

Stratovan■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...

SIMULATED ANNEALING. (The process of "annealing" is studied in thermodynamics and concerns the cooling process of materials driven by energy minimization. SIMULATED annealing, in our context, is a cost function optimization method adapted to classification system optimization.) For classification performance function optimization, a simulated annealing algorithm can be summarized at a high level as follows:

- define an initial value of the parameter vector W ;
- define an initial value of the temperature T ;
- compute $p(W) = \text{performance}(W)$;
- WHILE ($p(W)$ "not good enough" AND
no iterations $<$ max iterations)
 - determine a random perturbation ΔW ,
where $\Delta W = \Delta W(T, p(W), \dots)$;
 - set $W := W + \Delta W$;
 - compute $p(W)$;
 - IF ($p(W)$ has improved)
 - accept the new W value;
 - ELSE • accept the new W value
with a probability (< 1)
depending on T (and...);
 - IF ("time to reduce T ")
 - reduce T value;
- return values of W and $p(W)$;

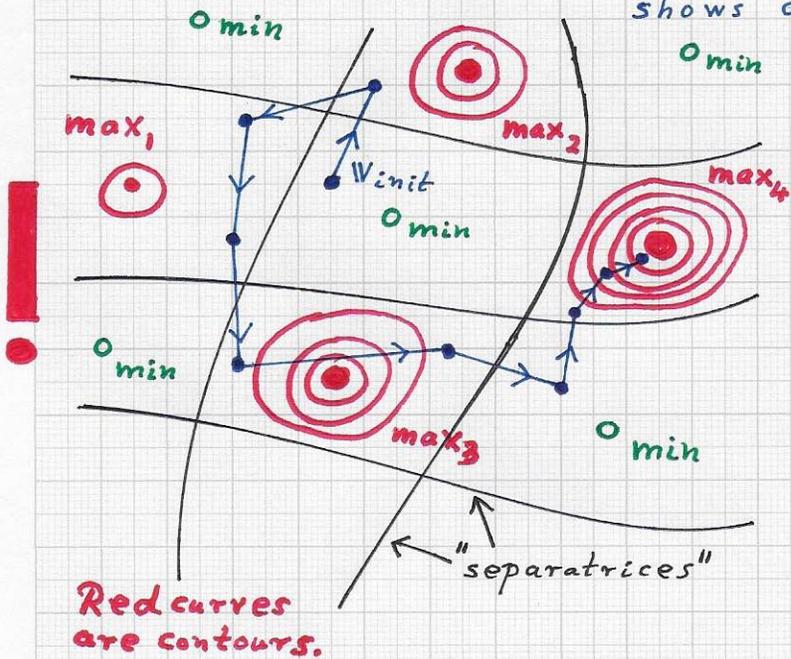
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We now explain this algorithm in more detail, with a focus on material classification. The essential (hyper-) parameter values of the classification system define the values of the parameter vector \mathbb{W} to be optimized. The annealing-specific temperature T , with monotonically decreasing value, is crucially important for "not getting stuck" in a local optimum. Temperature can be used in various way to allow the algorithm to explore \mathbb{W} 's domain space. Most importantly, smaller values of T imply lower probabilities for a new \mathbb{W} -value to be accepted when $p(\mathbb{W}_{\text{new}})$ is worse than $p(\mathbb{W}_{\text{old}})$. Further, one can also use the T -value to scale the magnitude/length of the perturbation vector $\Delta\mathbb{W}$: a large (small) value of T should imply a large (small) perturbation vector $\Delta\mathbb{W}$. The calculation of the system's performance $p(\mathbb{W})$ is the computationally most expensive part of the algorithm. The computation of $p(\mathbb{W})$ for a new parameter value setting makes it necessary to calculate new values for the relative occurrences of the classification result types, i.e., $\bar{n}_{0,0}, \bar{n}_{1,0}, \dots, \bar{n}_{0,c}, \dots, \bar{n}_{c,c}$, involving substantial data processing of material samples in the sample database with known ground truth information.

