

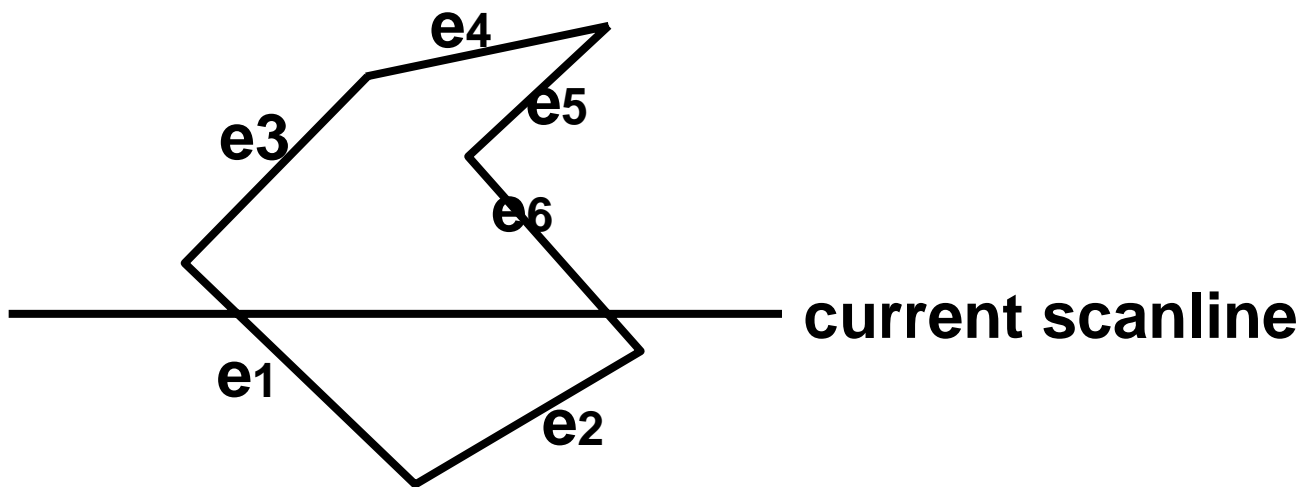
# Scanline Fill

## Performance Improvements

*brute force: intersect all the edges with each scanline*

### 1) Improvement 1:

find the  $y_{min}$  and  $y_{max}$  of each edge and intersect the edge only when it crosses the scanline



### 2) Improvement 2:

- only calculate the intersection of the edge with the 1st scanline it intersects
- calculate  $dx/dy$
- for subsequent scanlines, derive new intersections as  $x = x + dx/dy$

### 3) Improvement 3:

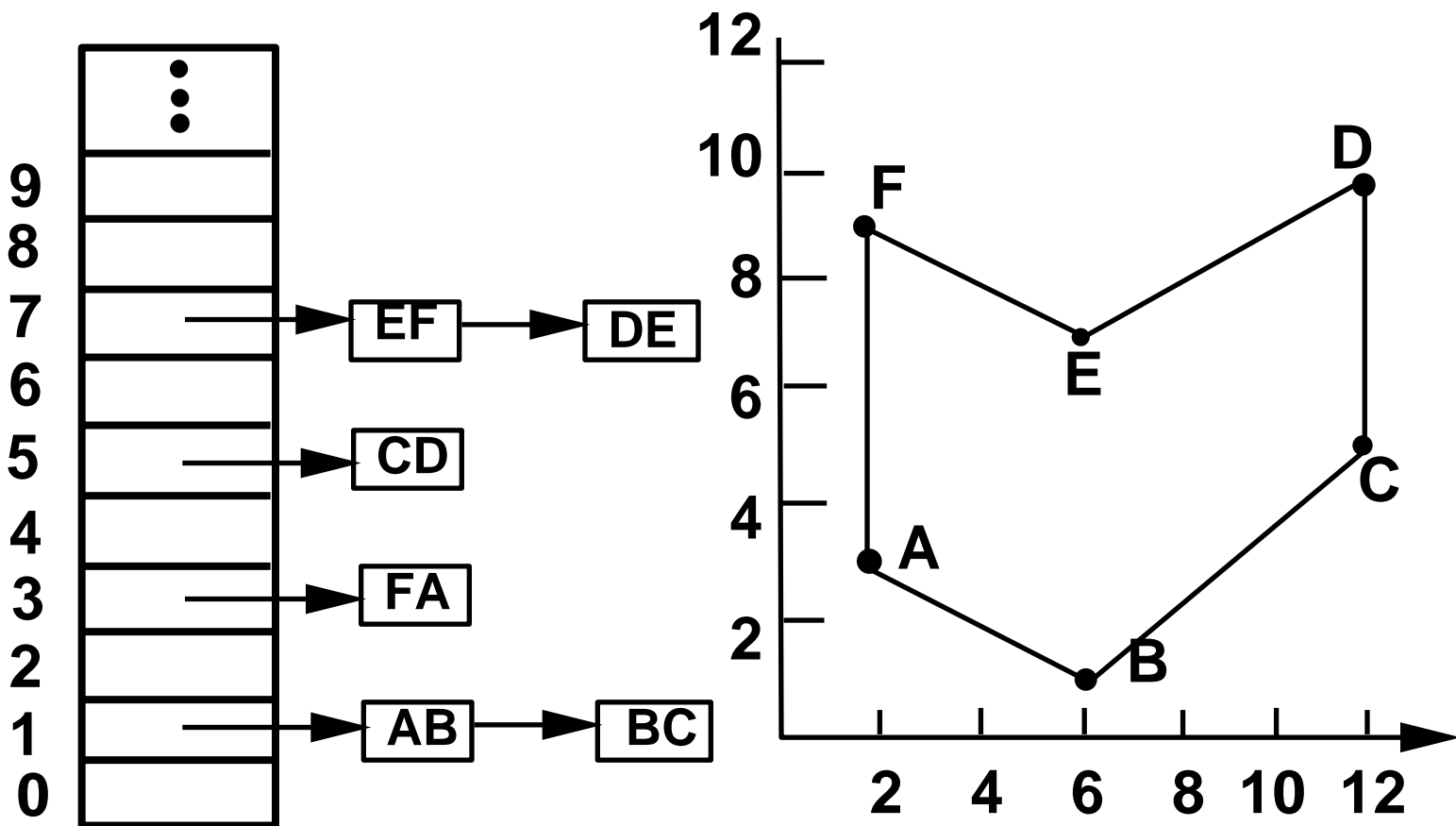
change  $x = x + dx/dy$  to integer arithmetic

