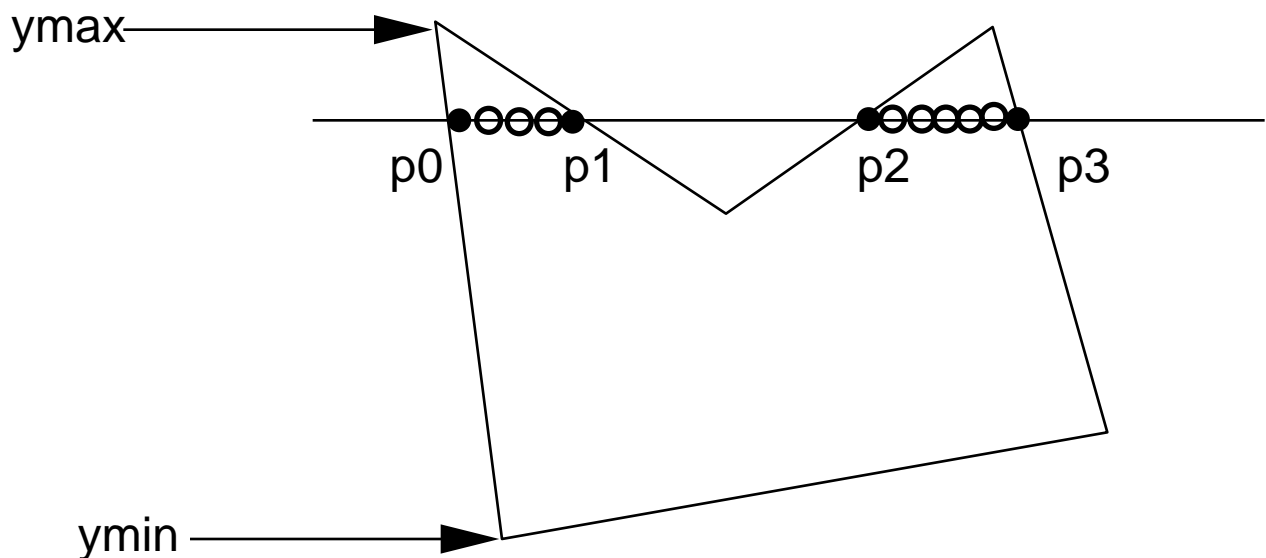


Scanline Fill Algorithm

- Intersect scanline with polygon edges
- Fill between pairs of intersections
- Basic algorithm:

For $y = y_{\min}$ to y_{\max}

- 1) intersect scanline y with each edge
- 2) sort intersections by increasing x
[p_0, p_1, p_2, p_3]
- 3) fill pairwise ($p_0 \rightarrow p_1, p_2 \rightarrow p_3, \dots$)



However, we need to handle some special cases and improve the performance

Special handling:

a) Make sure we only fill the interior pixels

Define interior:

For a given pair of intersectin points
(X_i, Y), (X_j, Y)

→ Fill ceiling(X_i) to floor(X_j)

important when we have polygons adjacent to each other

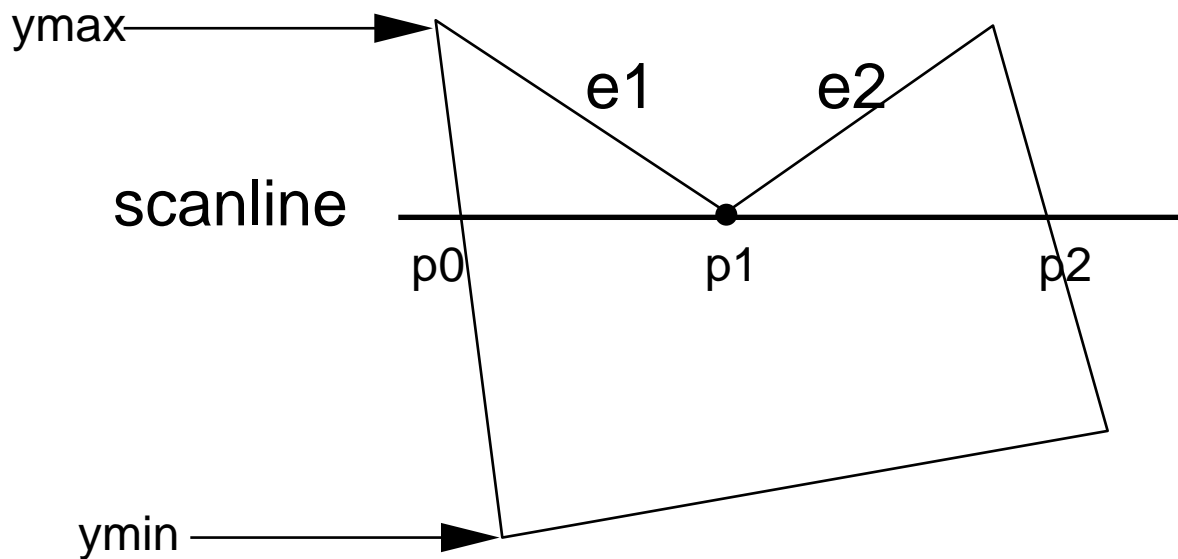
b) Intersection has an integer X coordinate

