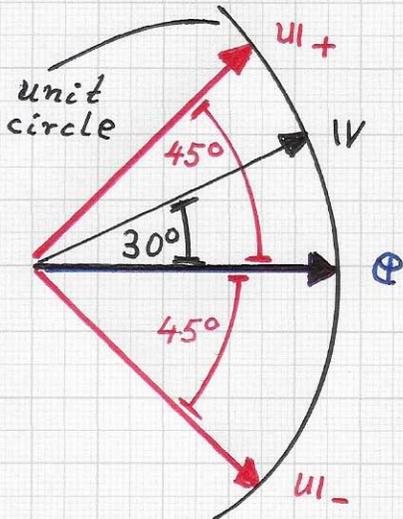


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OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks...

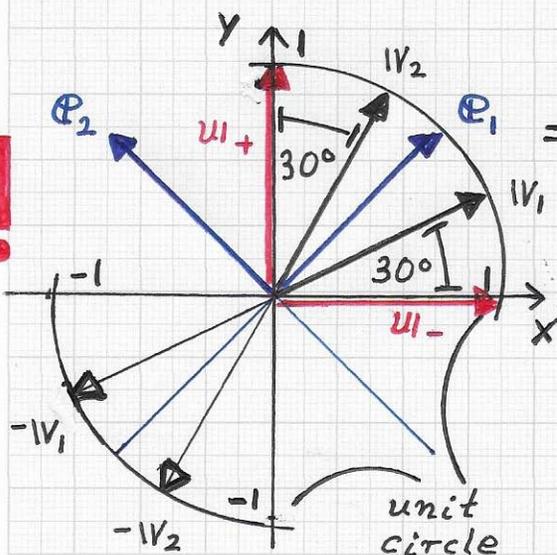


Simple 2D example.
The resulting vectors are

$$u_{1+} = (\sqrt{2}/2, \sqrt{2}/2)^T$$

and

$$u_{1-} = (\sqrt{2}/2, -\sqrt{2}/2)^T$$



We compute the two possible values of u_1 for the simple example sketched in the left figure. Using the formula provided on the previous page for the given vectors $e = (1, 0)^T$ and $v = (\sqrt{3}/2, 1/2)^T$, one obtains

$$\begin{aligned} u_1 &= \frac{\sqrt{2}}{2} \left(e \pm \frac{v - (v \cdot e) \cdot e}{\sqrt{1 - (v \cdot e)^2}} \right) \\ &= \frac{\sqrt{2}}{2} \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \pm \frac{(\sqrt{3}/2, 1/2)^T - \sqrt{3}/2 (1, 0)^T}{\sqrt{1 - (\sqrt{3}/2)^2}} \right) \\ &= \frac{\sqrt{2}}{2} \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \pm \frac{(0, 1/2)^T}{\sqrt{1/4}} \right) \\ &= \frac{\sqrt{2}}{2} \left(\begin{pmatrix} 1 \\ 0 \end{pmatrix} \pm 2 \begin{pmatrix} 0 \\ 1/2 \end{pmatrix} \right) \\ &= \frac{\sqrt{2}}{2} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix} = \begin{pmatrix} \sqrt{2}/2 \\ \pm \sqrt{2}/2 \end{pmatrix} \end{aligned}$$

A more complicated example is shown in the left figure. Two unit non-orthogonal vectors are given, v_1 and v_2 . Here, $v_1 = (\sqrt{3}/2, 1/2)^T$ and $v_2 = (1/2, \sqrt{3}/2)^T$. The desired pair of orthonormal vectors is given by $u_{1-} = (1, 0)^T$ and $u_{1+} = (0, 1)^T$.

Stratovan■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.• Laplacian eigenfunctions and neural networks...

In this 2D example, one must perform a principal components

analysis (PCA) step, to calculate the necessary eigen direction vector Φ needed for the computation of u_- and u_+ . (PCA actually yields

two orthogonal vectors; they are called Φ_1 and Φ_2 , after normalization, in the bottom-left figure on the previous page.) PCA is applied to four

vectors: $w_1 = (\sqrt{3}/2, 1/2)^T$, $w_2 = (1/2, \sqrt{3}/2)^T$, $-w_1$ and $-w_2$. For these four vectors PCA yields the

eigenvalues $\lambda_1 = 2 + \sqrt{3}$ and $\lambda_2 = 2 - \sqrt{3}$ with associated orthogonal eigenvectors $(1, 1)^T$

and $(-1, 1)^T$. After normalization, they de-

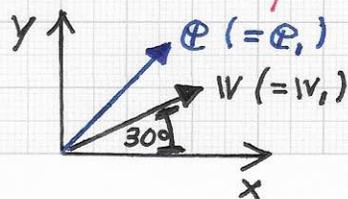
fine the orthonormal vectors $\Phi_1 = (\sqrt{2}/2, \sqrt{2}/2)^T$

and $\Phi_2 = (-\sqrt{2}/2, \sqrt{2}/2)^T$. (PCA is performed for

the matrix
$$\begin{pmatrix} \sqrt{3}/2 & 1/2 & -\sqrt{3}/2 & -1/2 \\ 1/2 & \sqrt{3}/2 & -1/2 & -\sqrt{3}/2 \end{pmatrix} \begin{pmatrix} \sqrt{3}/2 & 1/2 \\ 1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \\ -1/2 & -\sqrt{3}/2 \end{pmatrix} = \begin{pmatrix} 2 & \sqrt{3} \\ \sqrt{3} & 2 \end{pmatrix}.$$
)

We can now perform the described "optimal orthonormalization" for the vectors w_1 and w_2

by using Φ_1 as eigen direction Φ needed for the computation of u_- and u_+ . Further, we use



vector w_1 as w -vector needed for the equation for u_1 on page 10 (9/3/2023).