# Scanline Fill

## Data Structures

### 1. Edge Table

- keep a separate bucket for each scanline
- all edges sorted by their ymin and inserted into the table
- within each bucket, edges are sorted by increasing x of the ymin endpoint



Edge structure: ymax, xmin, dx/dy, next

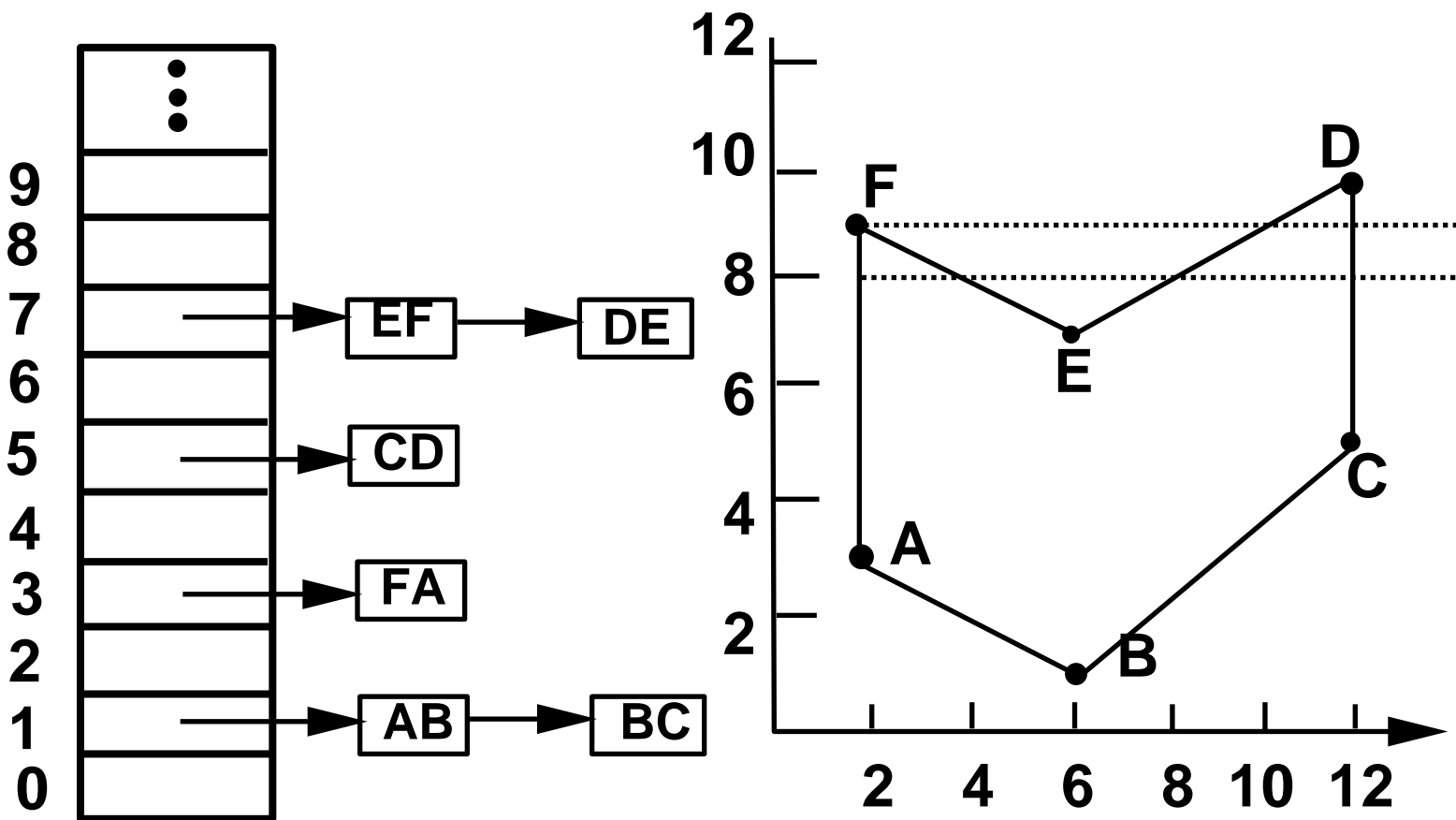
AB: 3, 6, -2, BC

# Scanline Fill

## Data Structures (cont'd)

### 1. Active Edge Table

A list of edges that are active for current scanline, sorted by increasing x intersection



Scanline 8

FA → EF → DE → CD

Scanline 9

DE → CD

# Scanline Fill

## Algorithm

**Construct the Edge Table (ET)**

**y = smallest y in the ET**

**Active Edge Table (AET) = NULL**

**for y = ymin to ymax**

**Merge-sort ET[y] into AET by x value**

**Fill between pairs of x in AET**

**for each edge in AET**

**if edge.ymax = y**  
**remove edge from AET**

**else**  
**edge.x = edge.x + dx/dy**

**Sort AET by x value (as needed)**

**end scan\_fill**