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shows a two-dimensional system parameter space V . Nine sub-regions are associated with five locations "min" where the performance value of $p(V)$ is a local minimum. Of interest are the four locations "max₁", "max₂", "max₃" and "max₄" where the

$p(V)$ function has local maxima. It is assumed that $p(\text{max}_4)$ is the globally maximal value of p , and that the location "max₄" must be found. (The so-called "separatrices" define the topological neighborhood relationship between the minimum- and maximum-regions. "Separatrices" are shown simply to provide structure.) The super-imposed blue polygon with directed edges visualizes a possible progression of V -tuples during the iterative simulated annealing process — starting with V_{init} and ending very close to "max₄". In this example, the algorithm performs as desired, i.e., it does not "get stuck" at local optima but it finds the global maximum — involving 10 $p(V)$ computations.

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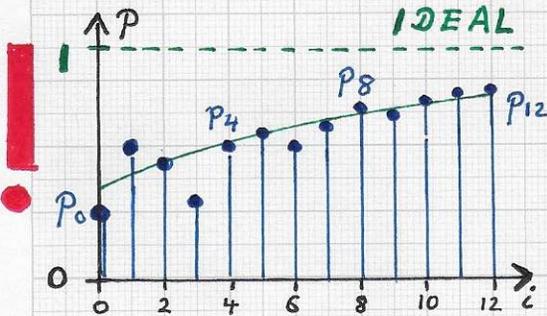
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The WHILE Loop of the simulated annealing algorithm will always terminate since only a finite number of iterations (max iterations) is permitted. The $p(W)$ "not good enough" part of the termination condition can be defined in a variety of ways, for example: $p(W)$ is not yet larger than the expected/required p_{min} -value, i.e., $p(W) \not> p_{min}$; or, considering the set of the most recently computed $p(W)$ -values, one cannot observe a "trend" of generally improving, i.e., generally increasing, $p(W)$ -values (keeping in mind that strict monotonically increasing $p(W)$ -value behavior is NOT required by simulated annealing — where it is in fact permitted to accept decreasing $p(W)$ -values. In the W parameter space, one "moves" from a current location to a new location via a random perturbation ΔW serving as an offset/propagation vector, i.e., $W \mapsto W + \Delta W$. Again, one can consider several possibilities to define and compute a ΔW -value: In the early stage of the simulated annealing process, at relatively higher temperature, one should permit relatively large magnitudes of ΔW -values; in the late stage, one should permit only relatively small magnitudes of ΔW -values.

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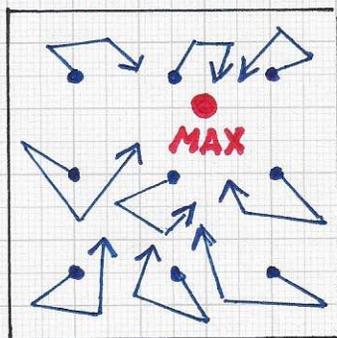
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One can consider the values of the current temperature T , the current performance $p(V)$, the current location of V (in the finite, bounded parameter space domain) and other values to compute ΔV . (The

figure (top-left) sketches a hypothetical, desirable progression of p_i -values, as a function of iteration index i . The general "trend" is asymptotic convergence towards the ideal p -value of one.) We compute

$p(V_{new}) = p(V + \Delta V)$ and must decide whether to accept the new V value (or not). Simulated annealing always accepts the new V value if $p(V + \Delta V) > p(V)$; if $p(V + \Delta V) \leq p(V)$, then the new V value will be accepted with a probability (< 1) that decreases - often in an exponentially decreasing fashion - during the progression of simulated annealing. Usually the temperature value is most important for the definition of this probability.



At certain stages, one must (monotonically) reduce the T value ("annealing schedule"). The output will be the values of V and $p(V)$, for the best, largest value of p obtained.

Using multiple initial locations 'o' to start simulated annealing.