, h2 and h3.

Generalizing the concept of "similarity between two segments S and S" to the concept of "similarity between a segment S and a set of segments {S_{sg}}" reduces the P-values to values only depending on class and scale:

	scales		
	I	...	H
class ₁	P _{1,1}	...	P _{1,H}
⋮	⋮	⋮	⋮
class _c	P _{c,1}	...	P _{c,H}

When comparing a segment S against C classes and H scales, C · H P_{c1,sc} values result.

The left figure illustrates our setting:

Given a histogram h and the set of histograms {h1, h2, h3} - where h1, h2 and h3 are stored sample histograms of the same class - for a specific scale i, calculate a similarity value between h and

{h1, h2, h3}. One could, for example, define similarity as follows:

i) $SIM_{max} = \max \{ \langle h, h_i \rangle \}_{i=1}^3$ or

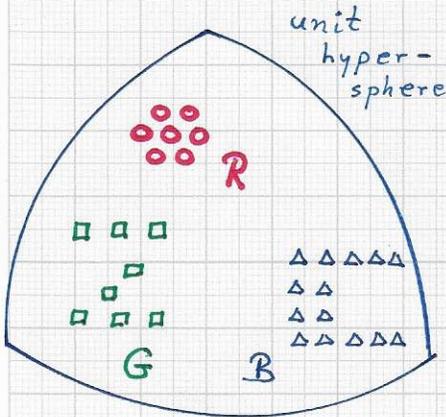
ii) $SIM_{avg} = \langle h, \bar{h} \rangle$, where
$$\bar{h} = \frac{(h_1 + h_2 + h_3) / 3}{\| (h_1 + h_2 + h_3) / 3 \|}$$

When one has decided which definition of similarity is "a proper and simply computable" option, OUR PROBLEM IS SOLVED: WE HAVE A MEANS FOR CALCULATING SIMILARITY BETWEEN A GIVEN, NEW HISTOGRAM h AND A SET OF HISTOGRAMS THAT CORRESPOND TO SEVERAL SEGMENTS, ALL BELONGING TO THE SAME CLASS.

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OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

Laplacian eigenfunctions and neural networks:...

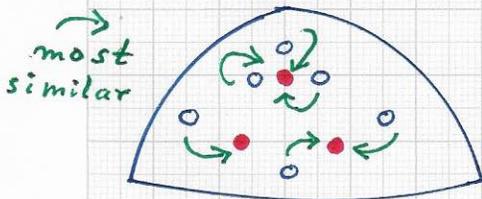


IN SUMMARY, it is now possible to calculate p_i -values — and p_i -value distributions — for the definition of univariate decider functions $F_i(p_i)$. A p_i -value captures the similarity between an unclassified segment S and a classified, stored segment s . **WE CAN NOW UNDERSTAND s ALSO AS A SET OF CLASSIFIED, STORED SEGMENTS $\{s_{sg}\}$. We can now**

Note. Generally, one should assume that same-class, same-scale histograms of multiple sample segments form "compact clusters" — like cluster **R**. **BUT:** In principle, it might be possible that same-class, same-scale segment histograms define non-compact clusters — like clusters **G** and **B**. **THUS:**

The similarity measure SIM_{max} is preferable.
(See previous page.)

reconsider the construction of a decider function $F_i(p_i)$. The left figure (bottom) illustrates the construction process. We use two datasets: **(i)** For a specific material class and a specific scale, the database stores multiple histograms associated with samples (of this class); this is the first dataset, shown as '**●**' in the figure. **(ii)** For the same material class and scale, ADDITIONAL samples (of this class) are made available and characterized via the same type of histograms, shown as '**○**'. The sets **{●}** and **{○}** define a p_i -value distribution.



Definition of p_i -value distribution. ● = histograms from database, ○ = histograms of add'l samples.

...
The sets **{●}** and **{○}** define a p_i -value distribution.