

Stratovan■ OBJECT AND MATERIALS EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...

- Thus, the to-be-classified 3D image segment is STATISTICALLY characterized by H binned histograms/distributions (properly normalized in the domain value range, $[0, 1]$, and with respect to its integral norm, $\|\cdot\|$). These histograms describe the segment's low-, medium- and high-frequency behaviors; they are the segment's H "fingerprints".
- Subsequent segment comparison and classification steps are based on a metric that makes possible a meaningful and efficient computation of similarity of / distance between two eigenfunction-based coefficient value histograms, for the same scale of two material segments. "Degree of similarity" (concerning a specific scale) becomes the foundation of match-probabilities for the to-be-classified segment and classified segments.
- A database of materials to be recognized contains data for C classes c_l , $c_l = 1 \dots C$. (Class 0 is understood as the class that is NOT class 1, ..., NOT class C .) Class c_l is represented in the database by k_{c_l} material samples.

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- Laplacian eigenfunctions and neural networks:... • Note. The key material samples stored in the database for class c_l must be "REPRESENTATIVE" for class c_l in the following sense: As far as "features," "texture," "multi-scale characteristics" etc. of material class c_l is concerned, the class- c_l segment data stored in the database must capture the allowed and practically possible "variability spectrum" of class c_l in all its appearances (in 3D image data). Further, the relative numbers of allowed samples for class- c_l should reflect the "segment types" of class- c_l AS OBSERVED IN A REAL-WORLD SETTING. For example, if material class c_l exhibits a certain 3D checkerboard texture in 50% of all observed real-world cases, then it will be imperative to also populate the database accordingly, i.e., 50% of the class c_l samples in the database will have to exhibit such a checkerboard texture. In other words, the practically possible "segment types" of class c_l and their relative occurrences must be reflected, preserved by the chosen class- c_l samples in the database. This database design goal, to be achieved via proper training/learning, is CRUCIAL FOR THE COMPUTATION OF MATCH-PROBABILITY VALUES FOR A TO-BE-CLASSIFIED SEGMENT throughout the classification process.

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• Laplacian eigenfunctions and neural networks:...

- Each material segment - every segment in the database and the one to-be-classified segment - is represented by H normalized (binned) histograms (over a domain interval $[0, 1]$). Thus, every segment has H "fingerprints" generated by moving a convolution mask over the entire segment; determining the mask-associated coefficient values of many local eigenfunction-based density function expansions; and establishing the H coefficient value histograms.
- It is possible to compare each of the H histograms of the to-be-classified segment with the same-scale histograms of all the segments in the database (all classes c_l , all samples per class). The result of this comparison is a set of "similarity values" defining the scale-specific values of the chosen distance metric for histograms.
- One can now calculate match-probabilities $P_{c_l}^{sc}$ that consider similarity at only one scale sc and define a probability of belonging to class c_l for the to-be-classified segment. (This probability considers and therefore depends on the "representative" k_{c_l} samples in the database.)

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• Note. Considering merely similarity for one scale vs. considering all (or several selected) scales

Leading to multiple scale-specific similarities impacts the definition and calculation of match-probabilities

The to-be-classified image segment is statistically characterized for H scales. Therefore, some of these scales are more and some are less similar to the scales of a specific material class' sample representatives in the database. (It is important to keep in mind that each material class in the database is captured via a representative set of class samples; and each sample is identified with its corresponding H scale histograms. This aspect is relevant for the computation of a similarity between a scale of the to-be-classified segment and the multitude of same-scale histograms of the set of samples of a certain class.)

The crucially important definition(s) in this context concerns SIMILARITY and CLOSEST SAMPLE in the database of class segment samples. We understand a coefficient value histogram as a discrete, binned normalized histogram lh , having, for example, 64 coordinates (all non-negative). Since $\|lh\|_2=1$, one can interpret lh as a positional vector from the origin to a point on a unit hyper-sphere.

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• Laplacian eigenfunctions and neural networks:... The to-be-classified image segment is represented via H scales,

i.e., via H histograms. One can write the set of histograms as a "vector of histograms h_1, \dots, h_H ":

$$H = (h_1, h_2, \dots, h_H)$$

SIMILARITY of two image segments for a specific scale is defined by histogram similarity. In our setting, we can use **COS-SIMILARITY**: The similarity of two histograms h_a and h_b is

$$s(h_a, h_b) = \cos(h_a, h_b) = \langle h_a, h_b \rangle,$$

where $\langle \cdot, \cdot \rangle$ is the inner product and $0 \leq s \leq 1$. The value $s = 0$ indicates orthogonality and the value $s = 1$ equality of the two histograms. Among the stored k_{cl} histograms given for the k_{cl} material samples of class cl , one must determine that histogram vector sgH_{cl} that is closest/most similar to H . (We use the notation sgH_{cl} to denote the histogram vector of a specific sample segment sg belonging to class cl .) Here,

$$sgH_{cl} = (sgh_{cl}^1, sgh_{cl}^2, \dots, sgh_{cl}^H)$$

We can now use the cos-measure to compute similarities for each component of vectors of histograms:

$$sgS_{cl} = (s(h_1, sgh_{cl}^1), \dots, s(h_H, sgh_{cl}^H)) \\ = (sgs_{cl}^1, \dots, sgs_{cl}^H)$$

For the vector-valued quantity sgS_{cl} , one can compute the norms:

$$i) \|sgS_{cl}\|_{\max} = \max_{sc=1..H} \{sgs_{cl}^{sc}\}; \quad ii) \|sgS_{cl}\|_2^2 = \sum_{sc=1}^H (sgs_{cl}^{sc})^2$$