

## The Cook-Levin Theorem

Recall that a language  $L$  is *NP-complete* if  $L \in \text{NP}$  and if  $L$  is at least as hard as *every* language in NP: for all  $A \in \text{NP}$ , we have that  $A \leq_P L$ . Our *first* NP-complete language is the hardest to get, since we have no NP-hard language to reduce to it. A first NP-complete language is provided by the Cook-Levin theorem, due to Stephen Cook (1971, USA/Canada) and, independently, Leonid Levin (1973, but the subject of lectures, in Russia, for some years before). The particular NP-complete problem we select is not of great importance; we will use SAT. What is more important is that we show *some* particular language NP-complete so, using it, we can start populating our universe with *other* known-to-be-NP-complete problems.

**Theorem [Cook-Levin].** SAT is NP-complete.

To prove the theorem we must show that  $\text{SAT} \in \text{NP}$ , which we know, and that, for any  $A \in \text{NP}$ , we can poly-time reduce  $A$  to SAT. So fix  $A \in \text{NP}$ , some NP-complete language. Fix  $M = (Q, \Sigma, \Gamma, \delta, q_0, q_A, q_R)$ , a verifier that accepts  $A$ . Fix  $p(n)$ , a polynomial that upperbounds the running time of  $M$ : the number of steps  $\text{TIME}_M(w \sqcup c)$  that  $M(w \sqcup c)$  takes is always less than  $p(n)$ , where  $n = |w|$  and  $c \in \Gamma^*$  is arbitrary. We know that

- $w \in A \Rightarrow (\exists c) M(w \sqcup c)$  accepts
- $w \notin A \Rightarrow (\forall c) M(w \sqcup c)$  rejects

We haven't been very explicit about where the certificate  $c$  is drawn from. We may consider it to be an element of  $\Gamma^*$ . In fact, given our bound on the running time of  $A$ , we may assume that  $c \in \Gamma^{p(n)-1-n}$ . Strings longer than this will not even have their rightmost characters read.

Nor our job is to, by polynomial-time transformation, map  $w \in \Sigma^*$  to a Boolean formula  $\phi$  such that  $w \in A$  iff  $\phi$  is satisfiable. Our transformation will depend on machine  $M$  and polynomial  $p$ . To describe  $\phi$ , fix  $w \in \Sigma^*$ . Let  $n = |w|$ .

First, we specify the *variables* that  $\phi$  will use. These are

1.  $Q_{q,t}$  for each  $q \in Q$  and  $1 \leq t \leq p(n)$ .  
*Variable  $Q_{q,t}$  is supposed to mean that machine  $M$  is in state  $q$  at time  $t$ .*
2.  $H_{i,t}$  for each  $1 \leq i \leq p(n)$ ,  $1 \leq t \leq p(n)$ .  
*Variable  $H_{i,t}$  is supposed to mean that the head of the machine  $M$  is at position  $i$  at time  $t$ .*
3.  $X_{a,i,t}$  for each  $a \in \Gamma$ ,  $1 \leq i \leq p(n)$ ,  $1 \leq t \leq p(n)$ .  
*Variable  $X_{a,i,t}$  is supposed to mean that there is an  $a$ -character at position  $i$  of the tape at time  $t$ .*

Now “all” we have to do is to write a collection of Boolean constraints that collectively capture the idea that our machine  $M$ , on input  $w \sqcup c$  (for the given  $w$  and an arbitrary  $c$ ), computes correctly and winds up in an accepting state. If you AND together all the constraints you get a Boolean formula that will be satisfiable iff  $w \in L$ . Lets show how some of these constraints look.

1. The machine starts off in its start state:

$$Q_{q_0,1} \Leftrightarrow 1$$

2. The head starts off at the left edge:

$$H_{1,1} \Leftrightarrow 1$$

3. The tape starts off with a  $w \sqcup c$  written on it:

$$\begin{aligned} X_{w[i],i,1} &\Leftrightarrow 1 \text{ for all } 1 \leq i \leq n \\ X_{\sqcup,n+1,1} &\Leftrightarrow 1 \\ \bigvee_{a \in \Gamma} X_{a,i,1} &\Leftrightarrow 1 \text{ for each } n+2 \leq i \leq p(n) \end{aligned}$$

4. You end up in an accept state.

$$\bigvee_{1 \leq t \leq p(n)} Q_{q_A,t}$$

5. Each step of the machine is computed according to the transition.

In particular, if  $\delta(q, a) = (q', b, R)$  then

$$(Q_{q,t} \wedge H_{i,t} \wedge X_{a,i,t}) \Rightarrow (Q_{q',t+1} \wedge H_{i+1,t+1} \wedge X_{b,i,t+1}) \quad \text{for all } 1 \leq i < p(n), 1 \leq t < p(n)$$

Similarly define the following constraints for when  $\delta(q, a) = (q', b, L)$ . Here it is convenient to assume that  $M$  never tries to move its head to the left of the left edge of the tape, which is without loss of generality.

$$(Q_{q,t} \wedge H_{i,t} \wedge X_{a,i,t}) \Rightarrow (Q_{q',t+1} \wedge H_{i-1,t+1} \wedge X_{b,i,t+1}) \quad \text{for all } 1 \leq i < p(n), 1 \leq t < p(n)$$

Finally, if the head is *not* the immediate vicinity, the tape contents should simply be copied:

$$(H_{i,t} \wedge X_{a,j,t}) \Rightarrow X_{a,i,t+1} \quad \text{for all } 1 \leq i, j < p(n), i \neq j, 1 \leq t < p(n)$$

6. If you're in one state, you're not in another; if your head is somewhere, it's not somewhere else; if something is written on a tape cell, nothing else isn't written there.

$$\begin{aligned} Q_{q,t} &\rightarrow \overline{Q_{q',t}} && \text{for all } q, q' \in Q, q \neq q', 1 \leq t \leq p(n) \\ H_{i,t} &\rightarrow \overline{H_{j,t}} && \text{for all } 1 \leq i, j \leq p(n), i \neq j, 1 \leq t \leq p(n) \\ X_{a,i,t} &\rightarrow \overline{X_{b,i,t}} && \text{for all } a, b \in \Gamma, a \neq b, 1 \leq i \leq p(n), 1 \leq t \leq p(n) \end{aligned}$$

Now we should verify the following: (1) The transformation is polynomial time. This is clear. Of course the polynomial depends on  $p(n)$ , which depends on  $L$ . That is as one would expect. (2) if  $w \in L(M)$  then  $\phi$  is satisfiable. This is easy; the computation of  $M$  on a certificate that demonstrates  $w \in L$  provides a satisfying assignment of  $\phi$ . (3) if  $\phi$  is satisfiable, then  $w \in L(M)$ . This is the most tricky part. We read the certificate  $c$  that demonstrates  $w \in L$  off of the satisfying assignment of  $\phi$ . We have to have added enough constraints in our formula that a satisfying assignment really does correspond to possessing a certificate  $c$  and then performing a correct, accepting computation of  $M$  on input  $w \sqcup c$ .