The left figure shows these choices.

StratovanOBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:...

In summary, we use the vectors $\underline{\Phi} = (\sqrt{2}/2, \sqrt{2}/2)^T$ and $\underline{W} = (\sqrt{3}/2, 1/2)^T$ for the computation of the pair of orthonormal vectors u_{1+} and u_{1-} . One obtains:

$$\begin{aligned} \underline{u}_1 &= \frac{\sqrt{2}}{2} \left(\underline{\Phi} \pm \frac{\underline{W} - (\underline{W} \cdot \underline{\Phi}) \cdot \underline{\Phi}}{\sqrt{1 - (\underline{W} \cdot \underline{\Phi})^2}} \right) \\ &= \frac{\sqrt{2}}{2} \left(\begin{pmatrix} \sqrt{2}/2 \\ \sqrt{2}/2 \end{pmatrix} \pm \frac{(\sqrt{3}/2, 1/2)^T - (\sqrt{3}/2, 1/2)^T \cdot (\sqrt{2}/2, \sqrt{2}/2)^T \underline{\Phi}}{\sqrt{1 - ((\sqrt{3}/2, 1/2)^T \cdot (\sqrt{2}/2, \sqrt{2}/2)^T)^2}} \right) \\ &= \text{"complicated square roots"} \dots \\ &= \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix} \pm \frac{\sqrt{2}}{2} \cdot \frac{(\sqrt{3}/2, 1/2)^T - 0.965926 (\sqrt{2}/2, \sqrt{2}/2)^T}{\sqrt{1 - (0.965926)^2}} \\ &= \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix} \pm \frac{\sqrt{2}}{2} \left(3.863703 \left(\begin{pmatrix} \sqrt{3}/2 \\ 1/2 \end{pmatrix} - 0.965926 \begin{pmatrix} \sqrt{2}/2 \\ \sqrt{2}/2 \end{pmatrix} \right) \right) \\ &= \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix} \pm \frac{\sqrt{2}}{2} \left(3.863703 \begin{pmatrix} 0.183013 \\ -0.183013 \end{pmatrix} \right) \\ &= \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix} \pm \frac{\sqrt{2}}{2} \begin{pmatrix} \sqrt{2}/2 \\ -\sqrt{2}/2 \end{pmatrix} = \begin{pmatrix} 1/2 \\ 1/2 \end{pmatrix} \pm \begin{pmatrix} 1/2 \\ -1/2 \end{pmatrix} = \underline{\underline{\begin{pmatrix} 1/2 \pm 1/2 \\ 1/2 \mp 1/2 \end{pmatrix}}} \end{aligned}$$

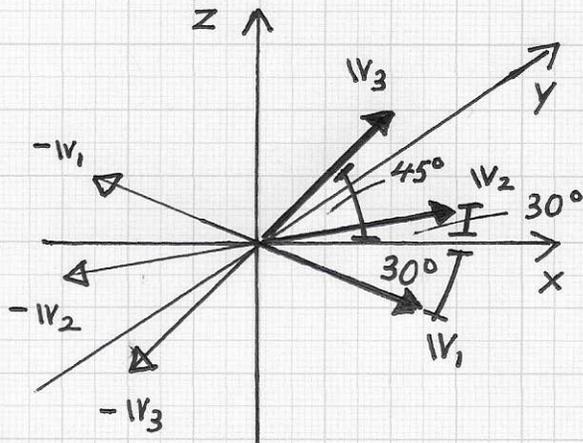
Thus, the two resulting u_1 -vectors are the vectors $(1, 0)^T$ and $(0, 1)^T$, as expected.

One can define $u_{1-} = (1, 0)^T$ and $u_{1+} = (0, 1)^T$ (or vice versa). The construction of such an "optimal orthogonal basis vector set" must ultimately be performed for the D -dimensional setting.

■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks... We consider a 3D example next.

Here, we are using as input for the approach three normalized non-orthogonal basis vectors. The goal is the construction of three orthonormal basis vectors that approximate the given three vectors "optimally" - in the same way as described for the 2D case. We use a 3D example



that uses vectors and angles similar to those used in the 2D examples. The left figure provides a sketch: The three given normalized non-orthogonal vectors are $v_1 = (\sqrt{3}/2, -1/2, 0)^T$, $v_2 = (\sqrt{3}/2, 1/2, 0)^T$ and $v_3 = (\sqrt{2}/2, 0, \sqrt{3}/2)^T$.

