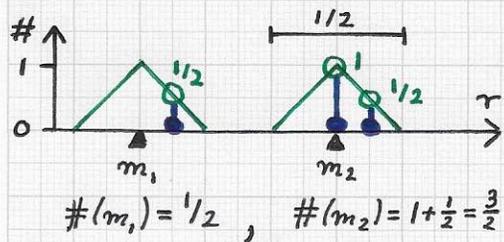
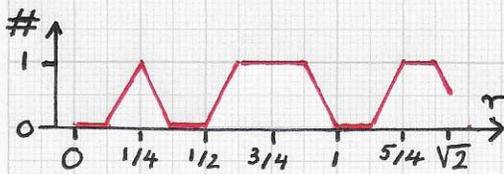
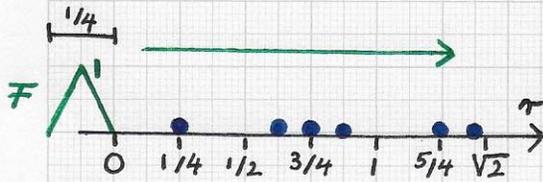


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OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...

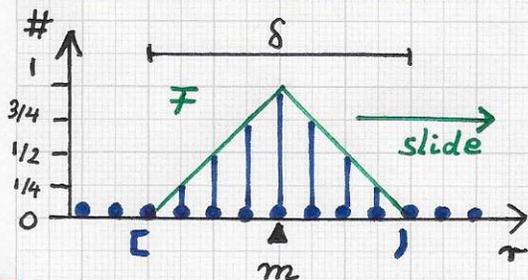


The sketches shown here (left) illustrate an example for $D=2$ where a "hat function" of domain/window width $1/4$ and peak value 1 is moved on the τ -axis from left to right. The "hat function" serves as the filter F that is used for convolution with the set $\{\bullet\}$. The third sketch explains the essential calculation of

the value of the function called '#': We determine all τ -values (\bullet) inside the window of the (sliding) "hat function" and the values of F , i.e., the "hat function", for these τ -values; and we sum up the resulting values of the "hat function" and assign the sum as value of # at the current location of the midpoint m_i . Sliding the filter F over the chosen set $\{\bullet\}$ of 6 τ -values produces the piecewise linear function shown in the second sketch. Our goal is the estimation of probability density function values with respect to the D -dimensional domain space in which the actual points reside. We are not interested in densities relative to the τ -axis.

OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

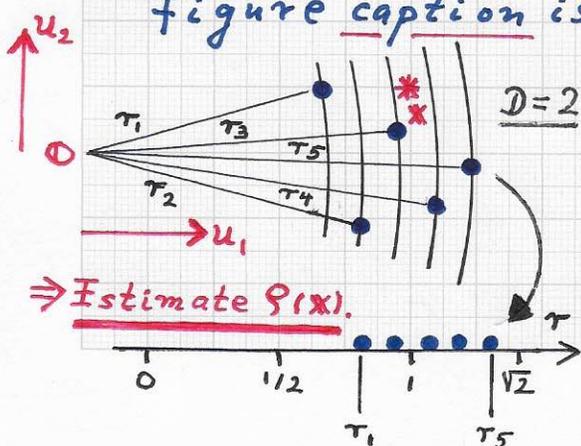
- Laplacian eigenfunctions and neural networks:...



$\#(m) = 0 + 1/4 + 1/2 + 3/4 + 1 + 3/4 + 1/2 + 1/4 + 0 = 3.$

While BOX function and HAT function filter masks F are simple and can be implemented efficiently, many functions can be considered to serve as a "counting" filter function F used in the convolution