→ if X_i is integer, we define it to be interior

→ if X_j is integer, we define it to be exterior
(so don't fill)

Special handling (cont'd)

c) Intersection is an edge end point



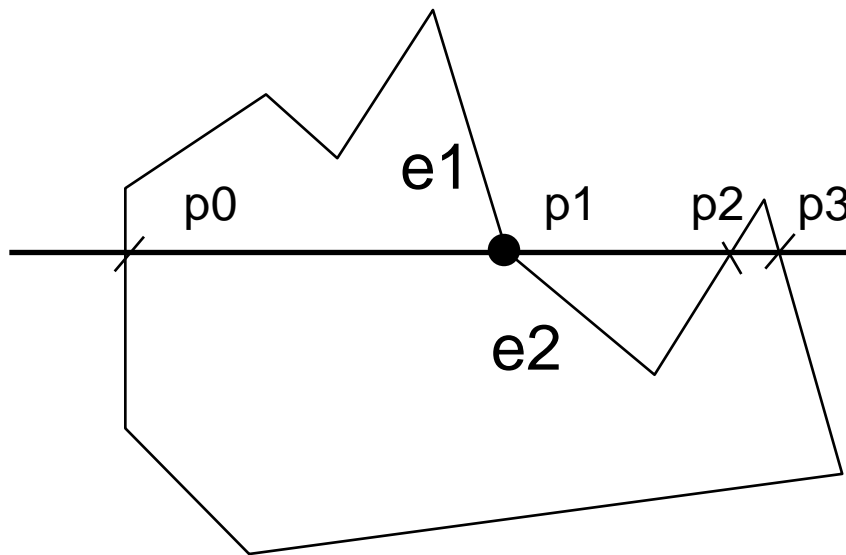
Intersection points: (p_0, p_1, p_2) ???

→ (p_0, p_1, p_1, p_2) so we can still fill pairwise

→ In fact, if we compute the intersection of the scanline with edge e_1 and e_2 separately, we will get the intersection point p_1 twice. Keep both of the p_1 .

Special handling (cont'd)

c) Intersection is an edge end point (cont'd)



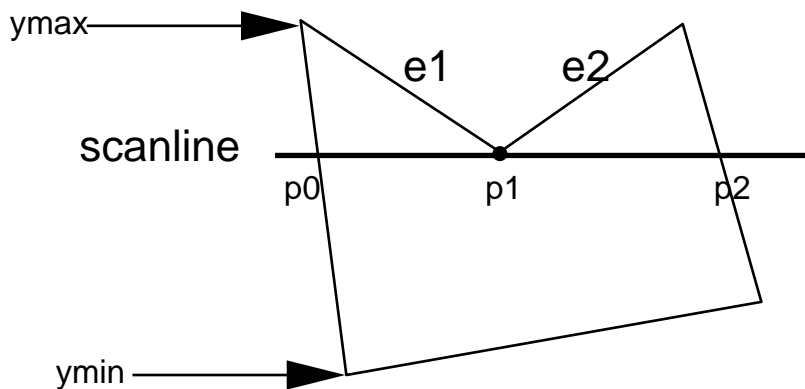
However, in this case we don't want to count p1 twice (p0,p1,p1,p2,p3), otherwise we will fill pixels between p1 and p2, which is wrong

Special handling (cont'd)

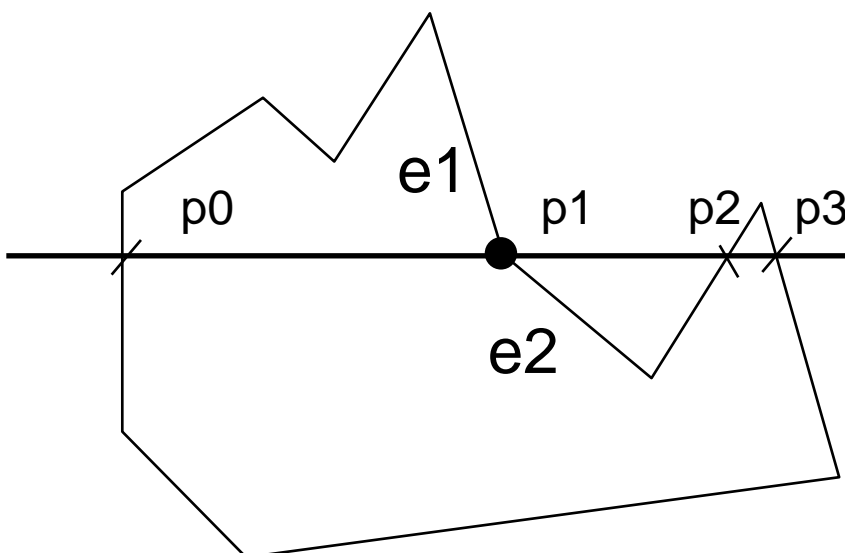
c) Intersection is an edge end point (cont'd)

Rule:

If the intersection is the y_{min} of the edge's endpoint, count it. Otherwise, don't.



Yes, count
p1 for both
e1 and e2



No, don't count
p1 for the edge e2