• PCA is applied to six vectors: $v_1, v_2, v_3, -v_1, -v_2$ and $-v_3$.

The covariance matrix for which one must compute eigenvalues and eigenvectors is the matrix

$$\underbrace{\begin{bmatrix} \sqrt{3}/2 & \sqrt{3}/2 & \sqrt{2}/2 & -\sqrt{3}/2 & -\sqrt{3}/2 & -\sqrt{2}/2 \\ -1/2 & 1/2 & 0 & 1/2 & -1/2 & 0 \\ 0 & 0 & \sqrt{2}/2 & 0 & 0 & -\sqrt{2}/2 \end{bmatrix}}_M \cdot M^T = \underbrace{\begin{bmatrix} 4 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}}_C = C.$$

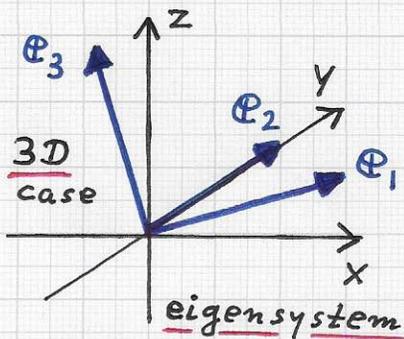
The three eigenvalues and eigenvectors of C are $\lambda_1 = (5 + \sqrt{13})/2$, $\lambda_2 = 1$ and $\lambda_3 = (5 - \sqrt{13})/2$, and $e_1 = ((3 + \sqrt{13})/2, 0, 1)^T$, $e_2 = (0, 1, 0)^T$ and $e_3 = ((3 - \sqrt{13})/2, 0, 1)^T$, respectively.

...

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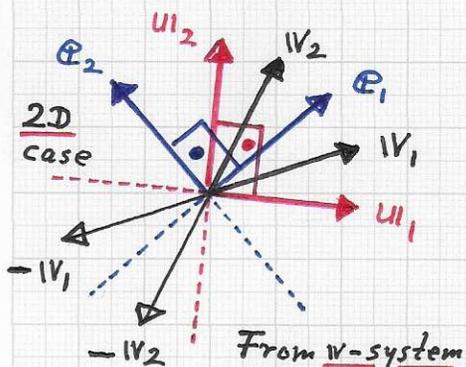
■ OBJECT AND MATERIAL EIGENFUNCTIONS - Cont'd.

• Laplacian eigenfunctions and neural networks:... After normalization, the values of these three eigenvectors are approximately $\mathcal{E}_1 = (0.957092, 0, 0.289784)^T$, $\mathcal{E}_2 = (0, 1, 0)^T$ and $\mathcal{E}_3 = (-0.289784, 0, 0.957092)^T$. (Of course, the vectors $\mathcal{E}_1, \mathcal{E}_2$ and \mathcal{E}_3 are mutually orthogonal.) The objective is the construction of an orthonormal basis vector set from the PCA-generated orthonormal eigenvectors $\mathcal{E}_1, \mathcal{E}_2$ and \mathcal{E}_3 , see left figure.



of an orthonormal basis vector set from the PCA-generated orthonormal eigenvectors $\mathcal{E}_1, \mathcal{E}_2$ and \mathcal{E}_3 , see left figure.

{ • Note. In the 2D case, one can understand the needed u1-vectors as vectors that are "dual" to the E-eigenvectors defined by two normalized, non-orthogonal vectors \mathcal{V}_1 and \mathcal{V}_2 , see left figure. Here, PCA is applied



to the four vectors $\mathcal{V}_1, \mathcal{V}_2, -\mathcal{V}_1$ and $-\mathcal{V}_2$. The two resulting eigenvectors (after normalization) are \mathcal{E}_1 and \mathcal{E}_2 . The "optimal u1-system" is defined by the normalized, orthogonal vectors u_1 and u_2 . The vectors u_1 and u_2 are "dual" to \mathcal{E}_1 and \mathcal{E}_2 , since one can obtain u_1 and u_2 by rotating \mathcal{E}_1 and \mathcal{E}_2 by $\pm 45^\circ (\pm \pi/4)$, or by calculating $\mathcal{E}_1 + \mathcal{E}_2$ and $\mathcal{E}_1 - \mathcal{E}_2$ to define u_1 - and u_2 -directions. }...

From V-system to the four vectors $\mathcal{V}_1, \mathcal{V}_2, -\mathcal{V}_1$ and $-\mathcal{V}_2$. to E-system to u1-system.

The two resulting eigenvectors (after normalization) are \mathcal{E}_1 and \mathcal{E}_2 . The "optimal u1-system" is defined by the normalized, orthogonal vectors u_1 and u_2 . The vectors u_1 and u_2 are "dual" to \mathcal{E}_1 and \mathcal{E}_2 , since one can obtain u_1 and u_2 by rotating \mathcal{E}_1 and \mathcal{E}_2 by $\pm 45^\circ (\pm \pi/4)$, or by calculating $\mathcal{E}_1 + \mathcal{E}_2$ and $\mathcal{E}_1 - \mathcal{E}_2$ to define u_1 - and u_2 -directions. }...