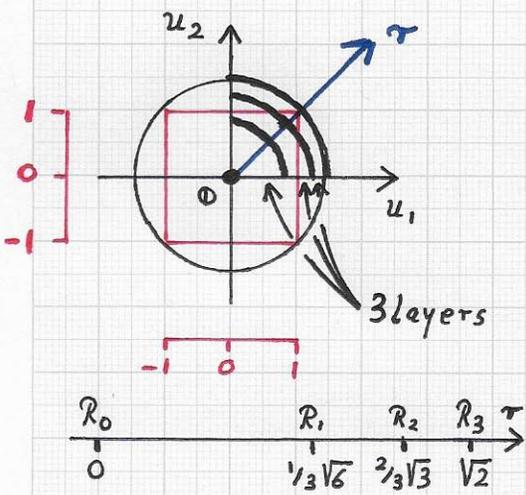
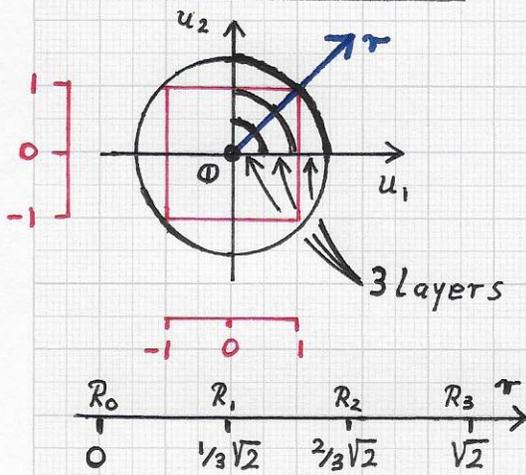
process. For example, normalized B-spline basis functions of any degree can be considered as they have many desirable properties one wants F to have, including non-negativity and partition of unity. The top-left figure illustrates how F serves as a "weight function": An τ -value (•) lying in that part of F's domain where F has a positive value is assigned this positive value as its weight. The computation of the value of $\#(m)$ in the figure caption is an example. To summarize the



most important aspects of this discussion, we must (1) choose a filter F; (2) define the "width" delta of F; and (3) normalize the resulting # - values to serve as proper values supporting the computation of probability density function values.

OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...



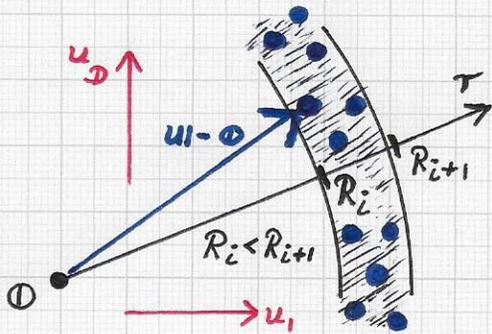
Two Layer models for φ function.

We re-consider the issue of using R_i -values, $i = 0 \dots N$, such that $|R_{i+1} - R_i| = \text{const}$ or all layer hyper-volumes in the u -space domain have the same hyper-volume. This issue is relevant for the calculation of proper probability density values - relative to u -space and NOT relative to the radial τ -line. We consider a simple example for $D=2$ and $N=3$. The top-left figure sketches the first case: The maximal 2-ball hyper-volume is $V = 2\pi$. The equidistantly spaced R_i -values are $R_i = \frac{i}{3}\sqrt{2}$. The hyper-volume of the i^{th} layer, V_i , is $V_i = (R_{i+1}^2 - R_i^2)\pi$, i.e., $V_0 = \frac{2}{9}\pi$, $V_1 = \frac{2}{3}\pi$ and $V_2 = \frac{10}{9}\pi$. ($\sum V_i = V$.)

The next figure sketches the second case: Each Layer must have the same hyper-volume $V_i = \frac{2}{3}\pi$. The R_i -values are given as $R_i = \sqrt{\frac{i}{3}}\sqrt{2}$, i.e., $R_0 = 0$, $R_1 = \frac{1}{3}\sqrt{6}$, $R_2 = \frac{2}{3}\sqrt{3}$ and $R_3 = \sqrt{2}$. (See p. 8 (5/27/2023).)

■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...



If one defines point (•) density only relatively to the one-dimensional r-line, then the probability density estimate for the interval $[R_i, R_{i+1})$ will be $\rho_i = n_i / (R_{i+1} - R_i)$, where

n_i is the number of u_1 -points with positional vector $(u_i - 0)$ that satisfy the layer condition $R_i^2 \leq \|u_i - 0\|^2 < R_{i+1}^2$, see top-left figure. Considering the actual hyper-volume of the u_1 -space layer sketched in the figure for $D=2$, the probability density estimate is ${}^2\rho_i = n_i / (\pi (R_{i+1}^2 - R_i^2))$. For the case $D=3$, one obtains the density estimate ${}^3\rho_i = n_i / (\frac{4}{3}\pi (R_{i+1}^3 - R_i^3))$. For the general D -dimensional case, one obtains two formulae, see p. 9 (4/25/2023):

$${}^D\rho_i = n_i / \left(\frac{1}{(D/2)!} \pi^{D/2} (R_{i+1}^D - R_i^D) \right), D=0,2,4,\dots,$$

$${}^D\rho_i = n_i / \left(\frac{2^{\lfloor D/2 \rfloor}}{D!!} \pi^{\lfloor D/2 \rfloor} (R_{i+1}^D - R_i^D) \right), D=1,3,5,\dots$$

Thus, a " D -dimensional density ${}^D\rho_i$ " is a certain multiple, scaled version of $\rho_i = {}^1\rho_i$. By computing ρ_i , one can obtain ${}^D\rho_i, D \in \{2,3,4,\dots\}$, via multiplication.

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■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks: ... More compactly, we can write a " \mathcal{D} -dimensional density ${}^{\mathcal{D}}\varphi_i$ " as

${}^{\mathcal{D}}\varphi_i = n_i / (c_{\mathcal{D}} (R_{i+1}^{\mathcal{D}} - R_i^{\mathcal{D}}))$, where $c_{\mathcal{D}}$ is the factor that depends on the dimension \mathcal{D} . We can express φ_i in terms of ${}^{\mathcal{D}}\varphi_i$ (and vice versa):

$$\frac{\varphi_i}{{}^{\mathcal{D}}\varphi_i} = \frac{n_i}{R_{i+1} - R_i} \cdot \frac{n_i}{c_{\mathcal{D}} (R_{i+1}^{\mathcal{D}} - R_i^{\mathcal{D}})} = c_{\mathcal{D}} \frac{R_{i+1}^{\mathcal{D}} - R_i^{\mathcal{D}}}{R_{i+1} - R_i}.$$

It is possible to symbolically compute the term $(R_{i+1}^{\mathcal{D}} - R_i^{\mathcal{D}}) / (R_{i+1} - R_i)$ exactly. We obtain:

$\mathcal{D} = 1$: $(R_{i+1} - R_i) / (R_{i+1} - R_i) = 1$

$\mathcal{D} = 2$: $(R_{i+1}^2 - R_i^2) / (R_{i+1} - R_i) = R_{i+1} + R_i$

$\mathcal{D} = 3$: $(R_{i+1}^3 - R_i^3) / (R_{i+1} - R_i) = R_{i+1}^2 + R_{i+1}R_i + R_i^2$

$\mathcal{D} = 4$: $(R_{i+1}^4 - R_i^4) / (R_{i+1} - R_i) = R_{i+1}^3 + R_{i+1}^2R_i + R_{i+1}R_i^2 + R_i^3$

$\Rightarrow (R_{i+1}^{\mathcal{D}} - R_i^{\mathcal{D}}) / (R_{i+1} - R_i) = R_{i+1}^{\mathcal{D}-1} + R_{i+1}^{\mathcal{D}-2}R_i + R_{i+1}^{\mathcal{D}-3}R_i^2 + \dots + R_{i+1}R_i^{\mathcal{D}-2} + R_i^{\mathcal{D}-1}$

$= \sum_{j=0}^{\mathcal{D}-1} R_{i+1}^{\mathcal{D}-1-j} R_i^j = \Sigma_{\mathcal{D}}$

It is now possible to express φ_i as

$\varphi_i = {}^{\mathcal{D}}\varphi_i c_{\mathcal{D}} \Sigma_{\mathcal{D}} \Leftrightarrow {}^{\mathcal{D}}\varphi_i = \varphi_i / (c_{\mathcal{D}} \Sigma_{\mathcal{D}})$

We consider a simple example for the case $\mathcal{D} = 2$ and $R_i = i/4\sqrt{2}$, $i = 0 \dots 4$ (equidistant spacing of R_i -values). Here, ${}^2\varphi_i = \varphi_i / (\pi(R_{i+1} + R_i))$, $i = 0 \dots 3$.

Further, $(R_{i+1} + R_i) = (i+1)/4\sqrt{2} + i/4\sqrt{2} = (2i+1)/4\sqrt{2}$.

...